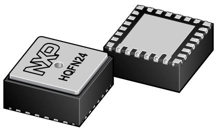
NTM88Jxx5S

Tire pressure monitor sensor

Rev. 3 — 25 September 2024 | Product data sheet



1 General description

The NTM88 family consists of small (4 mm x 4 mm x 1.98 mm), fully integrated tire pressure monitoring sensors (TPMS). The devices described in this data sheet, NTM88Jxx5S, provide low transmitting power consumption, large customer memory size, and single- or dual-axis accelerometer architecture. The NTM88Jxx5S TPMS solution integrates an 8-bit microcontroller (MCU), pressure sensor, accelerometers in three ranges, programmable RF transmitter and flexible LF receiver. The sensor supports seven GPIOs, client SPI, and a 2-channel timer / pulse-width module.

2 Features and benefits

- Optional pressure ranges[1]
- Optional accelerometer ranges: See Section 3.
- Transducer measurement interfaces with low-power AFE:
  - 10-bit compensated pressure sense element
  - 10-bit compensated accelerometers
  - 8-bit compensated internal device temperature measurement
  - 8-bit compensated internal device voltage measurement
  - Two I/O pins can be used for external signals
- 8-bit S08 compact instruction set controller:
  - 64 bytes low-power "always on" NVM parameter registers
  - 512 bytes SRAM
  - 16 kB flash memory (512 bytes reserved for NXP coefficients)
  - Family of NXP firmware libraries available via royalty-free license
- Programmable RF transmitter
  - Characterized for RF carrier typical of 315 MHz or 434 MHz
  - Characterized for FSK in ~3 kHz increments or OOK modulation
  - Characterized for baud rate examples of 9.6 kbp/s, 19.2 kbp/s, and 38.4 kbp/s
- Flexible 125 kHz LF receiver:
  - Capability for ASK or OOK demodulation
  - Automated Manchester decoding
- Two channel timer / pulse-width module
- Client SPI to support host access to internal peripherals, registers, and memory
- Seven GPIOs with programmable multiplexing to support software development, external analog voltage input, timer, SPI, and wake-up
- Qualified in compliance with AEC-Q100, Rev. H

1 Consult NXP sales for details or specific requests.

- Long battery service life
- Internal temperature sensor
- Internal voltage sensor
- Six-channel, 8-, 10-, or 12-bit analog-to-digital converter with two external I/O inputs
- Internal 315 MHz/434 MHz RF transmitter
  - External crystal oscillator
  - PLL-based output with fractional-n divider
  - OOK and FSK modulation capability
  - Programmable data rate generator
  - Manchester, Bi-Phase, or NRZ data encoding
  - 256-bit RF data buffer variable length interrupt
  - Direct access to RF transmitter from MCU for unique formats
  - Low-power consumption
- Differential input LF detector/decoder on independent signal pins
- Real-time Interrupt driven by LFO with intervals of 2, 4, 8, 16, 32, 64, or 128 ms
- Free-running counter, low-power, wake up timer and periodic reset driven by LFO
- Watchdog timeout with selectable times and clock sources
- Two-channel general-purpose timer/PWM module (TPM1)
- Internal oscillators
  - MCU bus clock of 0.5, 1, 2, and 4 MHz (1, 2, 4, and 8 MHz HFO)
  - Low frequency, low-power time clock (LFO) with 1 ms period
  - Medium frequency, controller clock (MFO) of 8 µs period
- Low-voltage detection

3 Ordering information

Table 1. Ordering information

Type number	Package		
	Name	Description	Version
NTM88Jxx5S	HQFN24	Plastic thermal enhanced quad flat package; no leads, 0.1 dimple wettable flank; 24 terminals; 0.5 mm pitch, 4 mm x 4 mm x 1.98 mm body	SOT1931-1(D)

Table 2. Ordering options

Part Number 'N8'	Pressure Range 'p'	Accelerometer 'aa'		X-axis Range	Z-axis Range	CodeH Hardware (First Rev)[1]
NTM88J125ST1[2]	90 kPa to 1110 kPa 'J'	XZ	'12'	–400 g to +400 g	–175 g to +550 g	$8C
NTM88J135ST1[2]			'13'	–80 g to +90 g	–360 g to +400 g	$8D
NTM88J145ST1[2]		XZ	14	–360 g to +400 g	–80 g to +90 g	$8E
NTM88J155ST1[2]			15	–360 g to +400 g	–360 g to +400g	$8F

[1] The value CodeF mentioned in the User Manual UM11227[1] depicts the version of firmware used by NXP during device tests, and will become $FF as the device is shipped. The value of CodeF will be replaced again by the version number of the firmware library used by the customer at the time of device final application programming.

[2] Product under development, consult your NXP sales representatives for samples.

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4 Block diagram

Figure 1 presents the device's main blocks and their signal interactions. Power management controls and bus control signals are not shown in this block diagram for clarity.

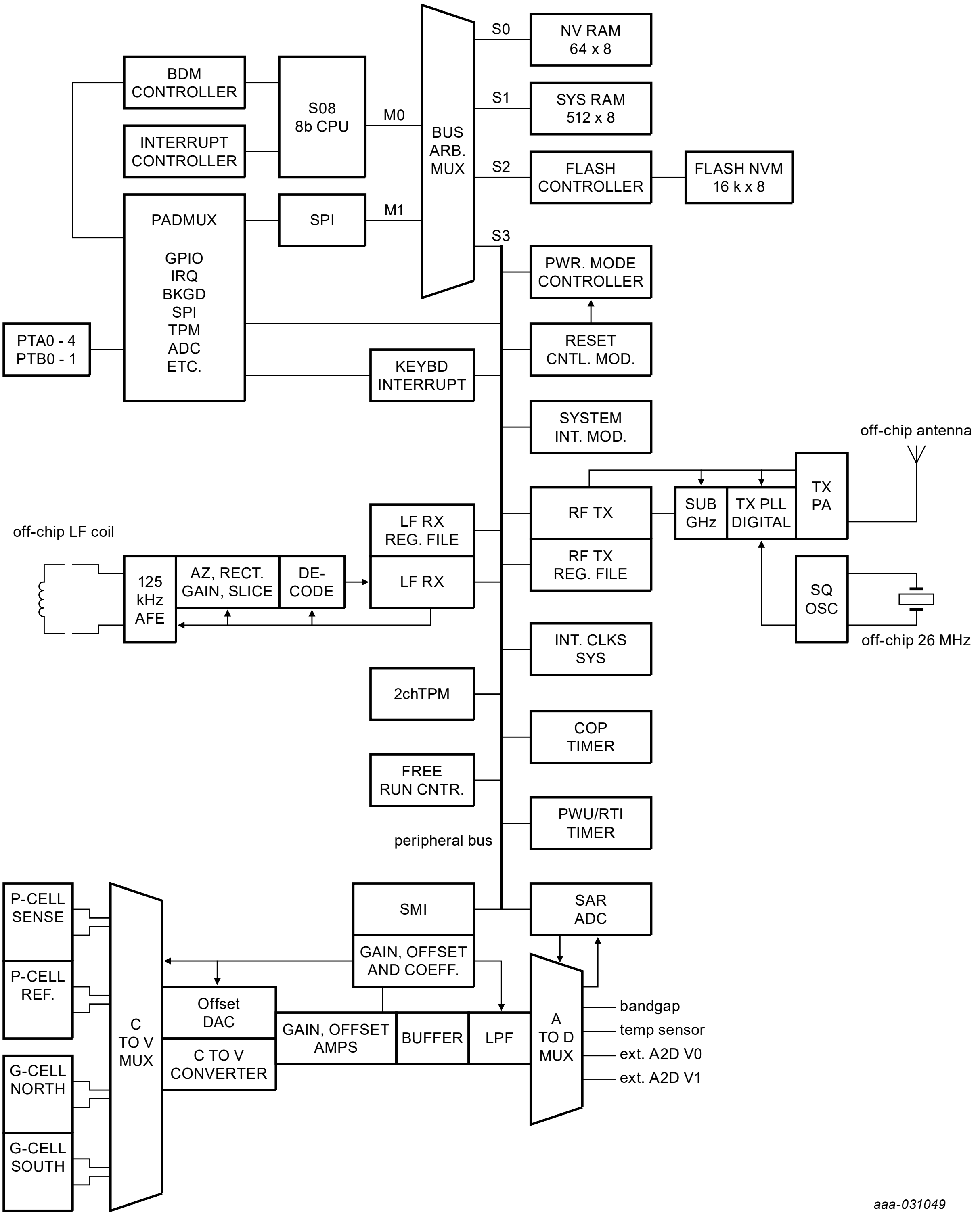

Figure 1. Block diagram

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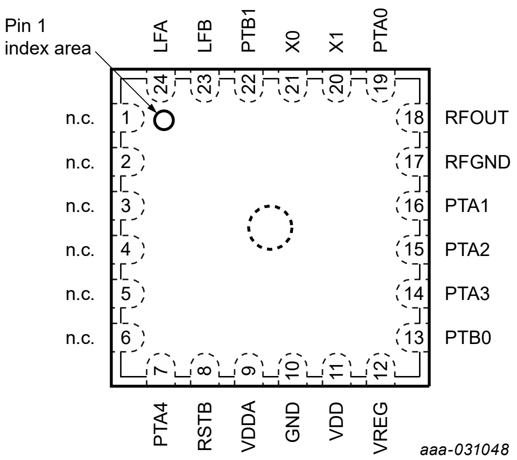
5 Pinning information

5.1 Pinning

A top view of the device pint with the pressure port on top is show in Figure 2. The orientation of the internal Z-axis accelerometer is shown in Figure 3.



Note: *Pins 1-6 are mechanically and electrically connected to the central flag; See Section 9.*

Figure 2. Pin configuration

5.2 Pin description

Table 3. Pin description

Symbol	Pin	Function	Description
n.c.	1	—	Do not connect electrical signals to this pin; solder joint only.
n.c.	2	—	Do not connect electrical signals to this pin; solder joint only.
n.c.	3	—	Do not connect electrical signals to this pin; solder joint only.
n.c.	4	—	Do not connect electrical signals to this pin; solder joint only.
n.c.	5	—	Do not connect electrical signals to this pin; solder joint only.
n.c.	6	—	Do not connect electrical signals to this pin; solder joint only.
PTA4	7	PTA4 / BKGD	PTA4 Pin - The PTA4 pin places the device in the BACKGROUND DEBUG mode (BDM) to evaluate MCU code and transfer data to/from the internal memory. If the BKGD/PTA4 pin is held low when the device comes out of a power-on-reset (POR), the device switches into the ACTIVE BACKGROUND DEBUG mode (BDM). The BKGD/PTA4 pin has an internal pullup device or can be connected to VDD in the application, unless there is a need to enter BDM operation after the device as been soldered into the PWB. If in-circuit BDM is desired, the BKGD/PTA4 pin should be connected to VDD through a resistor (~10 kΩ or greater) which can be over-driven by an external signal. This resistor reduces the possibility of inadvertently activating the debug mode in the application due to an EMC event. When the application programs port A to GPIOs, PTA4 becomes output-only.

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Table 3. Pin description*...continued*

Symbol	Pin	Function	Description
RST_B	8	Reset	The RST_B pin is an active-low hardware reset. When asserted, the MCU takes the reset vector. It is also used to establish a BDM connection and for other test purposes. The RST_B pin has an internal pullup device and can be connected to VDD in the application unless there is a need to enter BDM operation after the device as been soldered to the PWB. If in-circuit BDM is desired, the RST_B pin can be left unconnected; but should be connected to VDD through a low impedance resistor (<10 kΩ) which can be over-driven by an external signal. This low impedance resistor reduces the possibility of getting into the debug mode in the application due to an EMC event. Activation of the external reset function occurs when the voltage on the RST_B pin goes below 0.3 × V_{DD} for at least 100 ns before rising above 0.7 × V_{DD}.
VDDA	9	Analog supply	The analog circuits operate from a single power supply connected to the unit through the VDDA pin. VDDA is the positive supply and GND is the ground. The conductors to the power supply should be connected to the VDDA and GND pins and locally decoupled. Care should be taken to reduce measurement signal noise by separating the VDD, GND, VDDA, and RFGND pins using a “star” connection such that each metal trace does not share any load currents with other external devices.
GND	10	Digital and analog ground	The digital and analog circuits operate from a single power supply connected to the unit through the VDD, VDDA, and GND pins. GND is the ground. Care should be taken to reduce measurement signal noise by separating the GND and RFGND pins using a “star” connection such that each metal trace does not share any load currents with other external devices.
VDD	11	Digital supply	The digital circuits operate from a single power supply connected to the unit through the VDD and GND pins. VDD is the positive supply. The conductors to the power supply should be connected to the VDD and GND pins and locally decoupled.
VREG	12	1.8 V regulation	The internal regulator for the RF analog circuits requires an external stabilization capacitor to GND.
PTB0	13	PTB0 / TPMCH0 / AD3	The PTB[0] pin is a general-purpose I/O pin. This pin can be configured as a nominal bidirectional I/O pin with programmable pullup devices. User software must configure the general-purpose I/O pin (PTB[1:0]) so that they do not result in “floating” inputs. PTB0 can be mapped to TPM channel 0, or to ADC channel 3.
PTA3	14	PTA3 / KBI3 / MOSI	The PTA[3] pin is a general-purpose I/O pin. The pulldown devices can only be activated if the wake-up interrupt capability is enabled. User software must configure the general-purpose I/O pins so that they do not result in “floating” inputs. PTA[3] maps to keyboard interrupt function bit [3]. When SPI is enabled, PTA[3] serves as MOSI.
PTA2	15	PTA2 / KBI2 / MISO	The PTA[2] pin is a general-purpose I/O pin. The pulldown devices can only be activated if the wake-up interrupt capability is enabled. User software must configure the general-purpose I/O pins so that they do not result in “floating” inputs. PTA[2] maps to keyboard interrupt function bit [2]. When SPI is enabled, PTA[2] serves as MISO.
PTA1	16	PTA1 / KBI1 / SCLK	The PTA[1] pin is a general-purpose I/O pin. The pulldown devices can only be activated if the wake-up interrupt capability is enabled. User software must configure the general-purpose I/O pins so that they do not result in

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Table 3. Pin description*...continued*

Symbol	Pin	Function	Description
			“floating” inputs. PTA[1] maps to keyboard interrupt function bit [1]. When SPI is enabled, PTA[1] serves as SCLK
RFGND	17	RF ground	Power in the RF output amplifier is returned to the supply through the RFGND pin. This conductor should be connected to the power supply using a “star” connection such that each metal trace does not share any load currents with other supply pins.
RFOUT	18	RF output	The RFOUT pin is the RF energy data supplied by the unit to an external antenna.
PTA0	19	PTA0 / KBI0 / SS_B / IRQ	The PTA[0] pin is a general-purpose I/O pin. PTA[0] can be configured as a normal bidirectional I/O pin with programmable pullup or pulldown devices and/or wake-up interrupt capability. PTA[0] can be configured for external interrupt (IRQ). The pulldown devices can only be activated if the wake-up interrupt capability is enabled. User software must configure the general-purpose I/O pins so that they do not result in “floating” inputs. PTA[0] maps to keyboard interrupt function bit [0]. When SPI is enabled, PTA0 serves as SS_B.
X1	20	RF crystal input	The X1 pin is for an external 26 MHz crystal to be used by the internal PLL for creating the carrier frequencies and data rates for the RF pin.
X0	21	RF crystal output	The X0 pin is for an external 26 MHz crystal to be used by the internal PLL for creating the carrier frequencies and data rates for the RF pin.
PTB1	22	PTB1 / TPMCH1 / AD4	The PTB[1] pin is a general-purpose I/O pin. This pin can be configured as a nominal bidirectional I/O pin with programmable pullup devices. User software must configure the general-purpose I/O pins (PTB[1:0]) so that they do not result in “floating” inputs. PTB1 can be mapped to TPM channel 1, or to ADC channel 4.
LFB	23	LF input '-'	The LF[A:B] pins can be used by the LF receiver (LFR) as one differential input channel for sensing low-level signals from an external low frequency (LF) coil. The external LF coil should be connected between the LF[A] and the LF[B] pins. Signaling into the LFR pins can place the unit into various diagnostic or operational modes. The LFR is comprised of the detector and the decoder. Each LF[A:B] pin always has an impedance of approximately 500 kΩ to GND due to the LFR input circuitry. The LFA/LFB pins are used by the LFR when the LFEN control bit is set and are not functional when the LFEN control bit is clear.
LFA	24	LF input '+'	The LF[A:B] pins can be used by the LF receiver (LFR) as one differential input channel for sensing low-level signals from an external low frequency (LF) coil. The external LF coil should be connected between the LF[A] and the LF[B] pins. Signaling into the LFR pins can place the unit into various diagnostic or operational modes. The LFR is comprised of the detector and the decoder. Each LF[A:B] pin always has an impedance of approximately 500 kΩ to GND due to the LFR input circuitry. The LFA/LFB pins are used by the LFR when the LFEN control bit is set and are not functional when the LFEN control bit is clear.

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5.3 Orientation

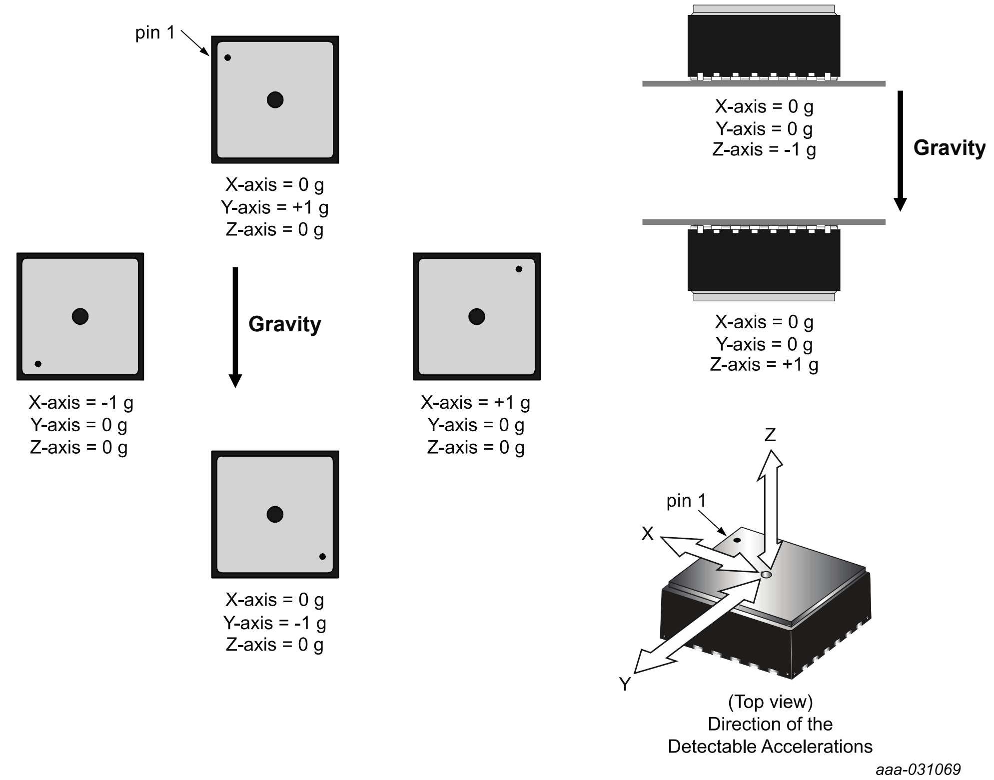

Figure 3. NTM88Jxx5S orientation at rest.

6 Electrical specifications

Tables in the electrical and mechanical specification sections of this data sheet may contain hyperlinked note references in the last cell of the row. The hyperlinks are linked to and defined in Table 4.

Table 4. Electrical and mechanical specification note definition table

Note identifier	Description
A	Parameters tested 100 % at final test.
B	Parameters tested 100 % at unit probe.
C	Verified by characterization, not tested in production.
D	For information only, may be determined by simulation.

6.1 Maximum ratings (electrical)

Maximum ratings are the extreme limits the device can be exposed to without permanently damaging it. The device contains circuitry to protect the inputs against damage from high static voltages; however, do not apply voltages higher than the values shown in Table 5. Keep V_{IN} and V_{OUT} within the range $V_{SS} \leq (V_{IN}$ or $V_{OUT}) \leq V_{DD}$.

In all cases of transient environment, the sensor functional behaviors, parametric behaviors, and dimensions may deviate from the listed steady-state environment tolerances as compared to external reference(s). τ is the characteristic thermal time constant, from device case ambient to the on-die temperature transducer. Transient

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environment means less than 2.3 × τ seconds since the last step-function transient of a condition; pressure, motion, temperature, supply voltage, electro-magnetic, humidity, vapor, media. Steady-state environment means 2.3 × τ or more seconds of stable conditions; pressure, motion, temperature, supply voltage, electro-magnetic, humidity, vapor, media. Examples of step-function transient condition might be tire blow-out, drop impact, ice-bath submersion, battery connection 'bounce', nearby radio transmitter, and so forth.

Table 5. Maximum ratings

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
V_{DD}	V_{DD} or V_{DDA} to V_{SS}	$T_L \le T_A \le T_h$	–0.3	—	3.6	V	C
V_{IO}	IO pin current, each pin vs V_{DD} / V_{DDA} or V_{SS}	T_{AS} Min ≤ T_A ≤ T_A Max	V_{SS} – 0.3	—	V_{DD} + 0.3	V	C
I_{IO}	IO pin current, pin vs V_{DD} / V_{DDA} or V_{SS}	$T_L \le T_A \le T_H$, V_{DDR} Min ≤ V_{DD} ≤ V_{DDR} Max	–10	—	10	mA	C
I_{SUBIO}	Substrate current injection, all IO pins except LFA LFB current from pin to V_{SS} – 0.3 V	$T_L \le T_A \le T_H$, V_{DDR} Min ≤ V_{DD} ≤ V_{DDR} Max	—	600	—	µA	C
I_{SUBLF}	Substrate current injection, LFA LFB current from pin to V_{SS} – 0.3 V	$T_L \le T_A \le T_H$, V_{DDF} Min ≤ V_{DD} ≤ V_{DDF} Max	—	2	—	mA	C
I_{LATCH}	Latch-up current, current to/from pin to V_{DD} / V_{DDA} + 0.3 V	$T_L \le T_A \le T_H$, V_{DDR} Min ≤ V_{DD} ≤ V_{DDR} Max	–100	—	100	mA	C
ESD_{HBM}	Electrostatic discharge, human body model (HBM), all pins except RF, and LF	T_A = 25 °C, V_{DD} = 3.0 V	–2000	—	2000	V	C
ESD_{HBM}	Electrostatic discharge, human body model (HBM), RF, and LF	T_A = 25 °C, V_{DD} = 3.0 V	–2000	—	2000	V	C
ESD_{CDM}	Electrostatic discharge, charged device model (CDM), all pins	T_A = 25 °C, V_{DD} = 3.0 V	–500	—	500	V	C
T_{STG}	Unpowered storage, temperature range	—	–50	—	150	°C	C

6.2 Operating conditions

The limits normally expected in the application that define the range of operation.

Table 6. Operating range

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
V_{DDR}	Operating voltage range, Parameter register retention where Min = V_L, Typ = 3.0 V, Max = V_H	T_{AS} Min ≤ T_A ≤ T_{AS} Max	1.2	3.0	3.6	V	C
V_{DDS}	Operating voltage range, MCU and SW, Flash Read, RF TX, Voltage Measurement where Min = V_L, Typ = 3.0 V, Max = V_H	T_{AS} Min ≤ T_A ≤ T_{AS} Max	V_{LVDRF}	3.0	3.6	V	C
V_{DDM}	Operating voltage range, Pressure, Temperature and Acceleration Measurements where Min = V_L, Typ = 3.0 V, Max = V_H	T_{AS} Min ≤ T_A ≤ T_{AS} Max	2.1	3.0	3.6	V	C
V_{DDF}	Operating voltage range, Flash Programming and LF RX, where Min = V_L, Typ = 3.0 V, Max = V_H	–20 °C ≤ T_A ≤ 85 °C	2.1	3.0	3.6	V	C
T_{AS}	Operating temperature range, Full functionality except LF RX, and Flash Programming where Min = T_L, Typ = 25 °C, Max = T_H	V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max	–40	25	125	°C	C

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Table 6. Operating range*...continued*

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
T_{AF}	Operating temperature range, Operating voltage range, Full functionality, including LF RX, and Flash programming	V_{DDF} Min ≤ V_{DD} ≤ V_{DDF} Max	–20	25	85	°C	C
$T_{A\text{-}EXC}$	Operating temperature range excursion; 12 excursions of 15 minutes ea. (all Tolerances may be out of spec)	V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max	—	—	150	°C	C
I_{DD1}	Supply Current; Stop1 Mode (only LFO, PWU, and param. reg. On)	Typ = 25 °C, 3.0 V, Max = T_{AS} Min to Max & V_{DDR} Min to Max	—	0.18	18	µA	B
I_{DD4}	Supply Current; Stop4 Mode (only MCU, RF, and LF disabled)	Typ = 25 °C, 3.0 V, Max = T_{AS} Min to Max & V_{DDS} Min to Max	—	75	125	µA	B
I_{DDLFS}	Supply Current; Standby LF sniff (and Stop1 equivalent)	Typ = 25 °C, 3.0 V, Max = T_{AF} Min to Max & V_{DDF} Min to Max	—	4.8	8.1	µA	C
I_{DDLFD}	Supply Current; Standby LF Decoding (and Stop1 equivalent)	Typ = 25 °C, 3.0 V, Max = T_{AF} Min to Max & V_{DDF} Min to Max	—	11.3	14.3	µA	C
i_{DDR5K}	Supply Current; MCU Run 500 kHz (and RF and LF disabled)	Typ = 25 °C, 3.0 V, Max = T_{AS} Min to Max & V_{DDS} Min to Max	—	0.8	1.0	mA	C
I_{DDR1M}	Supply Current; MCU Run 1 MHz (and RF and LF disabled)	Typ = 25 °C, 3.0 V, Max = T_{AS} Min to Max & V_{DDS} Min to Max	—	1.0	1.2	mA	C
I_{DDR2M}	Supply Current; MCU Run 2 MHz (and RF and LF disabled)	Typ = 25 °C, 3.0 V, Max = T_{AS} Min to Max & V_{DDS} Min to Max	—	1.42	1.6	mA	C
I_{DDR4M}	Supply Current; MCU Run 4 MHz (and RF and LF disabled)	Typ = 25 °C, 3.0 V, Max = T_{AS} Min to Max & V_{DDS} Min to Max	—	2.1	2.5	mA	B
I_{DDRFT3}	Supply Current; RF TX 5 dBm, 315 MHz (and Stop1 equivalent)	T_A = 25 °C, V_{DD} = 3.0 V	—	5.7	6.1	mA	B
I_{DDRFT4}	Supply Current; RF TX 5 dBm, 434 MHz (and Stop1 equivalent)	T_A = 25 °C, V_{DD} = 3.0 V	—	6.3	6.8	mA	B
$I_{DDRFTx1}$	Supply Current Increase w/ BOOST = 1 RF TX 5 dBm (and Stop1 equivalent)	T_A = 25 °C, V_{DD} = 3.0 V	—	—	0.6	mA	C
I_{DDIF0}	Supply Current, RF Interframe period, IFPD = 0	Typ = 25 °C, 3.0 V, Max = T_{AS} Min to Max & V_{DDS} Min to Max	—	610	870	µA	C
I_{DDIF1}	Supply Current, RF Interframe period, IFPD = 1	Typ = 25 °C, 3.0 V, Max = T_{AS} Min to Max & V_{DDS} Min to Max	—	19	36	µA	C
I_{DDA} or I_{DDP}	Supply Current Peak; Accel. or Pressure Measurements (and Stop4 equivalent)	Typ = 25 °C, 3.0 V, Max = T_{AS} Min to Max & V_{DDM} Min to Max	—	2.8	3.15	mA	C
I_{DDV} or I_{DDT}	Supply Current Peak; Voltage or Temp. Measurements (and Stop4 equivalent)	Typ = 25 °C, 3.0 V, Max = T_{AS} Min to Max & V_{DDM} Min to Max	—	2.8	3.8	mA	C

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6.3 Charge consumptions

Table 7. Charge consumptions

$T_L \leq T_A \leq T_H$, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
Q_{wake}	Stop1 to run charge consumption, F_{bus} set for 4 MHz	V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max	—	0.10	—	µA-sec	C
QPA_{r512}	Pressure or accelerometer charge consumption; Raw 512 µs settling per sample	V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max	—	0.95	—	µA-sec	C
QPA_{r2048}	Pressure or accelerometer charge consumption; Raw 2048 µs settling per sample	V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max	—	1.85	—	µA-sec	C
QP_{c3}	Pressure charge consumption; Compensation third order per sample	V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max	—	1.77	—	µA-sec	D
QA_{c2}	Accelerometer charge consumption; Compensation second order per sample	V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max	—	1.95	—	µA-sec	D
QVT_{r50}	Voltage or temperature charge consumption; Raw 50 µs conversion per sample	V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max	—	0.2	—	µA-sec	C
QVT_{c250}	Voltage or temperature charge consumption; Compensation ~0.25 ms per sample	V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max	—	0.50	—	µA-sec	D

6.4 Clocks and thresholds

Table 8. Clocks and thresholds

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
f_{BUS}	MCU bus frequency multiple of HFO	$V_{DD} > V_{LVDRF}$	—	0.5	—	x HFO	D
f_{HF0}	High frequency oscillator, multiple of MFO	$V_{DD} > V_{LVDRF}$	—	64	—	x MFO	D
t_{HFOST}	Stabilization time	—	—	300	1000	µs	D
f_{MFO}	Medium frequency oscillator	$V_{DD} > V_{LVDRF}$	107	125	135	kHz	A
f_{LFO}	Low frequency oscillator	—	504	—	1512	Hz	B
f_{LFRO}	LFR Clock (derived from LFRO)	—	120	129	139	kHz	B
t_{STOP1}	MCU wake-up time	From Stop1 to 1st instruction, 4 MHz	—	50	70	µs	C
t_{STOP4}	MCU wake-up time	From Stop4 to 1st instruction, 4 MHz	—	25	35	µs	C
t_{LV}	Low voltage times	$V_{DD} < V_{LVx}$	—	—	10	µs	D
V_{LVWLF}	Low voltage warning (LVW)	Lower threshold, V_{DD} falling	1.95	—	2.2	V	C
V_{LVWLR}	Low voltage warning (LVW)	Lower threshold, V_{DD} rising	2.02	—	2.1	V	C
V_{LVWHF}	Low voltage warning (LVW)	Higher threshold, V_{DD} falling	2.28	—	2.54	V	C
V_{LVWHR}	Low voltage warning (LVW)	Higher threshold, V_{DD} rising	2.34	—	2.61	V	C
V_{LVDLF}	Low voltage detection (LVD)	Lower threshold, V_{DD} falling	1.79	—	1.96	V	C
V_{LVDLR}	Low voltage detection (LVD)	Lower threshold, V_{DD} rising	1.87	—	2.03	V	C

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Table 8. Clocks and thresholds*...continued*

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
V_{LVDHF}	Low voltage detection (LVD)	Higher threshold, V_{DD} falling	1.95	—	2.2	V	C
V_{LVDHR}	Low voltage detection (LVD)	Higher threshold, V_{DD} rising	2.02	—	2.1	V	C
V_{LVDRF}	RF LVD	V_{DD} falling	1.6	—	2.1	V	C
T_{FDR}	Flash memory data retention	—	10	—	—	Yr	D

6.5 Power-on reset operation

When power is initially applied to the device, or when the supply voltage drops below the V_{POR} level, the POR circuit causes a reset condition. As the supply voltage rises, the LVD circuit holds the chip in reset until the supply has risen above the level determined by LVDV bit. Both the POR bit and the LVD bit in SRS are set following a POR.

Table 9. Power-on reset

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
t_R	Power on reset (POR)	V_{DD} risetime to avoid latch up	—	—	1	s	C
t_{POR}	Power on reset (POR)	Time for V_{DD} < 0.5 V to assure POR	70	—	—	µs	C
V_{PORR}	Power on reset (POR)	Rising voltage to release reset	—	—	2.1	V	C
V_{PORA}	Power on reset (POR)	Falling voltage to assert reset	0.8	—	—	V	C

6.6 GPIO port pins

Table 10. GPIO port pins

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
V_{OH}	Output high voltage	I_{LOAD} = 5 mA	V_{DD} – 0.35	—	—	V	D
V_{OL}	Output low voltage	I_{LOAD} = 5 mA	—	—	V_{SS} + 0.35	V	D
V_{IHn}	Input high voltage	2.3 V ≤ V_{DD} ≤ V_H, T_A = T_L, T_H	0.7 × V_{DD} / V_{DDA}	—	V_{DD} / V_{DDA}	V	D
V_{IHlv}	Input high voltage	V_{DD} ≤ 2.3 V, T_A = 25 °C	0.85 × V_{DD} / V_{DDA}	—	V_{DD} / V_{DDA}	V	D
V_{ILn}	Input low voltage	2.3 V ≤ V_{DD} ≤ V_H, T_A = T_L, T_H	V_{SS}	—	0.35 × V_{DD} / V_{DDA}	V	D
V_{ILlv}	Input low voltage	V_{DD} ≤ 2.3 V, T_A = 25 °C	V_{SS}	—	0.28 × V_{DD} / V_{DDA}	V	D
I_{IH}	Input high current, PTA0:3	Pulldown disabled; V_{IH} Min	–1	—	+1	µA	D
I_{IHp}	Input high current, PTA0:3	Pulldown enabled; V_{IH} Min	0	—	120	µA	D
I_{IL}	Input low current, PTA0:3	Pullup disabled; V_{IL} Max	–1	—	+1	µA	D
I_{ILp}	Input low current, PTA0:3	Pullup enabled; V_{IL} Max	–120	—	0	µA	D
$I_{IH\text{-}IL}$	Input current PTA4 only	V_{IH} Min and V_{IL} Max	–120	—	120	µA	D

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Table 10. GPIO port pins...*continued*

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
C_{IO}	Pin capacitance	V_{DD} = 3.0 V	0	—	15	pF	D
C_{MISO}	MISO load capacitance	V_{DD} = 3.0 V	—	—	50	pF	D

6.7 SPI timing characteristics

Table 11. SPI timing

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
t_{SSMIN}	SS_B asserted period	—	1	—	—	f_{BUS} period	D
t_{ACCESS}	SS_B low to MISO	—	—	—	50	ns	D
t_{LEAD}	SS_B low to SCLK start	—	50	—	—	ns	D
t_{SETUP}	MOSI to SCLK start	—	20	—	—	ns	D
t_{SCLK}	SCLK period	—	100	—	—	ns	D
t_{SCLKH}	SCLK high portion	—	35	—	—	ns	D
t_{SCLKL}	SCLK low portion	—	35	—	—	ns	D
t_{SCLKR}	SCLK risetime	—	—	10	25	ns	D
t_{SCLKF}	SCLK fall time	—	—	10	25	ns	D
t_{VALID}	MISO valid transition time	—	—	—	30	ns	D
t_{HOLD_IN}	MOSI hold time	—	10	—	—	ns	D
t_{HOLD_OUT}	SCLK high to MISO transition start	—	0	—	—	ns	D
t_{LAG}	Final SCLK low to SS_B high	—	60	—	—	ns	D
$t_{DISABLE}$	SS_B high to MISO 3-state	—	—	—	60	ns	D
t_{SS_REJ}	SS_B noise rejection period	—	—	—	5	ns	D
t_{SSCLK}	SS_B high to SCLK high	—	50	—	—	ns	D
t_{CLKSS}	SCLK high to SCLK low	—	50	—	—	ns	D
t_{SSN}	SS_B not asserted period	—	6	—	—	f_{BUS} period	D
$t_{LEAD\text{-}WU}$	Wake-up by SS_B low to SCLK start	—	1	—	—	ms	D
t_{SPI_EN}	SPI enable by SS_B low after V_{DD} > V_{PORR}	—	200	—	—	µs	D

6.8 Temperature measurement characteristics

Table 12. Temperature measurement

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.

Transfer function: T °C = (1 °C / LSB × T_{CODE}) – 55 °C

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
$DT_{MAX\text{-}MIN}$	Sensitivity	—	0.93	1	1.08	°C / LSB	C
T_{ERROR}	Error	—	—	0	—	LSB	C
T_{UNDER}	Underflow	—	—	1	—	LSB	C

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Table 12. Temperature measurement...*continued*

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer function: T °C = (1 °C / LSB × T_{CODE}) – 55 °C

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
T_{OVER}	Overflow	—	—	255	—	LSB	C
T_{MIN}	Temperature measurement	T_A = –50 °C	—	5	—	LSB	D
$T_{RATE-MIN}$	Temperature measurement	T_A = –40 °C	11	15	19	LSB	C
T_{CODE}	Temperature measurement	T_A = –20 °C	32	35	38	LSB	A
T_{CODE}	Temperature measurement	T_A = 0 °C	52	55	58	LSB	C
T_{CODE}	Temperature measurement	T_A = 25 °C	77	80	83	LSB	B
T_{CODE}	Temperature measurement	T_A = 70 °C	122	125	128	LSB	C
T_{CODE}	Temperature measurement	T_A = 85 °C	137	140	143	LSB	A
T_{CODE}	Temperature measurement	T_A = 105 °C	156	160	164	LSB	C
$T_{RATE-MAX}$	Temperature measurement	T_A = 125 °C	175	180	185	LSB	B
T_{MAX}	Temperature measurement	T_A = 150 °C [1]	—	205	—	LSB	D
T_{STAB}	Temperature measurement stability range	—	–3	—	+3	LSB	C

[1] Temperature excursions, time at T_{MAX} must not exceed 12 events of 15 minutes duration during the product lifetime.

6.9 Voltage measurement characteristics

Table 13. Voltage measurement characteristics

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer function: V = (0.01 V / LSB × V_{CODE}) + 1.22 V
Interpolated limits between –40 °C to 0 °C and between 50 °C to 125 °C.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
$DV_{MAX-MIN}$	Sensitivity	—	9	10	12	mV / LSB	C
V_{ERROR}	Error	—	—	0	—	LSB	C
V_{UNDER}	Underflow	—	—	1	—	LSB	C
V_{OVER}	Overflow	—	—	255	—	LSB	C
V_{CODE}	V_{DD} voltage, 2.8 V	0 °C ≤ T_A ≤ 50 °C, V_{DD} = 2.8 V	153	158	163	LSB	C
V_{CODE}	V_{DD} voltage, 3.0 V	0 °C ≤ T_A ≤ 50 °C, V_{DD} = 3.0 V	173	178	183	LSB	C
V_{CODE}	V_{DD} voltage, 3.3 V	0 °C ≤ T_A ≤ 50 °C, V_{DD} = 3.3 V	203	208	213	LSB	C
V_{MIN}	V_{DD} voltage, 1.8 V	—	38	58	78	LSB	C
V_{CODE}	V_{DD} voltage, 2.1 V	—	68	88	108	LSB	B
V_{CODE}	V_{DD} voltage, 2.3 V	–40 °C ≤ T_A ≤ 0 °C or 50 °C ≤ T_A ≤ 125 °C, V_{DD} = 2.3 V	98	108	118	LSB	C
V_{CODE}	V_{DD} voltage, 2.8 V	–40 °C ≤ T_A ≤ 0 °C or 50 °C ≤ T_A ≤ 125 °C, V_{DD} = 2.8 V	148	158	168	LSB	C
V_{CODE}	V_{DD} voltage, 3.0 V	–40 °C ≤ T_A ≤ 0 °C or 50 °C ≤ T_A ≤ 125 °C, V_{DD} = 3.0 V	168	178	188	LSB	B
V_{CODE}	V_{DD} voltage, 3.3 V	–40 °C ≤ T_A ≤ 0 °C or 50 °C ≤ T_A ≤ 125 °C, V_{DD} = 3.3 V	198	208	218	LSB	C
V_{MAX}	V_{DD} voltage, 3.6 V	—	228	238	248	LSB	C
V_{STAB}	Voltage measurement stability range	—	–3	—	+3	LSB	C

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Table 14. External pin voltage measurement

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer function: V = (V_{DD} V / LSB × GxCODE) / 1023, where x = 0 for PTB0, 1 for PTB1

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
ΔGxMAX-MIN	Sensitivity	—	—	V_{DD} / 1023	—	V / LSB	C
GxERROR	Error	Status = $01	—	0	—	LSB	C
GxCODE	Voltage measurement, V = 0 V	Status = $00	—	0	—	LSB	C
GxCODE	Voltage measurement, V = VDD V	—	—	1023	—	LSB	C
GxSTAB	Voltage measurement stability range	—	–1	—	+1	LSB	C

6.10 Pressure measurement characteristics

Unless otherwise noted, stated tolerances are valid only with Initial Sample Delay [ISD3:0] set for > 2.5 ms and MCU placed in STOP4 mode.

6.10.1 Pressure measurement characteristic (90 kPa to 1110 kPa) range

Table 15. Pressure measurement characteristics (90 kPa to 1110 kPa) range

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer function: P kPa = (1.0 kPa / LSB × P_{CODE}) + 88.0 kPa
Interpolated limits between 105 °C and 125 °C.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
$\Delta P_{MAX-Min}$	Sensitivity	—	0.98	1.0	1.02	kPa/ LSB	C
P_{ERROR}	Error	—	—	0	—	LSB	C
P_{UNDER}	Underflow	FW error status bit 0 = 1	—	1	—	LSB	C
P_{OVER}	Overflow	FW error status bit 0 = 1	—	1023	—	LSB	C
P_{MIN}	Proof pressure, 90 kPa	–40 ° C ≤ T_A ≤ 105 ° C	—	2	14	LSB	D
P_{CODE}	Proof pressure, 100 kPa	–40 ° C ≤ T_A ≤ 105 ° C	7	12	17	LSB	A
P_{CODE}	Proof pressure, 260 kPa	–40 ° C ≤ T_A ≤ 105 ° C	167	172	177	LSB	C
P_{CODE}	Proof pressure, 300 kPa	–40 ° C ≤ T_A ≤ 105 ° C	207	212	217	LSB	C
P_{CODE}	Proof pressure, 430 kPa	–40 ° C ≤ T_A ≤ 105 ° C	337	342	347	LSB	C
P_{CODE}	Proof pressure, 600 kPa	–40 ° C ≤ T_A ≤ 105 ° C	507	512	517	LSB	C
P_{CODE}	Proof pressure, 770 kPa	–40 ° C ≤ T_A ≤ 105 ° C	677	682	687	LSB	C
P_{CODE}	Proof pressure, 800 kPa	–40 ° C ≤ T_A ≤ 105 ° C	707	712	717	LSB	A
P_{CODE}	Proof pressure, 940 kPa	–40 ° C ≤ T_A ≤ 105 ° C	847	852	857	LSB	C
P_{CODE}	Proof pressure, 1050 kPa	–40 ° C ≤ T_A ≤ 105 ° C	957	962	967	LSB	A
P_{MAX}	Proof pressure, 1110 kPa	–40 ° C ≤ T_A ≤ 105 ° C	1017	1022	—	LSB	D
P_{MIN}	Proof pressure, 90 kPa	T_A = 125 °C	—	2	14	LSB	D
P_{CODE}	Proof pressure, 100 kPa	T_A = 125 °C	1	12	23	LSB	A
P_{CODE}	Proof pressure, 260 kPa	T_A = 125 °C	161	172	183	LSB	C
P_{CODE}	Proof pressure, 300 kPa	T_A = 125 °C	201	212	223	LSB	C
P_{CODE}	Proof pressure, 430 kPa	T_A = 125 °C	331	342	353	LSB	C
P_{CODE}	Proof pressure, 600 kPa	T_A = 125 °C	501	512	523	LSB	C
P_{CODE}	Proof pressure, 770 kPa	T_A = 125 °C	671	682	693	LSB	C

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Table 15. Pressure measurement characteristics (90 kPa to 1110 kPa) range*...continued*

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer function: P kPa = (1.0 kPa / LSB × P_{CODE}) + 88.0 kPa
Interpolated limits between 105 °C and 125 °C.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
P_{CODE}	Proof pressure, 800 kPa	T_A = 125 °C	701	712	723	LSB	A
P_{CODE}	Proof pressure, 940 kPa	T_A = 125 °C	841	852	863	LSB	C
P_{CODE}	Proof pressure, 1050 kPa	T_A = 125 °C	951	962	973	LSB	A
P_{MAX}	Proof pressure, 1110 kPa	T_A = 125 °C	1011	1022	—	LSB	D
P_{DRIFT}	Pressure long-term drift[1]	–40 °C ≤ TA ≤ 105 °C	–8	—	+8	LSB	C

[1] The long-term drift is visible under the test conditions defined by AEC-Q103, and using maximum pressures. Drift is the change of tolerance over the device lifetime. This long-term drift is not additive to the current tolerances, but is the total tolerance.

6.11 Acceleration measurement characteristics

Unless otherwise noted, stated tolerances are valid only with Initial Sample Delay [ISD3:0] set for > 2.5 ms and MCU placed in STOP4 mode.

6.11.1 Acceleration measurement characteristics (–80 g to +90 g) range option

Table 16. Acceleration measurement characteristic (–80 g to +90 g) range option

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer Function: Offset Step 7 A g's = (0.020 g/LSB × A_{CODE}) – 10.039 g
Interpolated limits between –40 °C to –20 °C and between 85 °C to 125 °C

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
$DA_{MAX-MIN}$	Sensitivity	—	0.014	0.020	0.034	g / LSB	C
A_{ERROR}	Error	—	—	0	—	LSB	C
A_{UNDER}	Underflow	FW error status bit 0 = 1	—	1	—	LSB	C
A_{OVER}	Overflow	FW error status bit 0 = 1	—	1023	—	LSB	C
A_{MIN0}	Acceleration measurement, –80 g, Offset step 0	–20 °C ≤ T_A ≤ 85 °C	—	2	—	LSB	D
A_{CODE0}	Acceleration measurement, –75 g, Offset Step 0	–20 °C ≤ T_A ≤ 85 °C	—	257	—	LSB	D
A_{CODE0}	Acceleration measurement, –70 g, Offset Step 0	–20 °C ≤ T_A ≤ 85 °C	—	512	—	LSB	D
A_{CODE0}	Acceleration measurement, –65 g, Offset Step 0	–20 °C ≤ T_A ≤ 85 °C	—	767	—	LSB	D
A_{MAX0}	Acceleration measurement, –60 g, Offset Step 0	–20 °C ≤ T_A ≤ 85 °C	—	1022	—	LSB	D
A_{MIN7}	Acceleration measurement, –10 g, Offset Step 7	–20 °C ≤ T_A ≤ 85 °C	—	2	180	LSB	D
A_{CODE7}	Acceleration measurement, –5 g, Offset Step 7	–20 °C ≤ T_A ≤ 85 °C	104	257	410	LSB	D
A_{CODE7}	Acceleration measurement, 0 g, Offset Step 7	–20 °C ≤ T_A ≤ 85 °C	384	512	640	LSB	A
A_{CODE7}	Acceleration measurement, 5 g, Offset Step 7	–20 °C ≤ T_A ≤ 85 °C	614	767	920	LSB	D

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Table 16. Acceleration measurement characteristic (–80 g to +90 g) range option*...continued*

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer Function: Offset Step 7 A g's = (0.020 g/LSB × A_{CODE}) – 10.039 g
Interpolated limits between –40 °C to –20 °C and between 85 °C to 125 °C

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
A_{MAX7}	Acceleration measurement, 10 g, Offset Step 7	–20 °C ≤ T_A ≤ 85 °C	844	1022	—	LSB	D
A_{MIN7}	Acceleration measurement, –10 g, Offset Step 7	T_A = –40 °C and 125 °C	—	2	216	LSB	D
A_{CODE7}	Acceleration measurement, –5 g, Offset Step 7	T_A = –40 °C and 125 °C	73	257	441	LSB	D
A_{CODE7}	Acceleration measurement, 0 g, Offset Step 7	T_A = –40 °C and 125 °C	359	512	665	LSB	D
A_{CODE7}	Acceleration measurement, 5 g, Offset Step 7	T_A = –40 °C and 125 °C	583	767	951	LSB	D
A_{MAX7}	Acceleration measurement, 10 g, Offset Step 7	T_A = –40 °C and 125 °C	808	1022	—	LSB	D
A_{MIN15}	Acceleration measurement, 70 g, Offset Step 15	–20 °C ≤ T_A ≤ 85 °C	—	2	—	LSB	D
A_{CODE15}	Acceleration measurement, 75 g, Offset Step 15	–20 °C ≤ T_A ≤ 85 °C	—	257	—	LSB	D
A_{CODE15}	Acceleration measurement, 80 g, Offset Step 15	–20 °C ≤ T_A ≤ 85 °C	—	512	—	LSB	D
A_{CODE15}	Acceleration measurement, 85 g, Offset Step 15	–20 °C ≤ T_A ≤ 85 °C	—	767	—	LSB	D
A_{MAX15}	Acceleration measurement, 90 g, Offset Step 15	–20 °C ≤ T_A ≤ 85 °C	—	1022	—	LSB	D
A_{STAB}	Acceleration measurement stability range	—	–5	—	+5	LSB	C

6.11.2 Acceleration measurement characteristic (–360 g to +400 g) range option

Table 17. Acceleration measurement characteristic (–360 g to +400 g) range option

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer Function: Offset Step 7 A g's = (0.088 g/LSB × A_{CODE}) – 45.176 g
Interpolated limits between –40 °C to –20 °C and between 85 °C to 125 °C

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
$DdrA_{MAX-MIN}$	Sensitivity	—	0.074	0.088	0.108	g / LSB	C
A_{ERROR}	Error	—	—	0	—	LSB	C
A_{UNDER}	Underflow	FW error status bit 0 = 1	—	1	—	LSB	C
A_{OVER}	Overflow	FW error status bit 0 = 1	—	1023	—	LSB	C
A_{MIN0}	Acceleration measurement, –360 g, Offset step 0	–20 °C ≤ T_A ≤ 85 °C	—	2	—	LSB	D
A_{CODE0}	Acceleration measurement, –338 g, Offset step 0	–20 °C ≤ T_A ≤ 85 °C	—	257	—	LSB	D
A_{CODE0}	Acceleration measurement, –315 g, Offset step 0	–20 °C ≤ T_A ≤ 85 °C	—	512	—	LSB	D
A_{CODE0}	Acceleration measurement, –293 g, Offset step 0	–20 °C ≤ T_A ≤ 85 °C	—	767	—	LSB	D

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Table 17. Acceleration measurement characteristic (–360 g to +400 g) range option*...continued*

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer Function: Offset Step 7 A g's = (0.088 g/LSB × A_{CODE}) – 45.176 g
Interpolated limits between –40 °C to –20 °C and between 85 °C to 125 °C

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
A_{MAX0}	Acceleration measurement, –270 g, Offset step 0	–20 °C ≤ T_A ≤ 85 °C	—	1022	—	LSB	D
A_{MIN7}	Acceleration measurement, –45 g, Offset step 7	–20 °C ≤ T_A ≤ 85 °C	—	2	81	LSB	D
A_{CODE7}	Acceleration measurement, –22.5 g, Offset step 7	–20 °C ≤ T_A ≤ 85 °C	203	257	311	LSB	D
A_{CODE7}	Acceleration measurement, 0 g, Offset step 7	–20 °C ≤ T_A ≤ 85 °C	483	512	541	LSB	A
A_{CODE7}	Acceleration measurement, 22.5 g, Offset step 7	–20 °C ≤ T_A ≤ 85 °C	713	767	821	LSB	D
A_{MAX7}	Acceleration measurement, 45 g, Offset step 7	–20 °C ≤ T_A ≤ 85 °C	943	1022	—	LSB	D
A_{MIN7}	Acceleration measurement, –45 g, Offset step 7	T_A = –40 °C and 125 °C	—	2	97	LSB	D
A_{CODE7}	Acceleration measurement, –22.5 g, Offset step 7	T_A = –40 °C and 125 °C	192	257	322	LSB	D
A_{CODE7}	Acceleration measurement, 0 g, Offset step 7	T_A = –40 °C and 125 °C	478	512	546	LSB	D
A_{CODE7}	Acceleration measurement, 22.5 g, Offset step 7	T_A = –40 °C and 125 °C	702	767	832	LSB	D
A_{MAX7}	Acceleration measurement, 45 g, Offset step 7	T_A = –40 °C and 125 °C	927	1022	—	LSB	D
A_{MIN15}	Acceleration measurement, 315 g, Offset Step 15	–20 °C ≤ T_A ≤ 85 °C	—	2	—	LSB	D
A_{CODE15}	Acceleration measurement, 338 g, Offset Step 15	–20 °C ≤ T_A ≤ 85 °C	—	257	—	LSB	D
A_{CODE15}	Acceleration measurement, 360 g, Offset Step 15	–20 °C ≤ T_A ≤ 85 °C	—	512	—	LSB	D
A_{CODE15}	Acceleration measurement, 383 g, Offset Step 15	–20 °C ≤ T_A ≤ 85 °C	—	767	—	LSB	D
A_{MAX15}	Acceleration measurement, 405 g, Offset Step 15	–20 °C ≤ T_A ≤ 85 °C	—	1022	—	LSB	D
A_{STAB}	Acceleration measurement stability range	—	–4	—	+4	LSB	C

6.11.3 Acceleration measurement characteristic (–175 g to +550 g) range option

Table 18. Acceleration measurement characteristic (–175 g to +550 g) range option

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer Function: Offset Step 7 A g's = (0.343 g/LSB × A_{CODE}) – 175.686 g
Interpolated limits between –40 °C to –20 °C and between 85 °C to 125 °C
Due to the inverted polarity calibration where the offset steps are in reverse order, the standard library function TPMS_READ_DYNAMIC_ACCEL is not compatible with this range option.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
$\Delta A_{MAX-MIN}$	Sensitivity		0.302	0.343	0.398	g / LSB	C

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Table 18. Acceleration measurement characteristic (–175 g to +550 g) range option*...continued*

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer Function: Offset Step 7 A g's = (0.343 g/LSB × A_{CODE}) – 175.686 g
Interpolated limits between –40 °C to –20 °C and between 85 °C to 125 °C
Due to the inverted polarity calibration where the offset steps are in reverse order, the standard library function TPMS_READ_DYNAMIC_ACCEL is not compatible with this range option.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
A_{ERROR}	Error			0		LSB	C
A_{UNDER}	Underflow	FW error status bit 0 = 1		1		LSB	C
A_{OVER}	Overflow	FW error status bit 0 = 1		1023		LSB	C
$A_{MIN}4$	Acceleration measurement, 200 g, Offset step 4	-20 °C ≤ TA ≤ 85 °C	—	2	—	LSB	D
$A_{CODE}4$	Acceleration measurement, 288 g, Offset step 4	-20 °C ≤ TA ≤ 85 °C	—	257	—	LSB	D
$A_{CODE}4$	Acceleration measurement, 375 g, Offset step 4	-20 °C ≤ TA ≤ 85 °C	—	512	—	LSB	D
$A_{CODE}4$	Acceleration measurement, 463 g, Offset step 4	-20 °C ≤ TA ≤ 85 °C	—	767	—	LSB	D
$A_{MAX}4$	Acceleration measurement, 550 g, Offset step 4	-20 °C ≤ TA ≤ 85 °C	—	1022	—	LSB	D
$A_{MIN}5$	Acceleration measurement, 75 g, Offset step 5	-20 °C ≤ TA ≤ 85 °C	—	2	—	LSB	D
$A_{CODE}5$	Acceleration measurement, 163 g, Offset step 5	-20 °C ≤ TA ≤ 85 °C	—	257	—	LSB	D
$A_{CODE}5$	Acceleration measurement, 250 g, Offset step 5	-20 °C ≤ TA ≤ 85 °C	—	512	—	LSB	D
$A_{CODE}5$	Acceleration measurement, 338 g, Offset step 5	-20 °C ≤ TA ≤ 85 °C	—	767	—	LSB	D
$A_{MAX}5$	Acceleration measurement, 425 g, Offset step 5	-20 °C ≤ TA ≤ 85 °C	—	1022	—	LSB	D
$A_{MIN}6$	Acceleration measurement, -50 g, Offset step 6	-20 °C ≤ TA ≤ 85 °C	—	2	—	LSB	D
$A_{CODE}6$	Acceleration measurement, 38 g, Offset step 6	-20 °C ≤ TA ≤ 85 °C	—	257	—	LSB	D
ACODE6	Acceleration measurement, 125 g, Offset step 6	-20 °C ≤ TA ≤ 85 °C	—	512	—	LSB	D
$A_{CODE}6$	Acceleration measurement, 213 g, Offset step 6	-20 °C ≤ TA ≤ 85 °C	—	767	—	LSB	D
$A_{MAX}6$	Acceleration measurement, 300 g, Offset step 6	-20 °C ≤ TA ≤ 85 °C	—	1022	—	LSB	D
A_{MIN} 7	Acceleration measurement, –175 g, Offset step 7	-20 °C ≤ TA ≤ 85 °C	—	2	60	LSB	D
A_{CODE} 7	Acceleration measurement, –88 g, Offset step 7	-20 °C ≤ TA ≤ 85 °C	224	257	290	LSB	D
A_{CODE} 7	Acceleration measurement, 0 g, Offset step 7	-20 °C ≤ TA ≤ 85 °C	504	512	520	LSB	A
A_{CODE} 7	Acceleration measurement, 88 g, Offset step 7	-20 °C ≤ TA ≤ 85 °C	734	767	800	LSB	D
A_{MAX} 7	Acceleration measurement, 175 g, Offset step 7	-20 °C ≤ TA ≤ 85 °C	964	1022	—	LSB	D

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Table 18. Acceleration measurement characteristic (–175 g to +550 g) range option*...continued*

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer Function: Offset Step 7 A g's = (0.343 g/LSB × A_{CODE}) – 175.686 g
Interpolated limits between –40 °C to –20 °C and between 85 °C to 125 °C
Due to the inverted polarity calibration where the offset steps are in reverse order, the standard library function TPMS_READ_DYNAMIC_ACCEL is not compatible with this range option.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
A_{MIN} 7	Acceleration measurement, –175 g, Offset step 7	TA = -40 °C & 125 °C	—	2	72	LSB	D
A_{CODE} 7	Acceleration measurement, –88 g, Offset step 7	TA = -40 °C & 125 °C	218	257	296	LSB	D
A_{CODE} 7	Acceleration measurement, 0 g, Offset step 7	TA = -40 °C & 125 °C	503	512	525	LSB	D
A_{CODE} 7	Acceleration measurement, 88 g, Offset step 7	TA = -40 °C & 125 °C	728	767	806	LSB	D
A_{MAX} 7	Acceleration measurement, 175 g, Offset step 7	TA = -40 °C & 125 °C	952	1022	—	LSB	D
A_{MIN} 8	Acceleration measurement, –300 g, Offset step 8	-20 °C ≤ TA ≤ 85 °C	—	2	—	LSB	D
A_{CODE} 8	Acceleration measurement, –213 g, Offset step 8	-20 °C ≤ TA ≤ 85 °C	—	257	—	LSB	D
A_{CODE} 8	Acceleration measurement, –125 g, Offset step 8	-20 °C ≤ TA ≤ 85 °C	—	512	—	LSB	D
A_{CODE} 8	Acceleration measurement, –38 g, Offset step 8	-20 °C ≤ TA ≤ 85 °C	—	767	—	LSB	D
A_{MAX} 8	Acceleration measurement, 50 g, Offset step 8	-20 °C ≤ TA ≤ 85 °C	—	1022	—	LSB	D
A_{MIN} 9	Acceleration measurement, –425 g, Offset step 9	-20 °C ≤ TA ≤ 85 °C	—	2	—	LSB	D
A_{CODE} 9	Acceleration measurement, –338 g, Offset step 9	-20 °C ≤ TA ≤ 85 °C	—	257	—	LSB	D
A_{CODE} 9	Acceleration measurement, –250 g, Offset step 9	-20 °C ≤ TA ≤ 85 °C	—	512	—	LSB	D
A_{CODE} 9	Acceleration measurement, –163 g, Offset step 9	-20 °C ≤ TA ≤ 85 °C	—	767	—	LSB	D
A_{MAX} 9	Acceleration measurement, –75 g, Offset step 9	-20 °C ≤ TA ≤ 85 °C	—	1022	—	LSB	D
A_{MIN} 10	Acceleration measurement, –550 g, Offset step 10	-20 °C ≤ TA ≤ 85 °C	—	2	—	LSB	D
A_{CODE} 10	Acceleration measurement, –463 g, Offset step 10	-20 °C ≤ TA ≤ 85 °C	—	257	—	LSB	D
A_{CODE} 10	Acceleration measurement, –375 g, Offset step 10	-20 °C ≤ TA ≤ 85 °C	—	512	—	LSB	D
A_{CODE} 10	Acceleration measurement, –288 g, Offset step 10	-20 °C ≤ TA ≤ 85 °C	—	767	—	LSB	D
A_{MAX} 10	Acceleration measurement, –200 g, Offset step 10	-20 °C ≤ TA ≤ 85 °C	—	1022	—	LSB	D
A_{STAB}	Acceleration measurement stability range		–4		+4	LSB	C

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6.11.4 Acceleration measurement characteristic (–400 g to +400 g) range option

Table 19. Acceleration measurement characteristic (–400 g to +400 g) range option

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer Function: Offset Step 7 A g's = (0.294 g/LSB × A_{CODE}) – 150.59 g
Interpolated limits between –40 °C to –20 °C and between 85 °C to 125 °C

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
$\Delta A_{MAX-MIN}$	Sensitivity		0.260	0.294	0.342	g / LSB	C
A_{ERROR}	Error			0		LSB	C
A_{UNDER}	Underflow	FW error status bit 0 = 1		1		LSB	C
A_{OVER}	Overflow	FW error status bit 0 = 1		1023		LSB	C
A_{MIN} 6	Acceleration measurement, –400 g, Offset step 6	-20 °C ≤ TA ≤ 85 °C	—	2	—	LSB	D
A_{CODE} 6	Acceleration measurement, –325 g, Offset step 6	-20 °C ≤ TA ≤ 85 °C	—	257	—	LSB	D
A_{CODE} 6	Acceleration measurement, –250 g, Offset step 6	-20 °C ≤ TA ≤ 85 °C	—	512	—	LSB	D
A_{CODE} 6	Acceleration measurement, –175 g, Offset step 6	-20 °C ≤ TA ≤ 85 °C	—	767	—	LSB	D
A_{MAX} 6	Acceleration measurement, –100 g, Offset step 6	-20 °C ≤ TA ≤ 85 °C	—	1022	—	LSB	D
A_{MIN} 7	Acceleration measurement, –150 g, Offset step 7	-20 °C ≤ TA ≤ 85 °C	—	2	61	LSB	D
A_{CODE} 7	Acceleration measurement, –75 g, Offset step 7	-20 °C ≤ TA ≤ 85 °C	223	257	291	LSB	D
A_{CODE} 7	Acceleration measurement, 0 g, Offset step 7	-20 °C ≤ TA ≤ 85 °C	503	512	521	LSB	A
A_{CODE} 7	Acceleration measurement, 75 g, Offset step 7	-20 °C ≤ TA ≤ 85 °C	733	767	801	LSB	D
A_{MAX} 7	Acceleration measurement, 150 g, Offset step 7	-20 °C ≤ TA ≤ 85 °C	963	1022	—	LSB	D
A_{MIN} 7	Acceleration measurement, –150 g, Offset step 7	TA = -40 °C & 125 °C	—	2	73	LSB	D
A_{CODE} 7	Acceleration measurement, –75 g, Offset step 7	TA = -40 °C & 125 °C	216	257	298	LSB	D
A_{CODE} 7	Acceleration measurement, 0 g, Offset step 7	TA = -40 °C & 125 °C	501	512	523	LSB	D
A_{CODE} 7	Acceleration measurement, 75 g, Offset step 7	TA = -40 °C & 125 °C	726	767	808	LSB	D
A_{MAX} 7	Acceleration measurement, 150 g, Offset step 7	TA = -40 °C & 125 °C	951	1022	—	LSB	D
A_{MIN} 8	Acceleration measurement, 100 g, Offset step 8	-20 °C ≤ TA ≤ 85 °C	—	2	—	LSB	D
A_{CODE} 8	Acceleration measurement, 175 g, Offset step 8	-20 °C ≤ TA ≤ 85 °C	—	257	—	LSB	D
A_{CODE} 8	Acceleration measurement, 250 g, Offset step 8	-20 °C ≤ TA ≤ 85 °C	—	512	—	LSB	D
A_{CODE} 8	Acceleration measurement, 325 g, Offset step 8	-20 °C ≤ TA ≤ 85 °C	—	767	—	LSB	D

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Table 19. Acceleration measurement characteristic (–400 g to +400 g) range option*...continued*

V_{DDM} Min ≤ V_{DD} ≤ V_{DDM} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
Transfer Function: Offset Step 7 A g's = (0.294 g/LSB × A_{CODE}) – 150.59 g
Interpolated limits between –40 °C to –20 °C and between 85 °C to 125 °C

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
A_{MAX} 8	Acceleration measurement, 400 g, Offset step 8	-20 °C ≤ TA ≤ 85 °C	—	1022	—	LSB	D
A_{STAB}	Acceleration measurement stability range		–5		+5	LSB	C

6.12 Low frequency receiver characteristics

Table 20. LFR characteristics

V_{DDF} Min ≤ V_{DD} ≤ V_{DDF} Max, T_{AF} Min ≤ T_A ≤ T_{AF} Max, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
R_{LFDF}	LFA / LFB load resistance	—	0.8	—	4	MΩ	D
DR_{LFIN}	Dynamic range, f_C at BW_{ACC}	Data mode, always detect	56	—	—	dB	D
$V_{IN\text{-}AD\text{-}H}$	Sensitivity, high - carrier and data modes	Always detect	—	—	3.0	mVPP	B
$V_{IN\text{-}ND\text{-}H}$	Sensitivity, high - carrier and data modes	Never detect	0.25	—	—	mVPP	B
$V_{IN\text{-}AD\text{-}L}$	Sensitivity, low - carrier and data modes	Always detect	—	—	12.0	mVPP	B
$V_{IN\text{-}ND\text{-}L}$	Sensitivity, low - carrier and data modes	Never detect	4.0	—	—	mVPP	B
MD	Modulation depth	—	70	—	100	%	C
BRLF	Baud rate	—	3788	3906	4032	Bit/s	C
DCM	Manchester duty cycle tolerance	—	—	40 / 60	45 / 55	%	C
DCN	NRZ duty cycle tolerance	—	—	50 / 50	45 / 55	%	C
MER	Message error rate	—	—	5	—	%	C
BW_{ACC}	Bandwidth	Always detect	≥ 88	—	≤ 175	kHz	C
BW_{REJ}	Bandwidth	Never detect	< 88	—	> 175	kHz	C
t_{LF}	Signal rise / decay time constant, carrier envelope	—	15.3	—	—	µs	D

6.13 Radio frequency transmitter characteristics

Table 21. Radio frequency transmitter characteristics

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
All conditions characterized with NDK NX2016SA 26.000 MHz crystal.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
PRF3	Nominal output power with 50 Ω matching network[1]	315 MHz, 25 °C, 3.0 V PWR[4:0] = 0 1 1 0 0	—	5	—	dBm	C
PRF4	Nominal output power with 50 Ω matching network[1]	434 MHz, 25 °C, 3.0 V PWR[4:0] = 0 1 1 1 0	—	5	—	dBm	C
PRF	Output power, range	—	–1.5	—	8	dBm	C

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Table 21. Radio frequency transmitter characteristics...*continued*

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
All conditions characterized with NDK NX2016SA 26.000 MHz crystal.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
PRFSTEP	Output power, step size	—	—	0.5	—	dBm	C
PRFMINp	Output power, minimum PRF vs. T_A and V_{DD} under control of FW TPMS_RF_DYNAMIC_POWER	-40 °C ≤ TA ≤ 0 °C and 1.8 V ≤ V_{DD} ≤ 2.5 V, or 0 °C ≤ T_A ≤ 125 °C and 2.5 V ≤ V_{DD} ≤ 3.6 V	3	—	—	dBm	C
PRFMINn	Output power, minimum PRF vs. T_A and V_{DD} under control of FW TPMS_RF_DYNAMIC_POWER	25 °C ≤ T_A ≤ 60 °C and 2.5 V ≤ V_{DD} ≤ 3.6 V	5	—	—	dBm	C
PRFMIN00	Output power, Step = 00	—	—	–10	—	dBm	C
FSK	Frequency shift key step	—	—	3.17	—	kHz	D
MOOK	On off key modulation depth	—	60	80	—	dBc	C
BRRF	Baud rate range	—	1.2	—	38.4	kbits/sec	C
DR	Manchester encoding bit/s accuracy, based on MFO	—	–5	—	+5	%	D
DC	Modulation duty cycle, FSK, and OOK	—	45	50	55	%	C
FxTAL	External crystal frequency, all conditions	—	—	26	—	MHz	D
$t_{S\text{-}RCTS}$	Fixed portion, RF start-up process	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	500	620	µs	C
Bits	Variable portion, RF start-up process	—	—	3	—	bit times	C
tRF2	Total RF start time, write of SEND bit to start of RF output, at 2000 bit/s, where tRF = tS-RCTS + (Bits * bit/s^–1	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	2	2.2	ms	C
tRF9	Total RF start time, write of SEND bit to start of RF output, at 9600 bit/s, where tRF = tS-RCTS + (Bits * bit/s^–1	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	800	920	µs	C
tRF20	Total RF start time, write of SEND bit to start of RF output, at 20000 bit/s, where tRF = tS-RCTS + (Bits * bit/s^–1	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	640	760	µs	C
H2	Harmonic 2, 315 MHz or 434 MHz, with 50 Ω matching network[1], power step adjusted to reach target power in each domain.	—	—	—	–22	dBc	C
H3	Harmonic 3, 315 MHz or 434 MHz, with 50 Ω matching network[1], power step adjusted to reach target power in each domain.	—	—	—	–31	dBc	C
H4	Harmonic 4, 315 MHz or 434 MHz, with 50 Ω matching network[1], power step adjusted to reach target power in each domain.	—	—	—	–40	dBc	C
N3PH10k	315 MHz phase noise, ±10 kHz, Boost = 0	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	–87	–78	dBc / Hz	C

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Table 21. Radio frequency transmitter characteristics*...continued*

V_{DDS} Min ≤ V_{DD} ≤ V_{DDS} Max, T_{AS} Min ≤ T_A ≤ T_{AS} Max, unless otherwise specified.
All conditions characterized with NDK NX2016SA 26.000 MHz crystal.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
N3PH100k	315 MHz phase noise, ±100 kHz, Boost = 0	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	–95	–87	dBc / Hz	C
N3PH1M	315 MHz phase noise, ±1 MHz, Boost = 0	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	–82	–77	dBc / Hz	C
N31PH10k	315 MHz phase noise, ±10 kHz, Boost = 1	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	–75	–66	dBc / Hz	C
N31PH100k	315 MHz phase noise, ±100 kHz, Boost = 1	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	–83	–75	dBc / Hz	C
N31PH1M	315 MHz phase noise, ±1 MHz, Boost = 1	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	–96	–93	dBc / Hz	C
N4PH10k	434 MHz phase noise, ±10 kHz, Boost = 0	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	–85	–75	dBc / Hz	C
N4PH100k	434 MHz phase noise, ±100 kHz, Boost = 0	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	–92	–83	dBc / Hz	C
N4PH1M	434 MHz phase noise, ±1 MHz, Boost = 0	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	–83	–78	dBc / Hz	C
NPH10M	Phase noise, ±10 MHz	Typ = 25 °C, 3.0 V, Max = TAS Min to Max & VDDS Min to Max	—	–105	–101	dBc / Hz	C
NSP315	Spurious noise, <1 GHz, 10 kHz BW 315 MHz FCC 15.231a–e	—	—	—	–30	dBc	C
NSPUG	Spurious noise, < 1 GHz, 10 kHz BW 434 MHz ETSI EN300220	—	—	—	–40	dBc	C
NSPOG	Spurious noise, >1 GHz, 10 kHz BW 434 MHz ETSI EN300220	—	—	—	–40	dBc	C
OBWKF	Occupied bandwidth, < ±35 kHz FSK up to 19.2 kbit/s Korea, MIC 2007-63	—	—	—	200	kHz	C
OBWKO	Occupied bandwidth, OOK up to 9.6 kbit/s, Korea, MIC 2007-64	—	—	—	200	kHz	C
OBWJF	Occupied bandwidth, < ±45 kHz FSK up to 38.4 kbit/s, Japan, ARIB STD-T93	—	—	—	400	kHz	C
OBWJO	Occupied bandwidth, OOK up to 19.2 kbit/s, Japan, ARIB STD-T94	—	—	—	600	kHz	C
ML	Oscillation margin	—	850	—	—	Ω	D
f_{XCO}	Internal oscillator accuracy	—	–10	—	+10	ppm	D
v_{AREGOK}	RF V_{reg} capacitor Pre-charge voltage - Note: 0.47 µF V_{reg} capacitor connected.	V_{DDS} ≥ 2.1 V	—	1.5	—	V	C
t_{AREGOK}	RF V_{reg} capacitor Pre-charge Process - Note: 0.47 µF V_{reg} capacitor connected, additional to $t_{S\text{-}RCTS}$	V_{DDS} ≥ 2.1 V	—	630	1000	µSec	D

[1] 50 Ω is the input impedance of the measurement equipment

The firmware routine TPMS_PRECHARGE_EN performs the pre-charge of RF V_{reg} capacitor. When the pre-charge is successful, the execution time of the routine corresponds to t_{AREGOK} duration. When the pre-charge fails, the routine exits after a timeout longer than t_{AREGOK} max duration.

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6.14 Power consumption RF transmissions

Using the TPMS_RF_DYNAMIC_POWER firmware routine[2] allows adjusting the power step in order to compensate for variations of output power versus temperature and voltage. This routine is associated to a part-to-part trimming that initially adjusts the power step to compensate for process variations.

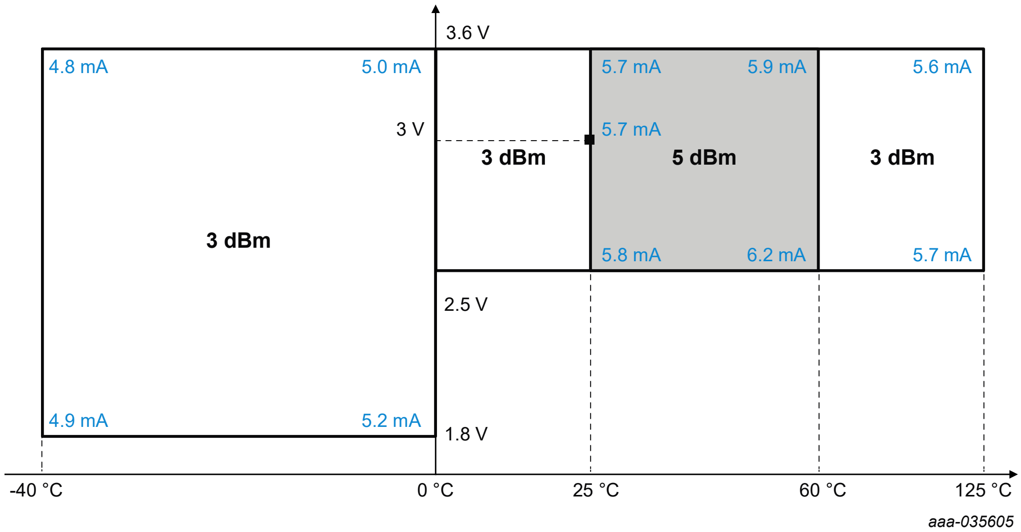

Figure 4. Dynamic power adjustment — 315 MHz

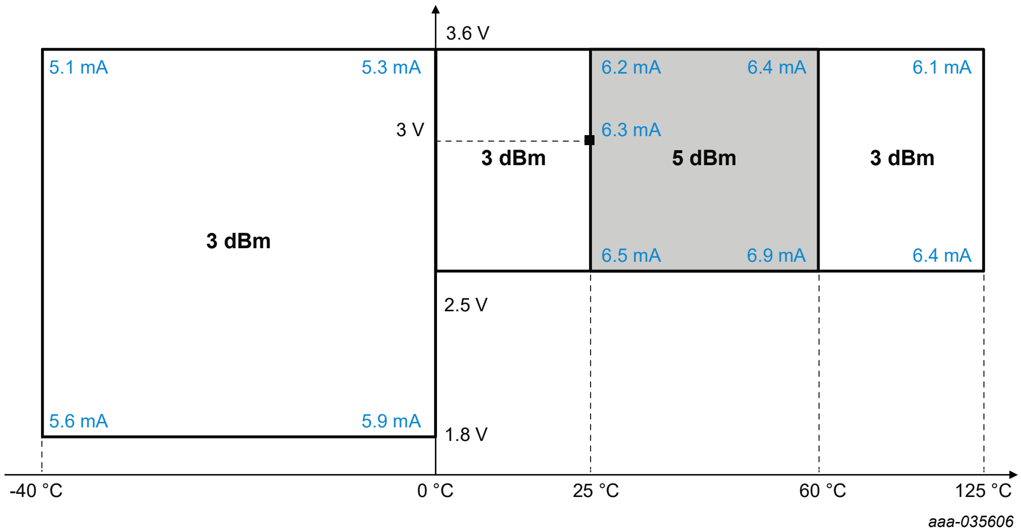

Figure 5. Dynamic power adjustment — 434 MHz

2 Refer to user manual, UM11227.[1]

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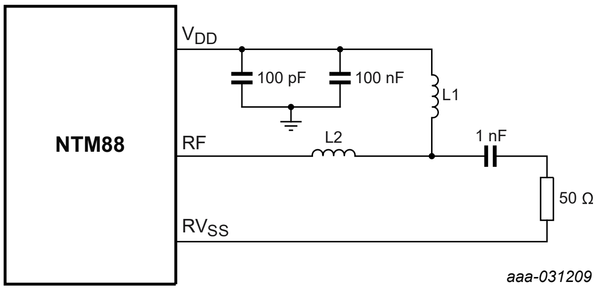

Figure 6. RF output power measurement configuration

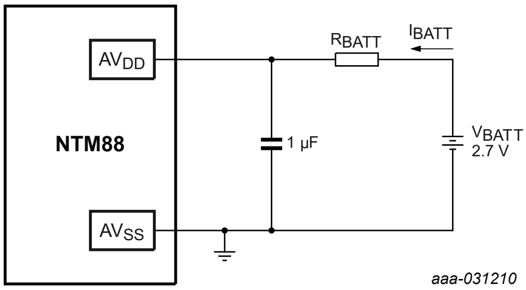

Figure 7. Battery performance test configuration

7 Mechanical specifications

7.1 Maximum ratings (mechanical)

Maximum ratings are the extreme limits the device can be exposed without permanent damage. The device contains circuitry to protect the inputs against damage from high static voltages; however, do not apply voltages higher than the values shown in Table 22. Keep V_{IN} and V_{OUT} within the range $V_{SS} \leq (V_{IN}$ or $V_{OUT}) \leq V_{DD}$.

Table 22. Maximum ratings

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
$P_{burst1k}$	Pressure transducer, minimum burst pressure	≤ 1200 kPa rating	2000	—	—	kPa	D
f_{P0}	Pressure transducer, minimum natural resonance frequency	—	—	5	—	MHz	D
Q_P	Pressure transducer damping ratio	—	—	1	—	—	D
PA_N	Pressure transducer, sensitivity to vertical acceleration	–500 g ≤ A ≤ +500 g	—	0	—	Pa / g	C
PA_{neg}	Pressure transducer, sensitivity to vertical acceleration	A < –500 g	2	4.5	6.5	Pa / g	C
PA_{pos}	Pressure transducer, sensitivity to vertical acceleration	A > +500 g	–6.5	–4.5	–2	Pa / g	C
f_{A0}	Accelerometer, minimum natural resonance frequency	—	7	—	16	kHz	D
Q_A	Accelerometer, damping ratio	—	1	—	4	—	D
AP1k	Accelerometer, sensitivity to pressure	90 kPa ≤ P ≤ 1200 kPa	–1.5	—	+1.5	g / 1000 kPa	C

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Table 22. Maximum ratings*...continued*

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Notes
A_{stop2h}	Accelerometer, minimum acceleration to reach travel stop	≤ 100 g rating	–200	—	+200	g	D
A_{stop7h}	Accelerometer, minimum acceleration to reach travel stop	> 100 g rating	–700	—	+700	g	D
m	Package Mass	—	—	0.2	—	gram	D
τ	Thermal time constant	—	—	101	—	sec	D

7.2 Media compatibility

Media compatibility is based on media and test method described in NXP Specification NXPOMS-1719007347-17056.[2] Consult your sales representative for more details and specific requirements.

Note:

The devices contain a gel that protects the pressure transducer and its inter-die connection wires from corrosion, which might otherwise result in catastrophic failure modes. NXP has observed that direct exposure to materials with the same or nearly-the-same solubility can potentially result in a corruption of the protective gel. A corruption can be less than catastrophic in nature, however may result in an offset of the pressure measurement from its factory calibrated value. An offset can potentially be larger than the allowed tolerances published in this data sheet.

Further, NXP does not recommend direct exposure to strong acid or strong base compounds as they can potentially result in a similar corruption as described above, or may result in a dissolution of the protective gel and/or the metal lid adhesive and/or the plastic device body. Such a dissolution can be catastrophic in nature, damaging the transducer surfaces and/or internal wire bonds and/or the control die surfaces. A potential dissolution may result in a similar offset, or cause the device to indicate overflow/underflow status, or may cause the device to cease operating in the worst case.

For a list of compounds known to generate out-of-tolerance offsets and/or catastrophic device failure, please contact an NXP sales representative.

8 Mounting recommendations

The package should be mounted with the pressure port pointing away from the axis of tire rotation. By mounting the pressure port away from the axis of tire rotation, centrifugal force propels any contaminants out of the pressure port. In cases where the application must orient the pressure port pointing inward, care must be taken to assure contaminants do not reach inside the pressure port.

A plugged port exhibits no change in pressure and can be cross checked in the user software. Use the method described in user manual UM11227.[1]

Refer to application note AN1902[3] for proper printed circuit board attributes and recommendations.

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9 Package outline

Consult the most recently issued drawing before initiating or completing a design. The drawings are available for download at https://www.nxp.com/docs/en/package-information/SOT1931-1_D.pdf.

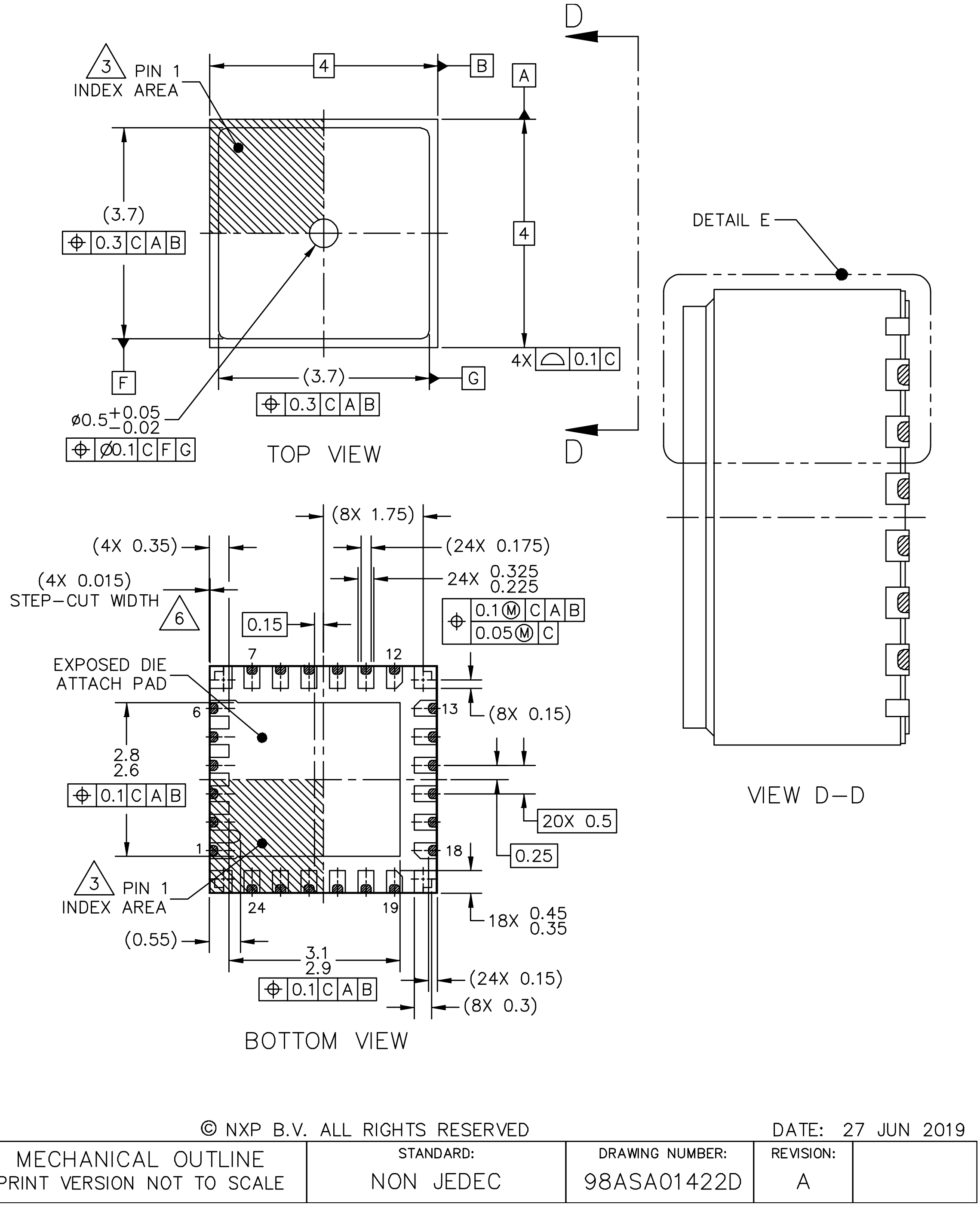
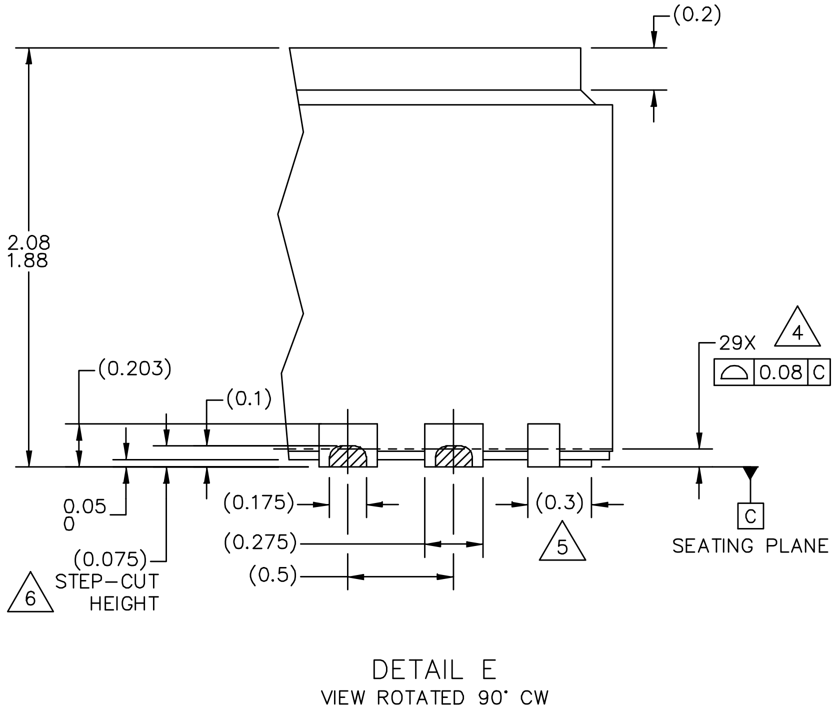


Figure 8. Package outline HQFN24 (SOT1931-1(D))



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DATE: 27 JUN 2019

MECHANICAL OUTLINE PRINT VERSION NOT TO SCALE	STANDARD: NON JEDEC	DRAWING NUMBER: 98ASA01422D	REVISION: A	

Figure 9. Package outline detail HQFN24 (SOT1931-1(D))

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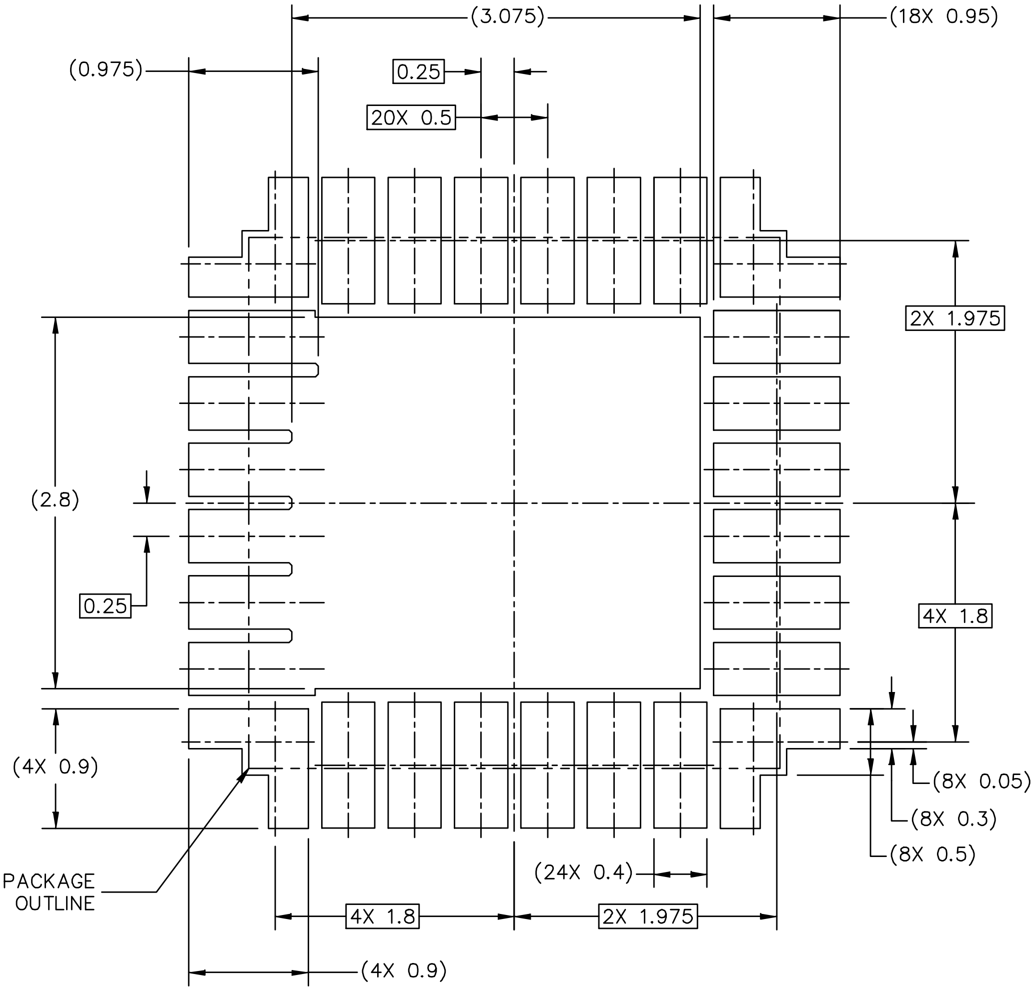

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Figure 10. Reflow soldering footprint part1 for HQFN24 (SOT1931-1(D))

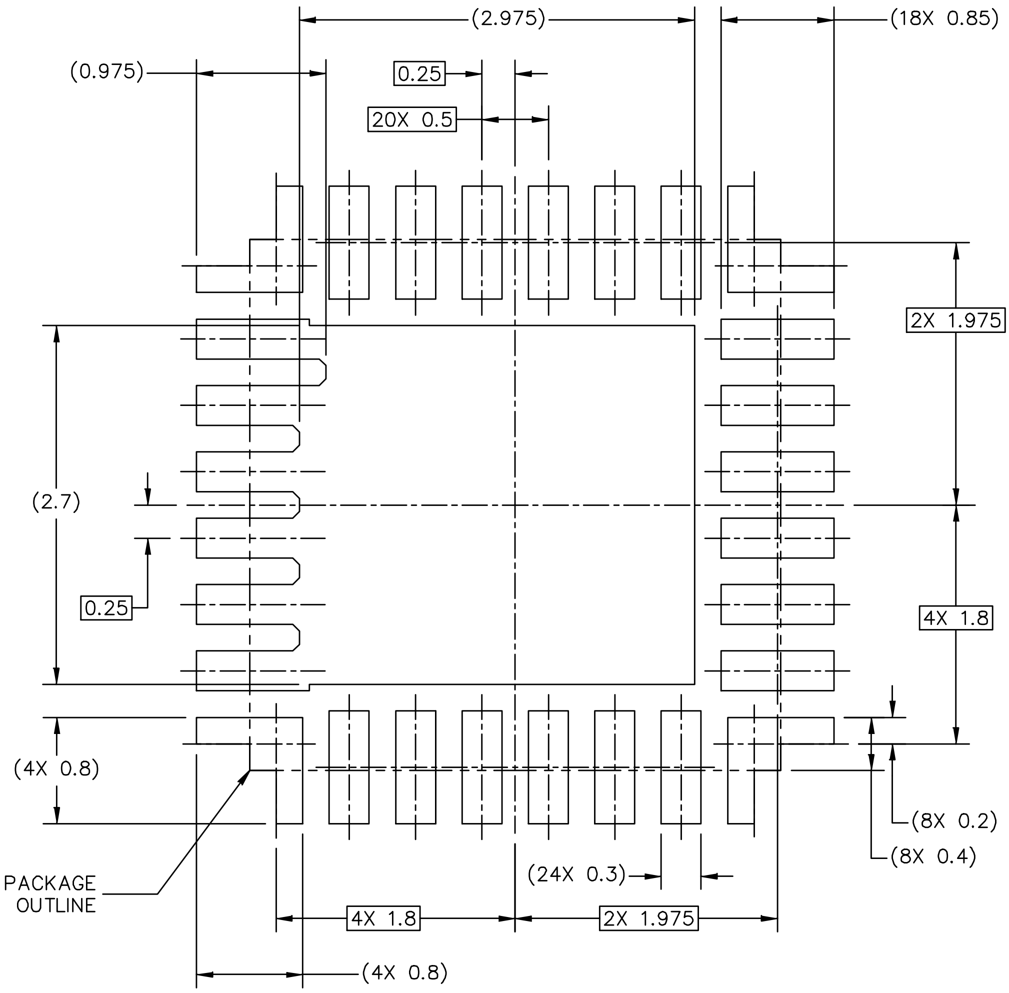

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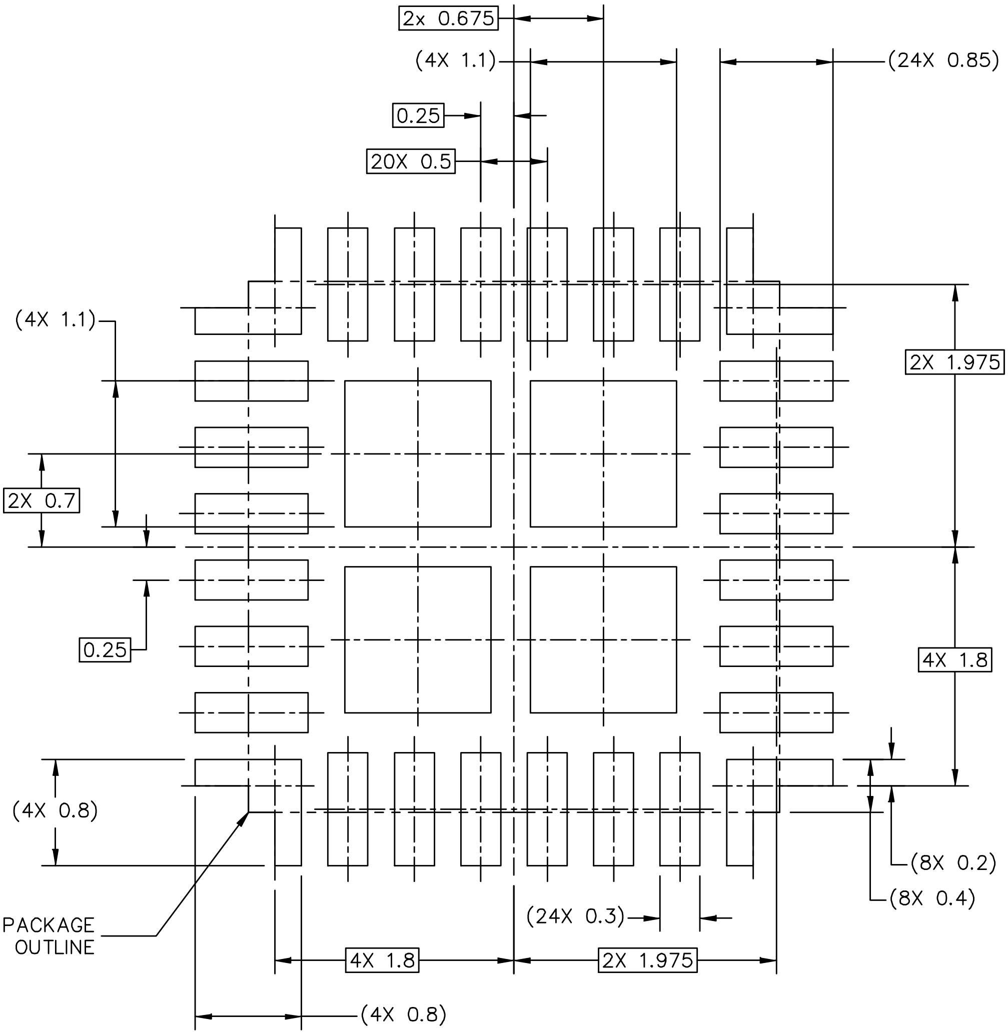
Figure 11. Reflow soldering footprint part2 for HQFN24 (SOT1931-1(D))



RECOMMENDED STENCIL THICKNESS 0.125

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Figure 12. Reflow soldering footprint part3 for HQFN24 (SOT1931-1(D))

NOTES:

1. ALL DIMENSIONS ARE IN MILLIMETERS.
2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M—1994.
3. PIN 1 FEATURE SHAPE, SIZE AND LOCATION MAY VARY.
4. COPLANARITY APPLIES TO LEADS, DIE ATTACH FLAG AND CORNER NON—FUNCTIONAL PADS.
5. ANCHORING PADS.
6. STEP—CUT IS APPLIED FOR BURR REMOVAL ONLY.

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Figure 13. Package outline notes HQFN24 (SOT1931-1(D))

10 References

NXP reference documents

[1] UM11227, *NTM88 family of tire pressure monitor sensors*

[2] NXP Specification NXPOMS-1719007347-17056, *Media Stress Methodologies for Sensors*, Contact your NXP sales representative for more information

[3] AN1902, *Assembly guidelines for QFN (quad flat no-lead) and SON (small outline no-lead) packages*

11 Revision history

Table 23. Revision history

Document ID	Release date	Description
NTM88Jxx5S v.3	25 September 2024	• NTM88Jxx5S v.3 supersedes NTM88Jxx5S v.2. • NTM88Jxx5S v.3 is a product data sheet, revised the status from preliminary to product. • Section 6.8, Table 12, revised "T_{DRIFT}" to "T_{STAB}" and revised the parameter description from "Temperature drift" to "Temperature measurement stability range". • Section 6.9, revised as follows: – Table 13, revised "V_{DRIFT}" to "V_{STAB} and revised the parameter description from "Volltage measurement drift" to "Voltage measurement stability range". – Table 14, revised "GxDRIFT" to "GxSTAB" and revised the parameter description from "Voltage measurement drift" to "Voltage measurement stability range". • Section 6.10.1, Table 15, revised the parameter description for P_{DRIFT} from "Pressure drift" to "Pressure long-term drift", inserted the condition " –40 °C ≤ TA ≤ 105 °C", and added a footnote. • Section 6.11.1, Table 16, revised "A_{DRIFT}" to "A_{STAB}" and revised the associated parameter from "Inertia drift" to "Acceleration measurement stability range". • Section 6.11.2, Table 17, revised "A_{DRIFT}" to "A_{STAB}" and revised the associated parameter from "Inertia drift" to "Acceleration measurement stability range". • Section 6.11.3, Table 18, revised "A_{DRIFT}" to "A_{STAB}" and revised the associated parameter from "Inertia drift" to "Acceleration measurement stability range". • Section 6.11.4, Table 19, revised "A_{DRIFT}" to "A_{STAB}" and revised the associated parameter from "Inertia drift" to "Acceleration measurement stability range".
NTM88Jxx5S v.2	6 June 2024	• NTM88Jxx5S v.2 supersedes NTM88Jxx5S v.1.2. • NTM88Jxx5S v.2 is a preliminary data sheet. • Section 2, revised "Six-channel, 8-, 10-, or 12-bit analog-to-digital converter (ADC10) with two external I/O inputs" to "Six-channel, 8-, 10-, or 12-bit analog-to-digital converter with two external I/O inputs". • Section 5.2, Table 3, revised as follows: – RST_B: Removed "/ V_{PP} programming voltage" from the Function and revised the first paragraph in the description. – GND: revised the first sentence of the description. • Section 6.10.1, Table 15, revised the table adding additional rows, revising values and updating references in the notes column. • Section 6.13, Table 21, added footnote to PRF2, PRF3, H2, H3, and H4 to the parameter field. • Section 7.1, Table 22, removed the row A_{CROSS} from the table. • Section 7.2, revised the specification and added a note. • Section 10, revised the NXP specification entry number and title.
NTM88Jxx5S v.1.2	21 July 2023	• NTM88Jxx5S v.1.2 supersedes NTM88Jxx5S v.1.1. • NTM88Jxx5S v.1.2 is an objective data sheet. • Section 3 "Ordering information", removed the subsection titled "Hardware version numbers".
NTM88Jxx5S v.1.1	23 June 2023	• NTM88Jxx5S v.1.1 supersedes NTM88Jxx5S v.1. • NTM88Jxx5S v.1.1 is an objective data sheet. • Table 2, revised the values for Code H.

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Table 23. Revision history*...continued*

Document ID	Release date	Description
NTM88Jxx5S v.1	12 October 2022	• NTM88J**xx**5S v.1 supersedes NTM88**xxx**5S v.1.2. This document supersedes NTM88**xxx**5S v.1.2 for the relevant part numbers in Section 3, Table 2 "Ordering options". • NTM88Jxx5S v.1 is an objective data sheet. • Initial release.

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Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.
[2] The term 'short data sheet' is explained in section "Definitions".
[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL https://www.nxp.com.

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