

MAX14830 Evaluation Kit

Evaluates: MAX14830

General Description

The MAX14830 evaluation kit (EV kit) provides a proven design to evaluate the MAX14830 quad-channel universal asynchronous receiver-transmitter (UART) IC. Each UART contains 128 words of receive and transmit first-in/first-out (FIFO) buffer that can be controlled through the SPI or I²C interface. Each of the four UARTs are selected through SPI or I²C in-band addressing.

Each of the four UARTs can interface with an IO-Link[®] master transceiver or an RS-485/RS-232 multiprotocol transceiver. The EV kit contains on-board IO-Link master transceivers, RS-485/RS-232 multiprotocol transceivers, and double-pole/double-throw (DPDT) switches are used to select between the IO link and RS-485/RS-232 transceivers.

The EV kit operates from a +3.3V and a +24V DC supply and requires 100mA of current from each supply. This EV kit requires a user-supplied SPI/I²C controller and software.

The EV kit comes with a MAX14830ETM+ installed.

Features

- ◆ +3.3V and +24V Power-Supply Operation
- ◆ On-Board IO-Link Master Transceivers (MAX14824)
- ◆ On-Board RS-485/RS-232 Multiprotocol Transceivers (MAX3160E)
- ◆ PCB Header for User-Supplied SPI- and I²C-Compatible Signals
- ◆ PCB Headers for UART Signals (J1)
- ◆ Evaluates the MAX14830 in a 48-Pin TQFN (7mm x 7mm) Package
- ◆ RoHS Compliant
- ◆ Proven PCB Layout
- ◆ Fully Assembled and Tested

[Ordering Information](#) appears at end of data sheet.

Component List

| DESIGNATION | QTY | DESCRIPTION |
|-----------------------------------|-----|--|
| AARDVARK | 1 | 10-pin (2 x 5) header |
| C1 | 1 | 10µF ±20%, 50V X7R ceramic capacitor (2220) TDK C5750X7R1H106M |
| C2 | 1 | 10µF ±10%, 6.3V X7R ceramic capacitor (0805) Murata GRM21BR70J106K |
| C3–C6, C8–C11, C20, C22, C24, C26 | 12 | 1µF ±10%, 10V X7R ceramic capacitors (0603) Murata GRM188R71A105K |
| C12–C15 | 4 | 1µF ±10%, 50V X7R ceramic capacitors (0805) Murata GRM21BR71H105K |
| C16–C19, C21, C23, C25, C27–C42 | 23 | 0.1µF ±10%, 50V X7R ceramic capacitors (0603) Murata GRM188R71H104K |
| C43, C45, C47, C49 | 4 | 270pF ±5%, 50V C0G ceramic capacitors (0603) TDK C1608C0G1H271J |
| C44, C46, C48, C50 | 4 | 1nF ±5%, 50V X7R ceramic capacitors (0603) KEMET C0603C102J5RACTU |

| DESIGNATION | QTY | DESCRIPTION |
|--|-----|--|
| D1–D12 | 12 | Green LEDs (0603) |
| D13, D14, D17, D18, D21, D22, D25, D26 | 8 | 40V, 2A Schottky diodes Diodes, Inc. DFLS240 |
| D15, D19, D23, D27, D29 | 5 | 33V, 4A TVS diodes (SOT23) Semtech SDC36C.TCT |
| GPIO | 1 | 5-pin header |
| IOLINK0–IOLINK3 | 4 | 4-pin headers |
| J1 | 1 | 2 x 24 right-angle socket strip |
| JU1–JU10 | 10 | 2-pin headers |
| JU11–JU17 | 7 | 3-pin headers |
| JU18, JU19 | 2 | 4-way, 5-pin headers |
| JU20 | 0 | Not installed, 2-pin header |
| R1–R4 | 4 | 1kΩ ±5% resistors (0603) |
| R5–R10 | 6 | 2kΩ ±5% resistors (0603) |
| R11–R26 | 16 | 10kΩ ±5% resistors (0603) |
| R27 | 1 | 0.5Ω ±5% resistor (2010) IRC LRC-LR2010LF-01-R500-J |
| RS0–RS3 | 4 | 6-pin headers |
| SPI/I ² C | 1 | 12-pin header |

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For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

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Component List (continued)

| DESIGNATION | QTY | DESCRIPTION |
|-------------|-----|---|
| SW1 | 1 | Momentary pushbutton switch |
| U1 | 1 | Quad SPI/I ² C UART with 128-word FIFOs (48 TQFN-EP) Maxim MAX14830ETM+ |
| U2, U3 | 2 | Quad DPDT switches (36 TQFN-EP) Maxim MAX4761ETX+ |
| U4-U7 | 4 | IO-Link master transceivers (24 TQFN-EP) Maxim MAX14824GTG+ |

| DESIGNATION | QTY | DESCRIPTION |
|-------------|-----|--|
| U8-U11 | 4 | Multiprotocol transceivers (20 SSOP) Maxim MAX3160EEAP+ |
| U12 | 1 | SPDT analog switch (6 SOT23) Maxim MAX4624EUT+ (Top Mark: AADL) |
| Y1 | 1 | 3.6864MHz crystal |
| — | 19 | Shunts |
| — | 1 | PCB: MAX14830 EVALUATION KIT |

Component Suppliers

| SUPPLIER | PHONE | WEBSITE |
|--|--------------|-----------------------------|
| Diodes Incorporated | 805-446-4800 | www.diodes.com |
| IRC, Inc. | 361-992-7900 | www.irctt.com |
| KEMET Corp. | 864-963-6300 | www.kemet.com |
| Murata Electronics North America, Inc. | 770-436-1300 | www.murata-northamerica.com |
| Semtech Corporation | 805-495-2111 | www.semtech.com |
| TDK Corp. | 847-803-6100 | www.component.tdk.com |

Note: Indicate that you are using the MAX14830 when contacting these component suppliers.

Quick Start

Required Equipment

- MAX14830 EV kit
- User-supplied SPI interface controller
- +3.3V, 100mA DC power supply
- +24V, 100mA DC power supply

Procedure

The EV kit is fully assembled and tested. Follow the steps below to verify board operation. **Caution: Do not turn on the power supply until all connections are completed.**

- 1) Verify that shunts are installed in their default positions, as shown in Table 1.
- 2) Connect the output of the SPI interface controller to the SPI/I²C 12-pin header, as follows:
 - Connect CSN to pin 5 of SPI/I²C
 - Connect MISO to pin 6 of SPI/I²C
 - Connect SCLK to pin 7 of SPI/I²C
 - Connect MOSI to pin 10 of SPI/I²C
- 3) Turn on the +3.3V power supply and set the supply to +3.3V, then disable the power supply.
- 4) Connect the positive terminal of the +3.3V power supply to the +3.3V PCB pad on the EV kit. Connect the negative terminal of the power supply to the GND PCB pad.
- 5) Turn on the +24V power supply and set the supply to +24V, then disable the power supply.
- 6) Connect the positive terminal of the +24V power supply to the +24V PCB pad on the EV kit. Connect the negative terminal of the power supply to the GND PCB pad.
- 7) Enable both power supplies.
- 8) Send SPI signals to the EV kit through the SPI/I²C 12-pin header.
- 9) Detect the output at the IOLINK1-IOLINK4 4-pin headers.
- 10) The EV kit is now ready for additional testing.

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Table 1. Default Shunt Positions (JU1–JU19)

| JUMPER | SHUNT POSITION | PIN CONNECTION | EV KIT FUNCTION |
|-----------|----------------|---|---|
| JU1 | Not installed | U1, pin 1 (SPI/I ² C) connected to +3.3V through resistor R11. | SPI mode. |
| JU2 | Not installed | U2, pin 4 and U3, pin 4 (INA) connected to GND through resistor R12. | IO link selected. |
| JU3–JU10 | Not installed | D5–D12 (anodes) not connected. | D5–D12 not used. |
| JU11 | 1-2 | U12, pin 1 (IN) connected to +3.3V. | SPI/I ² C header, pin 5 (CSN) connected to JU19, pin 3 (CS). |
| JU12 | 1-2 | SPI/I ² C header, pin 6 (MISO) connected to U1, pin 3. | U1 connected to SPI interface controller (MISO). |
| JU13 | 1-2 | SPI/I ² C header, pin 7 (SCLK) connected to U1, pin 4. | U1 connected to SPI interface controller (SCLK). |
| JU14–JU17 | 1-2 | Install shunts in the 1-2 default position (JU14–JU17 are “don’t care” when operating in SPI mode). | |
| JU18 | 1-3 | SPI/I ² C header, pin 10 (MOSI) connected to U1, pin 6. | U1 connected to SPI interface controller (MOSI). |
| JU19 | 1-3 | U12, pin 6 (CS) connected to U1, pin 5. | U1 connected to SPI interface controller (CSN). |

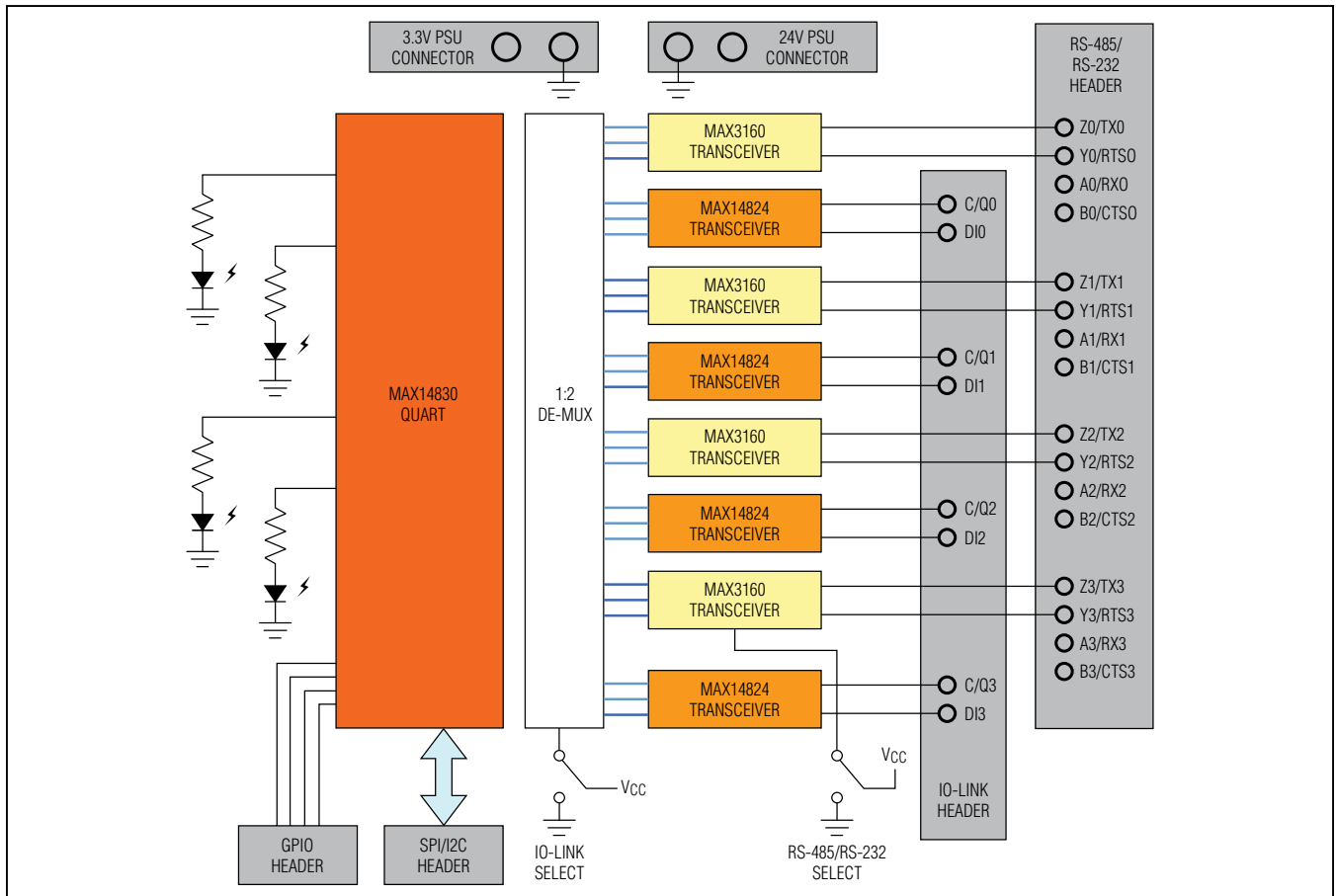


Figure 1. System Setup Example

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Detailed Description of Hardware

The MAX14830 EV kit provides a proven design to evaluate the MAX14830 IC. The IC is an advanced quad-channel UART with each UART containing 128 words of receive and transmit FIFO buffer that can be controlled through SPI or I²C. Each of the four UARTs is selected through SPI or I²C in-band addressing.

Each of the four UARTs can interface with an IO-Link master transceiver or an RS-485/RS-232 multiprotocol transceiver. The EV kit contains four on-board IO-Link master transceivers, four RS-485/RS-232 multiprotocol transceivers, and 8-channel DPDT switches to select between the IO link and RS-485/RS-232 transceivers.

Jumper Selection

SPI/I²C Operating Mode (SPI/I²C)

Jumper JU1 selects the IC's operating mode. The operating mode is selectable between SPI and I²C. See Table 2 for JU1 shunt positions.

Table 2. JU1 Jumper Selection (SPI/I²C)

| SHUNT POSITION | U1-1 (SPI/I ² C) CONNECTED TO | OPERATING MODE |
|----------------|--|------------------|
| Not installed* | +3.3V (through resistor R11) | SPI |
| Installed | GND | I ² C |

*Default position.

Table 3. JU2 Jumper Selection (INA)

| SHUNT POSITION | U2-4 AND U3-4 (INA) CONNECTED TO | OUTPUT INTERFACE |
|----------------|----------------------------------|------------------|
| Not installed* | GND (through resistor R12) | IO link |
| Installed | +3.3V | RS-485/RS-232 |

*Default position.

Table 5. JU11 Jumper Selection (CSN)

| SHUNT POSITION | U12-1 (IN) CONNECTED TO | SPI/I ² C HEADER, PIN 5 (CSN) CONNECTED TO | CSN SERVING |
|----------------|---|---|-----------------------|
| 1-2* | +3.3V | U1, pin 5 ($\overline{CS}/A0$) (through jumper JU19) | UART |
| 2-3 | GND | U4-U7, pin 6 (\overline{CS}) | IO links |
| Not installed | SPI/I ² C header, pin 11 (CSN_SEL) | CSN connection selected by CSN_SEL | Determined by CSN_SEL |

*Default position.

IO Link and RS-485/RS-232 Output Interface Selection (INA)

Jumper JU2 selects the IC's output interface. The output interface is selectable between the IO link and RS-485/RS-232 transceivers. See Table 3 for JU2 shunt positions.

IO-Link Signal Indicators ((C/Q)/(DI))

Jumpers JU3-JU10 connect or disconnect the IO-Link signal (C/Q)/(DI) from their respective LED indicators. Install shunts to connect or remove shunts to disconnect the IO-Link signal from their respective LED indicators. Table 4 lists the correspondence between jumpers JU3-JU10 to their respective IO-Link signal and LED indicators.

UART and IO-Link Chip-Select Signal (CSN)

Jumper JU11 selects the destination for the CSN (chip-select signal on the SPI/I²C header, pin 5). The CSN chip-select signal can be set to serve either the UART (MAX14830) or the four IO links (MAX14824) using JU11. See Table 5 for JU11 shunt positions.

Table 4. JU3-JU10 Jumper Legend (LEDs)

| JUMPER* | SIGNAL/POWER | LED |
|---------|--------------|-----|
| JU3 | IOLINK0 C/Q | D5 |
| JU4 | IOLINK0 DI | D6 |
| JU5 | IOLINK1 C/Q | D7 |
| JU6 | IOLINK1 DI | D8 |
| JU7 | IOLINK2 C/Q | D9 |
| JU8 | IOLINK2 DI | D10 |
| JU9 | IOLINK3 C/Q | D11 |
| JU10 | IOLINK3 DI | D12 |

*Install shunts to connect or remove (default) shunts to disconnect from LED.

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MISO/SDA

Jumper JU12 configures the MISO/SDA pin (U1, pin 3) and routes the signal to the respective headers. See Table 6 for JU12 shunt positions.

SCLK/SCL

Jumper JU13 configures the SCLK/SCL pin (U1, pin 4) and routes the signal to the respective headers. See Table 7 for JU13 shunt positions.

MOSI/A1

Jumpers JU14 and JU18 configure the MOSI/A1 pin (U1, pin 6). See Table 8 for JU14 and JU18 shunt positions.

$\overline{CS}/A0$

Jumpers JU15 and JU19 configure the $\overline{CS}/A0$ pin (U1, pin 5). See Table 9 for JU15 and JU19 shunt positions.

Table 6. JU12 Jumper Selection (MISO/SDA)

| SHUNT POSITION | MISO/SDA PIN CONNECTED TO | OPERATING MODE |
|----------------|--|------------------|
| 1-2* | SPI/ $\overline{I2C}$ header, pin 6 (MISO) | SPI |
| 2-3 | SPI/ $\overline{I2C}$ header, pin 9 (SDA) | I ² C |
| Not installed | Not connected | Not selected |

*Default position.

Table 7. JU13 Jumper Selection (SCLK/SCL)

| SHUNT POSITION | SCLK/SCL PIN CONNECTED TO | OPERATING MODE |
|----------------|--|------------------|
| 1-2* | SPI/ $\overline{I2C}$ header, pin 7 (SCLK) | SPI |
| 2-3 | SPI/ $\overline{I2C}$ header, pin 8 (SCL) | I ² C |
| Not installed | Not connected | Not selected |

*Default position.

Table 8. JU14 and JU18 Jumper Selection (MOSI/A1)

| SHUNT POSITION | | MOSI/A1 PIN CONNECTED TO | OPERATING MODE |
|----------------|----------|---|-------------------|
| JU18 | JU14 | | |
| 1-3 | Not used | SPI/ $\overline{I2C}$ header, pin 10 (MOSI) | SPI |
| 1-2 | Not used | +3.3V | I ² C* |
| 1-5 | Not used | GND | |
| 1-4 | 1-2 | SPI/ $\overline{I2C}$ header, pin 9 (SDA) | |
| | 2-3 | SPI/ $\overline{I2C}$ header, pin 8 (SCL) | |
| Not installed | Not used | Not connected | Not selected |

*Refer to the MAX14830 IC data sheet for the corresponding I²C slave address.

Table 9. JU15 and JU19 Jumper Selection ($\overline{CS}/A0$)

| SHUNT POSITION | | $\overline{CS}/A0$ PIN CONNECTED TO | OPERATING MODE |
|----------------|----------|---|-------------------|
| JU19 | JU15 | | |
| 1-3 | Not used | SPI/ $\overline{I2C}$ header, pin 5 (CSN) (with shunt installed on pins 1-2 of JU11) | SPI |
| 1-2 | Not used | +3.3V | I ² C* |
| 1-5 | Not used | GND | |
| 1-4 | 1-2 | SPI/ $\overline{I2C}$ header, pin 9 (SDA) | |
| | 2-3 | SPI/ $\overline{I2C}$ header, pin 8 (SCL) | |
| Not installed | Not used | Not connected | Not selected |

*Refer to the MAX14830 IC data sheet for the corresponding I²C slave address.

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RS-485/RS-232 Selection

Jumper JU16 selects between the RS-485 and RS-232 output protocols for the EV kit. See Table 10 for JU16 shunt positions.

Table 10. JU16 Jumper Selection (RS-485/RS-232)

| SHUNT POSITION | RS-485/RS-232 PINS CONNECTED TO | OUTPUT PROTOCOL |
|----------------|---------------------------------|-----------------|
| 1-2* | +3.3V | RS-485 |
| 2-3 | GND | RS-232 |
| Not installed | Not connected | Not selected |

*Default position.

Half Duplex and Full Duplex (HDPLX)

Jumper JU17 selects either a half-duplex or full-duplex output protocol for the EV kit. See Table 11 for JU17 shunt positions.

Table 11. JU17 Jumper Selection (HDPLX)

| SHUNT POSITION | HDPLX PINS CONNECTED TO | OUTPUT PROTOCOL |
|----------------|-------------------------|-----------------|
| 1-2* | +3.3V | Half duplex |
| 2-3 | GND | Full duplex |
| Not installed | Not connected | Not selected |

*Default position.

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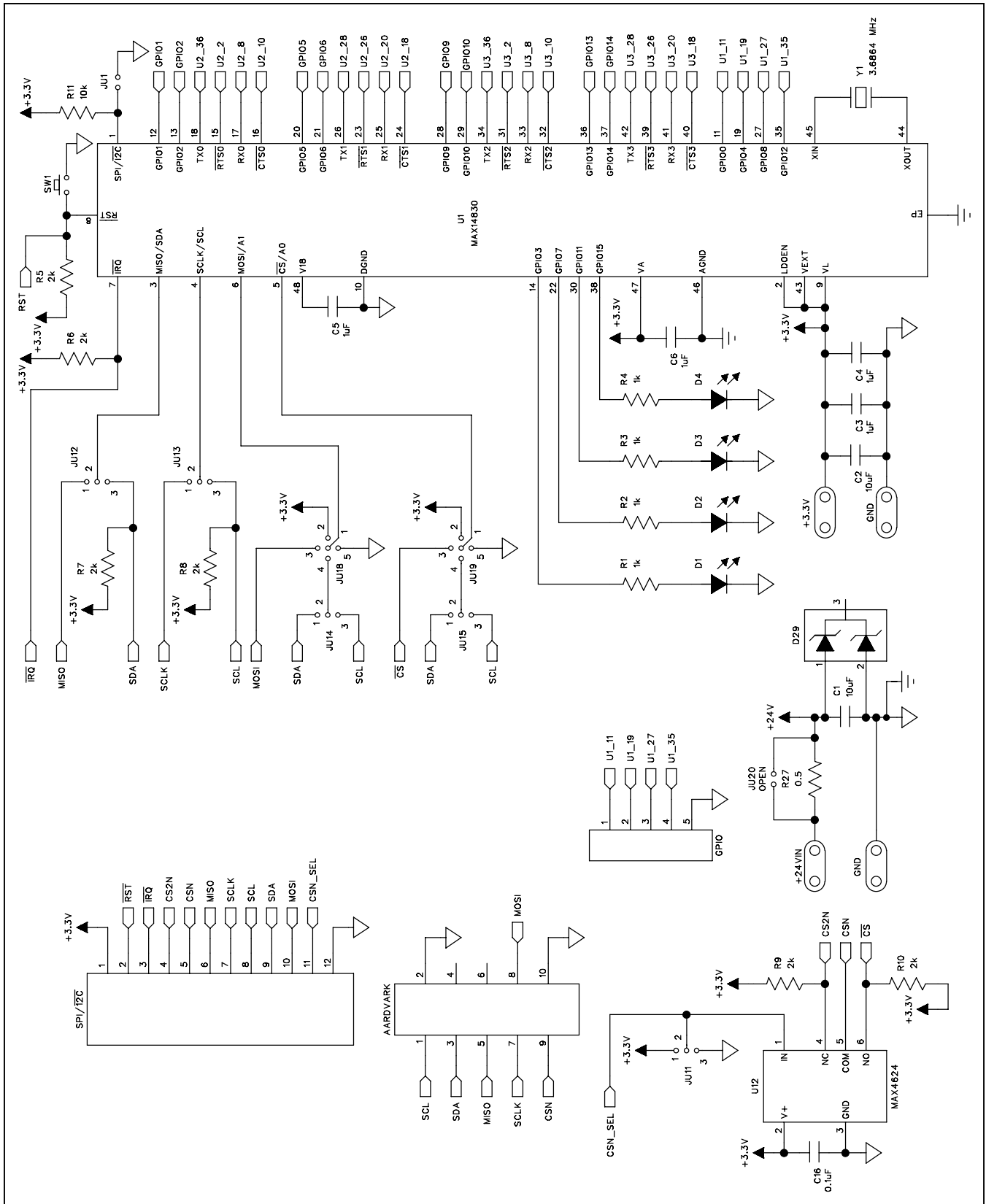


Figure 2a. MAX14830 EV Kit Schematic (Sheet 1 of 4)

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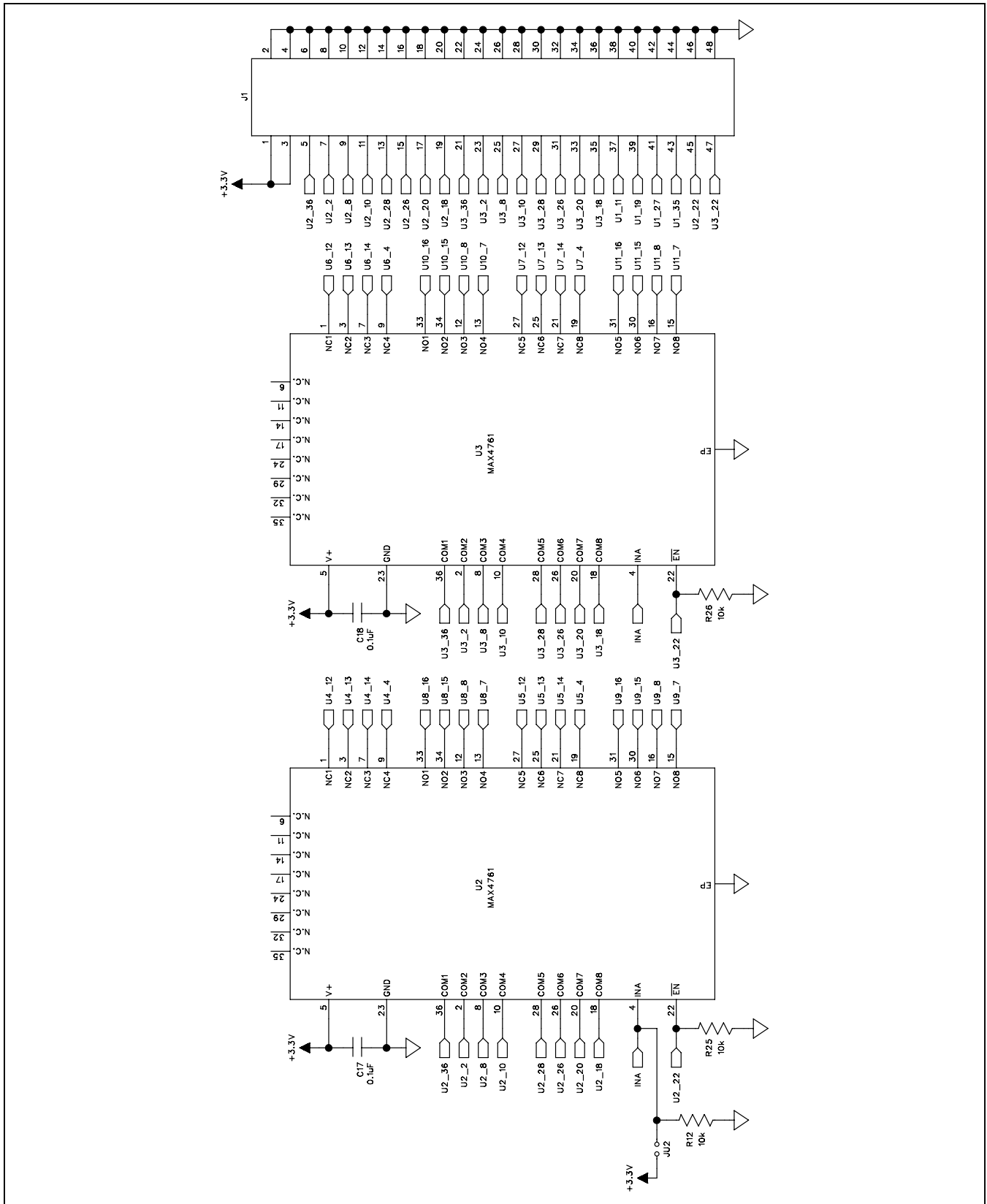


Figure 2b. MAX14830 EV Kit Schematic (Sheet 2 of 4)

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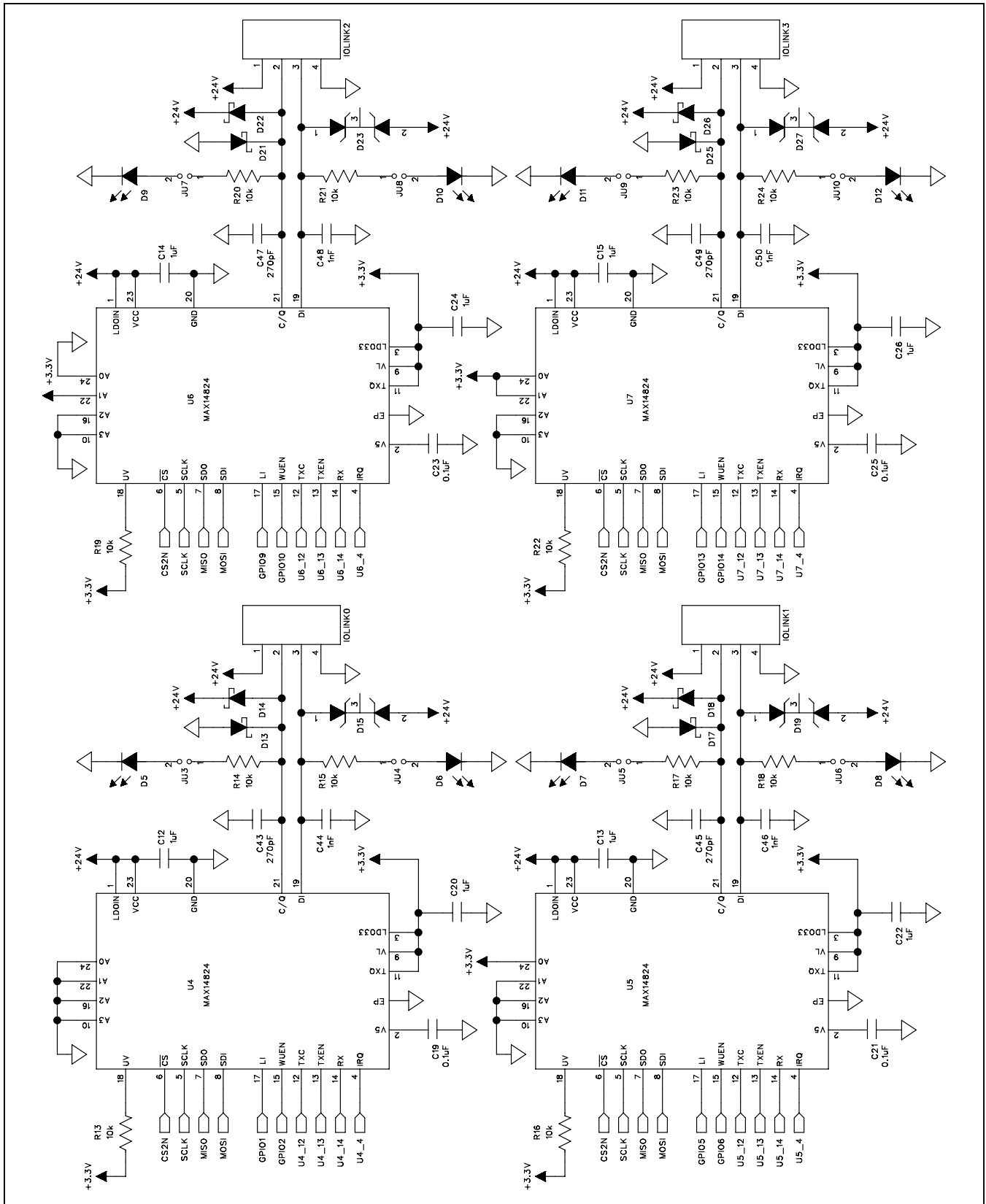


Figure 2c. MAX14830 EV Kit Schematic (Sheet 3 of 4)

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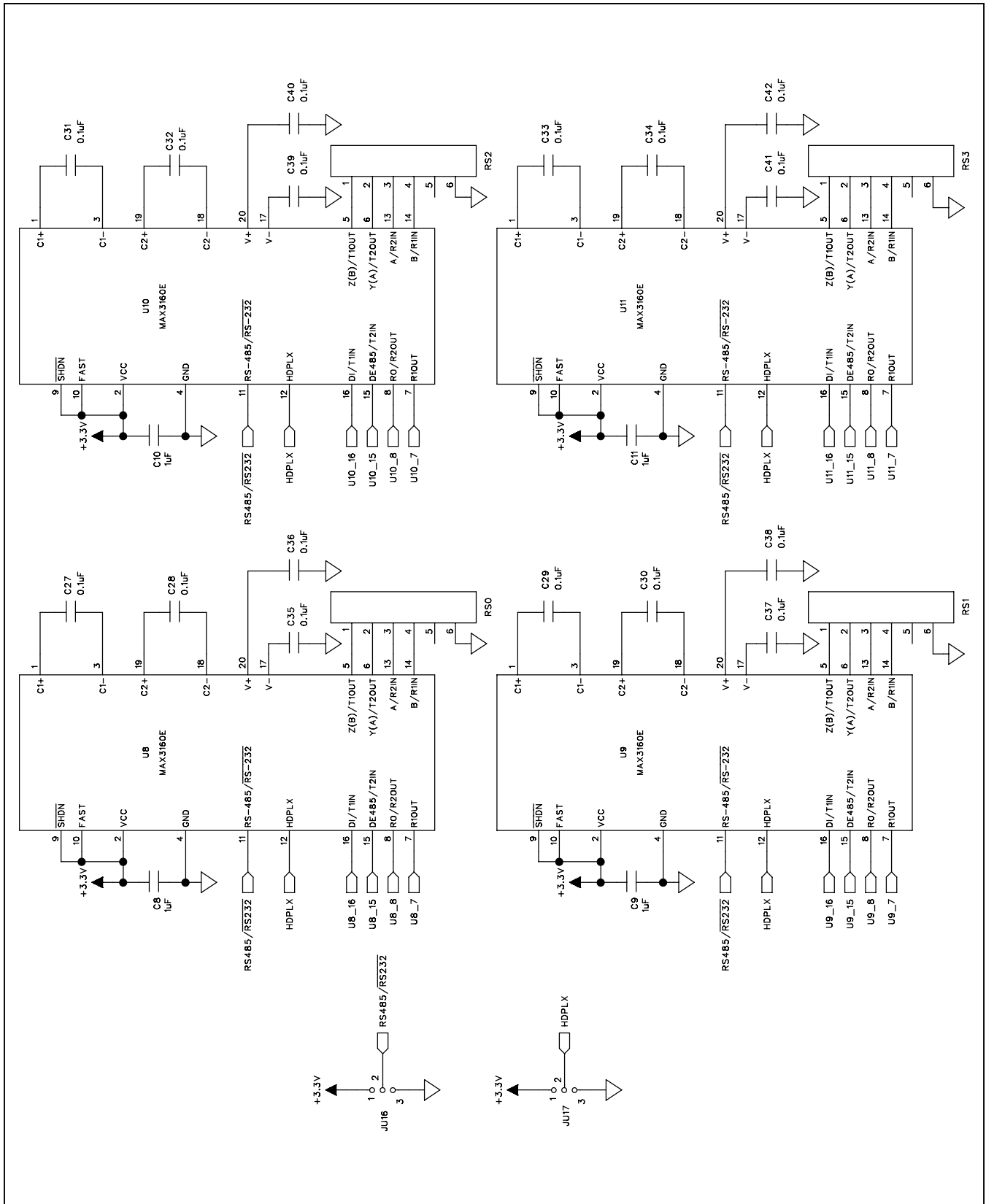


Figure 2d. MAX14830 EV Kit Schematic (Sheet 4 of 4)

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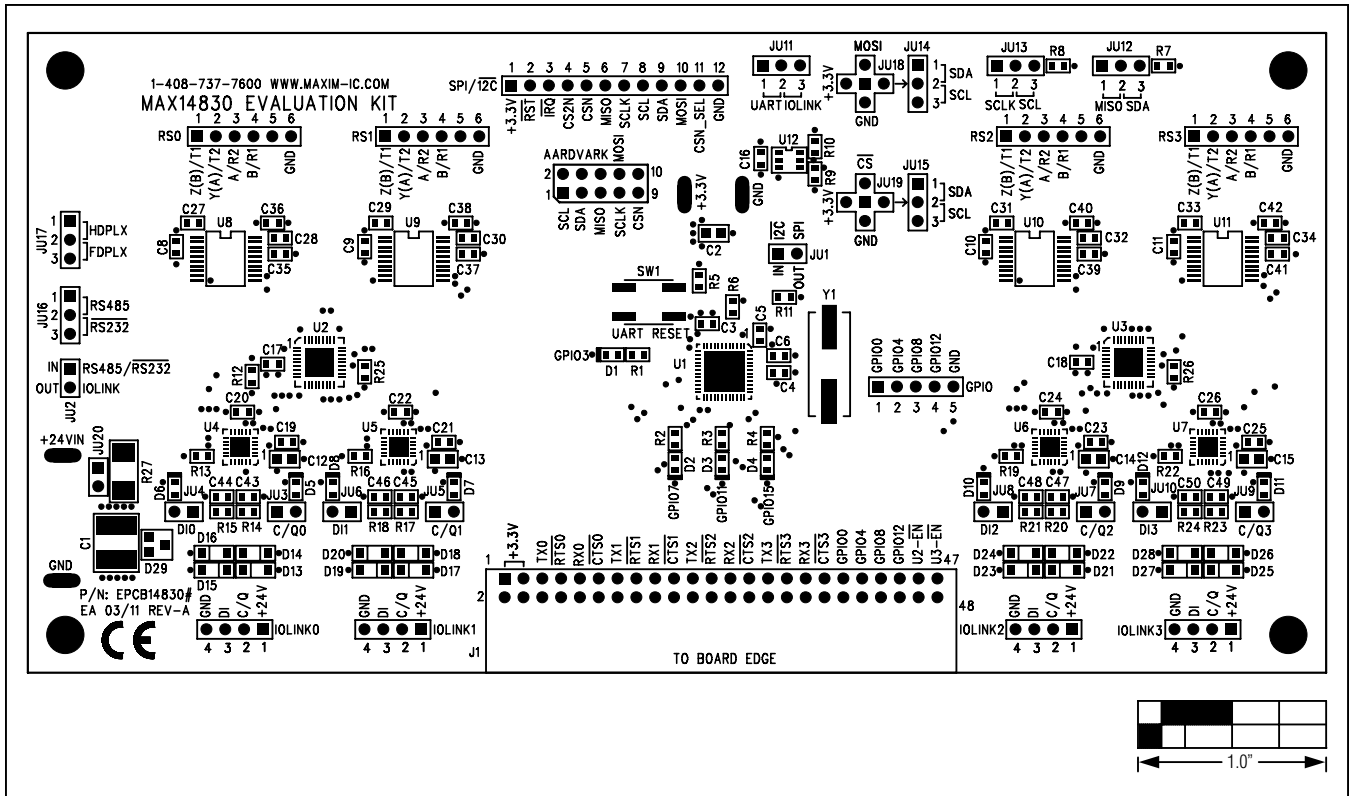


Figure 3. MAX14830 EV Kit Component Placement Guide—Component Side

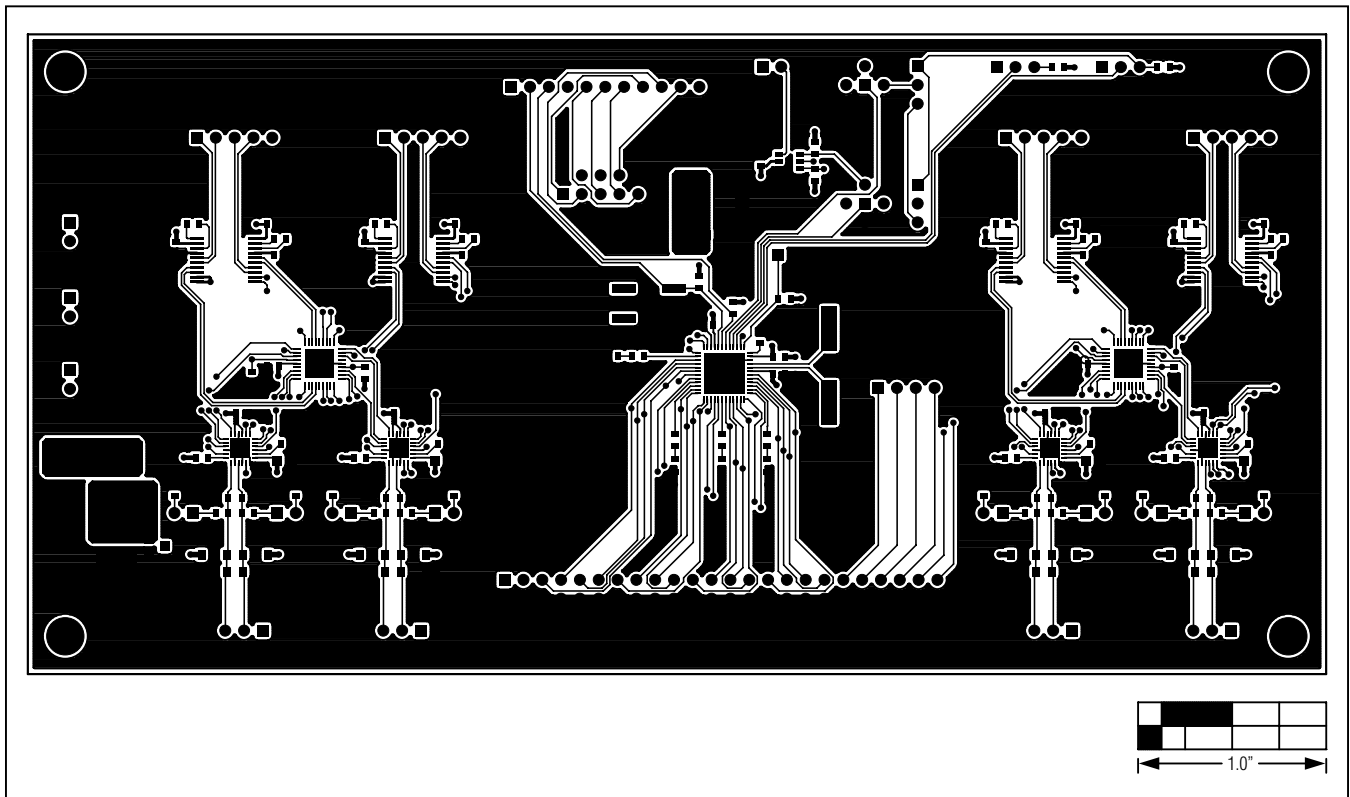


Figure 4. MAX14830 EV Kit PCB Layout—Component Side

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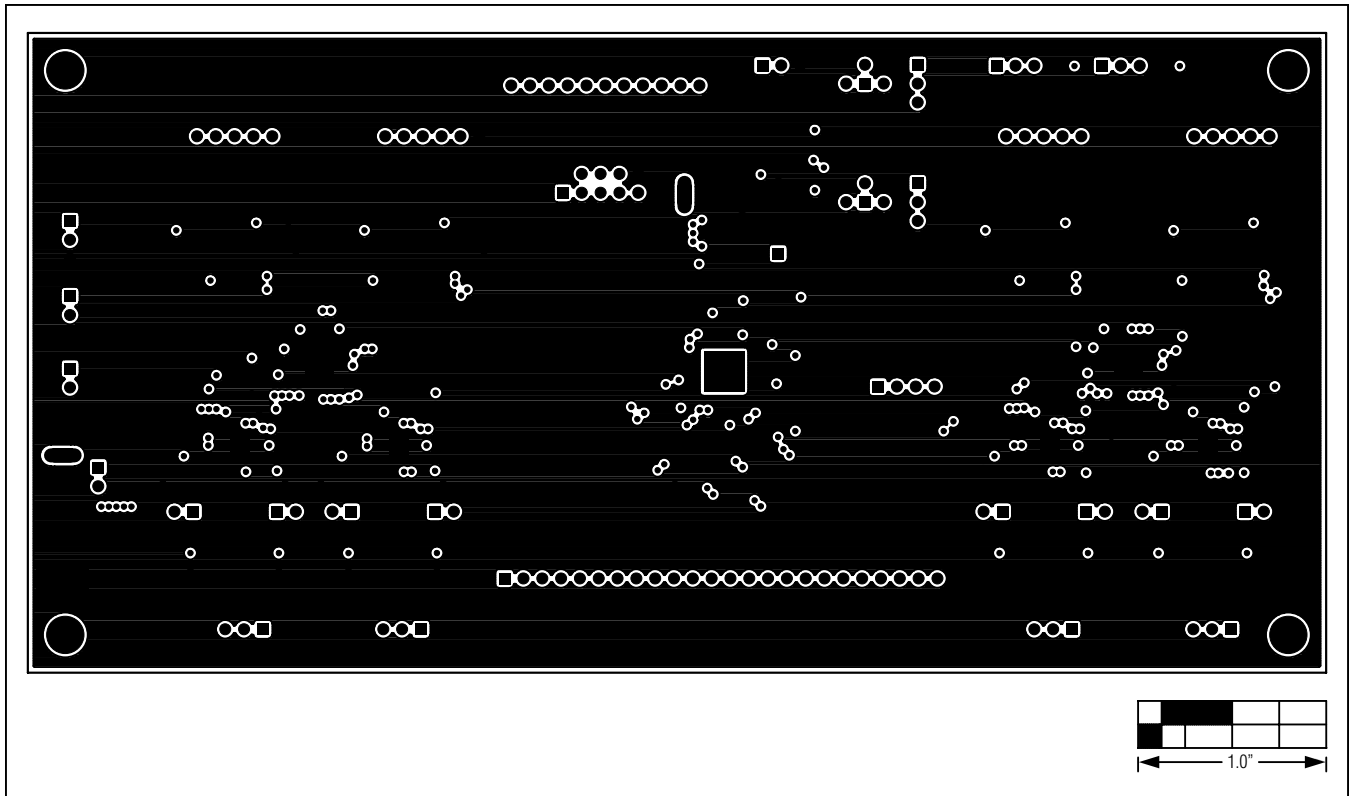


Figure 5. MAX14830 EV Kit PCB Layout—GND Layer 2

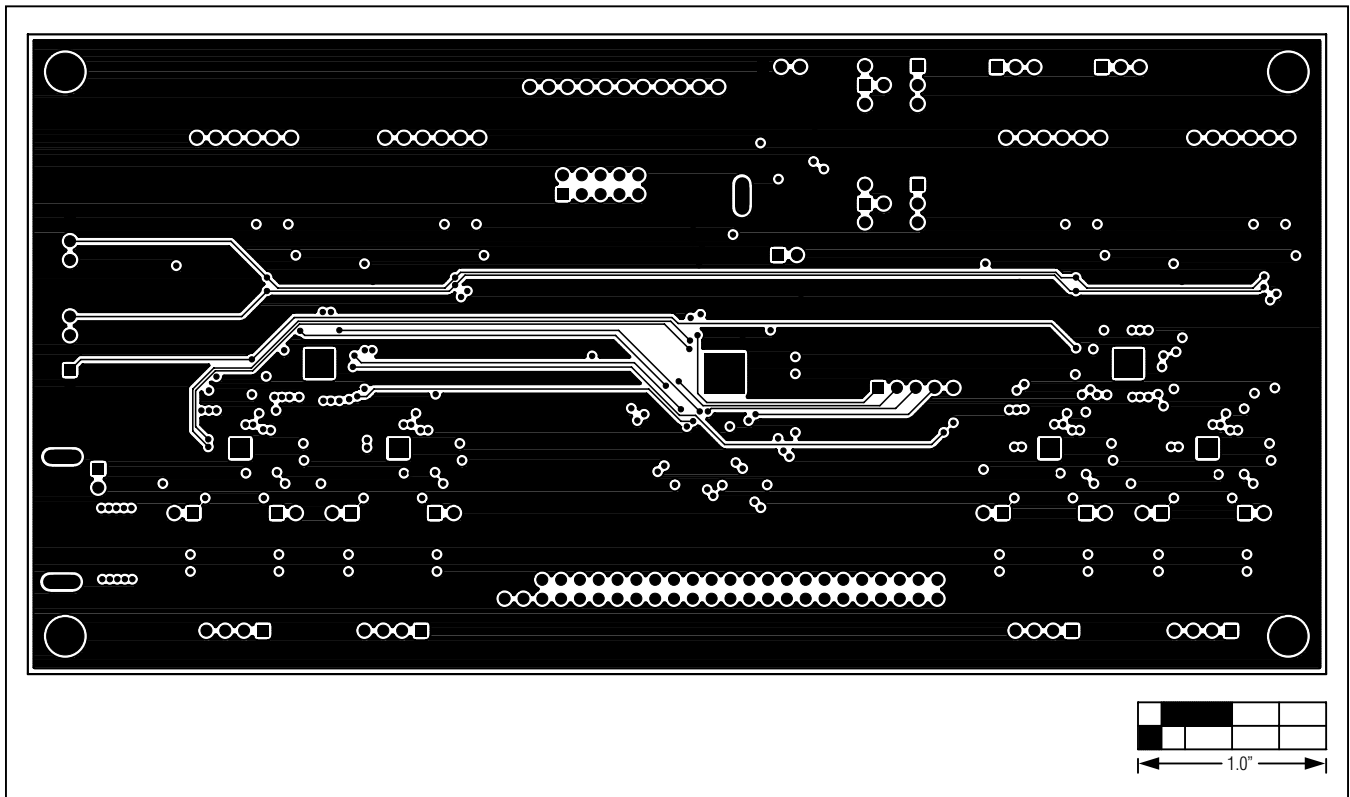


Figure 6. MAX14830 EV Kit PCB Layout—PWR Layer 3

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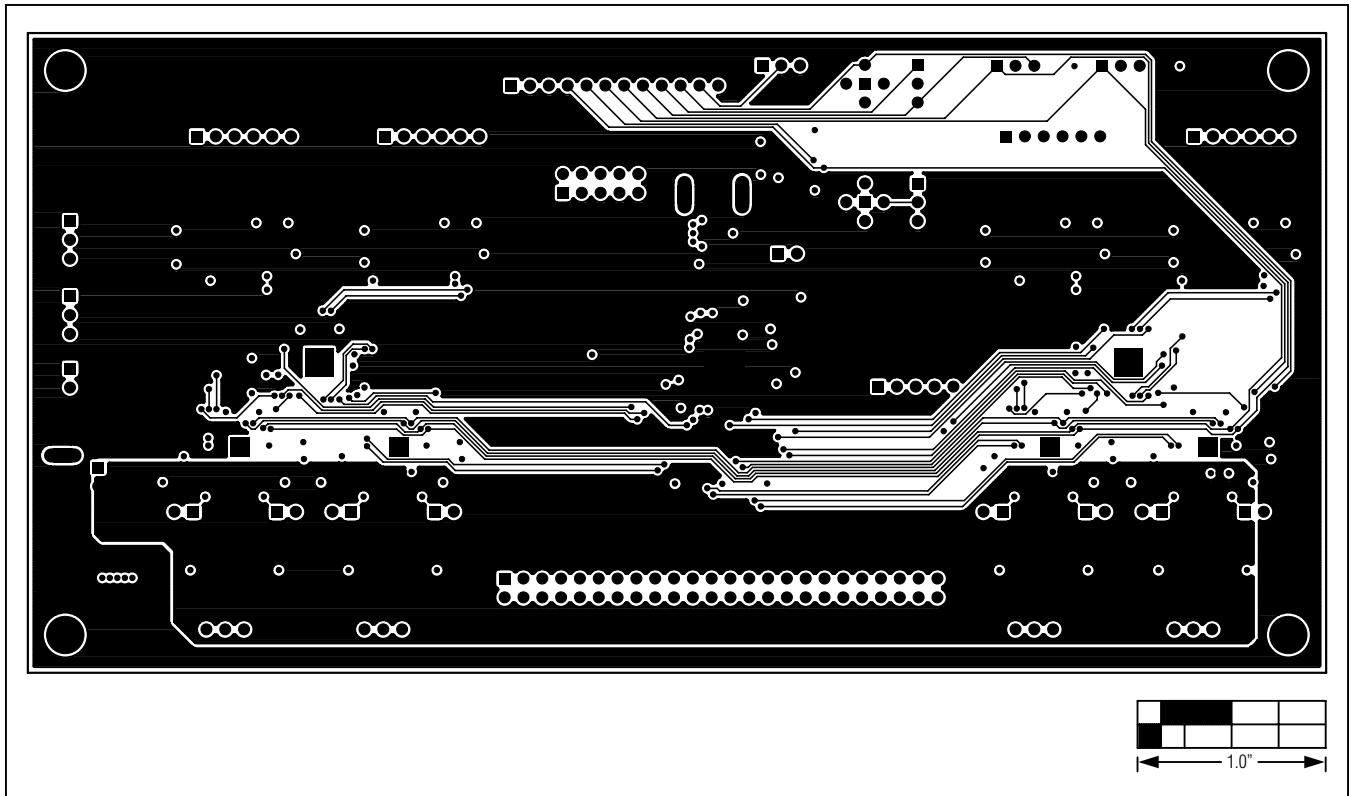


Figure 7. MAX14830 EV Kit PCB Layout—Solder Side

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Ordering Information

| PART | TYPE |
|----------------|-------------|
| MAX14830EVKIT# | EV Kit |

#Denotes RoHS compliant.

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Revision History

| REVISION NUMBER | REVISION DATE | DESCRIPTION | PAGES CHANGED |
|-----------------|---------------|---|---------------|
| 0 | 11/11 | Initial release | — |
| 1 | 7/12 | Updated <i>Component List</i> and Figure 2c | 1, 2, 9 |

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