

**User guide** 

Door control MOTIX<sup>™</sup> Bridge MOTIX<sup>™</sup> SBC Z8F80481275

## About this document

#### Scope and purpose

This user guide provides instructions for using the evaluation board, which is designed to evaluate the associated system solution for door control. Moreover, this user guide provides an overview on the whole system offering for door control and extensive technical information on the board.





Door control evaluation board



### About this document

#### **Intended audience**

This document is intended for anyone using Infineon's Door control evaluation board.

*Note: printed circuit board (PCB) and auxiliary circuits are NOT optimized for final customer design.* 



Important notice

## **Important notice**

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Safety precautions

## Safety precautions

Table 1	Safety precautions
	<b>Caution:</b> The heat sink and device surfaces of the evaluation or reference board may become hot during testing. Hence, necessary precautions are required while handling the board. Failure to comply may cause injury.
Â	<b>Caution:</b> Only personnel familiar with the drive, power electronics and associated machinery should plan, install, commission and subsequently service the system. Failure to comply may result in personal injury and/or equipment damage.
	<b>Caution:</b> The evaluation or reference board contains parts and assemblies sensitive to electrostatic discharge (ESD). Electrostatic control precautions are required when installing, testing, servicing or repairing the assembly. Component damage may result if ESD control procedures are not followed. If you are not familiar with electrostatic control procedures, refer to the applicable ESD protection handbooks and guidelines.
	<b>Caution:</b> A drive that is incorrectly applied or installed can lead to component damage or reduction in product lifetime. Wiring or application errors such as undersizing the motor, supplying an incorrect or inadequate AC supply, or excessive ambient temperatures may result in system malfunction.
	<b>Caution:</b> The evaluation or reference board is shipped with packing materials that need to be removed prior to installation. Failure to remove all packing materials that are unnecessary for system installation may result in overheating or abnormal operating conditions.



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### 1 System offering

## 1 System offering

## **1.1** Introduction to the system offering

Infineon's system offering for door control encompasses a range of components that work together to provide a comprehensive solution.

#### **Key Components:**

- Infineon door control evaluation board: A robust hardware foundation for efficient integration and connectivity with a TRAVEO<sup>™</sup> II microcontroller, a MOTIX<sup>™</sup> SBC TLE9562 a MOTIX<sup>™</sup> Bridge TLE9166EQ, MOSFETs and several interfaces. For more information, refer to Introduction to the Infineon door control evaluation board
- **MOTIX<sup>™</sup> device drivers**: Microcontroller-independent embedded software for configuring and controlling the:
  - MOTIX<sup>™</sup> TLE9166EQ; for more information, refer to Introduction to the MOTIX<sup>™</sup> TLE9166EQ device driver
  - MOTIX<sup>™</sup> TLE9562; for more information, refer to Introduction to the MOTIX<sup>™</sup> TLE9562 device driver
- Application software: An embedded software project for IAR embedded work bench which includes the device drivers and the Traveo<sup>™</sup> II sample driver library (SDL). There are two application software projects offered:
  - Infineon door control evaluation board application software basic : In this application software, the Traveo<sup>™</sup> II initializes the MOTIX<sup>™</sup> SBC TLE9562 and the MOTIX<sup>™</sup> Bridge TLE9166EQ over SPI and start the cyclic status check function. Moreover, this application provides a glance at the integration of the device driver. For more information, refer to Introduction to the Infineon door control evaluation board application software basic
  - **Infineon door control evaluation board application software advanced:** This application software extends the functionality of the basic software. Apart from all the initializations, the advanced software application contains a routine to operate various loads of the door control module such as the window lift operation, mirror features, and the door lock function. For more information, refer to Introduction to the Infineon door control evaluation board application software advanced
  - **MOTIX<sup>™</sup> multi half-bridge IC configuration wizard**: A PC tool consisting of a *graphical user interface (GUI)* for configuring and visualizing the state of the MOTIX<sup>™</sup> SBC TLE9562 and MOTIX<sup>™</sup> bridge TLE9166EQ. For more information, refer to Introduction to the MOTIX<sup>™</sup> multi half-bridge IC configuration wizard



#### 1 System offering



Figure 2 Infineon's door control system offerings

## **1.1.1** Introduction to the Infineon door control evaluation board

The evaluation board combines a TRAVEO<sup>™</sup> II microcontroller with a MOTIX<sup>™</sup> SBC TLE9562 and MOTIX<sup>™</sup> bridge TLE9166EQ. Every pin of the MOTIX<sup>™</sup> bridge TLE9166EQ and most pins of the MOTIX<sup>™</sup> SBC TLE9562 can be accessed via pin headers.

The evaluation board can be supplied over banana jacks with 12 Vdc. The board is protected against reverse polarity of the input voltage supply. The logic power supply for the microcontroller, MOTIX<sup>™</sup> Bridge TLE9166EQ and the charge pump voltage for the MOTIX<sup>™</sup> bridge TLE9166EQ is provided by the MOTIX<sup>™</sup> SBC TLE9562.

All the OptiMOS<sup>™</sup> MOSFET half-bridges are placed on the board to drive BDC motors. The board has a USB-C port to use the on-board *serial wire debug (SWD)*. The *controller area network (CAN)* and *local interconnect network (LIN)* interfaces are available at a push-in connector.

To get the evaluation board, refer to How to get the system offering.



### 1 System offering



**Block diagram** 



### 1 System offering



Figure 4 Board description

## **1.1.2** Introduction to the MOTIX<sup>™</sup> TLE9166EQ device driver

The MOTIX<sup>™</sup> TLE9166EQ device driver is a microcontroller-independent embedded software library that provides an easy-to-use *application programming interface (API)* for configuring the TLE9166 half-bridge driver *integrated circuit (IC)*. The device driver is designed to be integrated into various microcontroller platforms and provides a set of functions to configure the TLE9166EQ and read its status registers. The device driver is available in the Infineon Developer Center.

## **1.1.3** Introduction to the MOTIX<sup>™</sup> TLE9562 device driver

The MOTIX<sup>™</sup> TLE9562 device driver is a microcontroller-independent embedded software library that provides an easy-to-use *API* for configuring the TLE9562 multifunctional system *IC*. The device driver is designed to be integrated into various microcontroller platforms and provides a set of functions to configure the TLE9562 and read its status registers. The device driver is available in the Infineon Developer Center.

## 1.1.4 Introduction to the Infineon door control evaluation board application software - basic

The application software is designed to provide users with an initial insight into the capabilities of our devices. It serves as an example guide for integrating device drivers into software projects. It consists of an embedded software example tailored for the Infineon door control evaluation board. The application software:

- Is executed by the Traveo<sup>™</sup> II microcontroller
- Initializes the TLE9166 and TLE9562, activating their outputs and high sides



#### 1 System offering

- Periodically reads the status register of these devices, with errors indicated via *light-emitting diode (LED)*s on the board
- Integrates and uses the API provided in the embedded software libraries, including:
  - Traveo™ II Sample Driver Library
  - TLE9166 device driver
  - TLE9562 device driver

This approach ensures that developers can seamlessly incorporate the devices into their projects, optimizing functionality.

## 1.1.5 Introduction to the Infineon door control evaluation board application software - advanced

This application software enhances the capabilities of the basic software by incorporating additional functionalities. It not only encompasses all the features of the basic software but also includes routines specifically designed to manage various loads in the door control module. These loads include window lift motors, mirror folding, mirror glass movement, mirror *LED*s, and door locks.

The software is configured to use the necessary peripherals of the Traveo<sup>™</sup> II microcontroller such as *serial peripheral interface (SPI)*, *pulse-width modulation (PWM)*, and timers. Within the software, a state machine routine manages various configurations of Traveo<sup>™</sup> II, MOTIX<sup>™</sup> SBC TLE9562 and MOTIX<sup>™</sup> bridge TLE9166EQ, by enabling or disabling various output stages to control specific loads within the door control module.

For access to this software and comprehensive documentation, refer to How to get the system offering.

## 1.1.6 Introduction to the MOTIX<sup>™</sup> multi half-bridge IC configuration wizard

The MOTIX<sup>™</sup> multi-half-bridge *IC* configuration wizard is a PC tool consisting of a *GUI* within the Infineon Developer Center Launcher.

The GUI enables you to configure the charge pump of MOTIX<sup>™</sup> SBC TLE9562 and to configure the MOTIX<sup>™</sup> bridge TLE9166EQ during runtime. In addition, it monitors the values of the device register and the CM pin of the device.

This tool works together with the evaluation board and the uIO-stick, which sends the corresponding *SPI* messages, drives the digital inputs of the device, and monitors the CM analog pin of the device.

To get the configuration wizard, refer to How to get the system offering.

## 1.2 How to get the system offering

#### How to get the Infineon door control evaluation board

To order a board:

- **1.** Go to https://www.infineon.com
- 2. In the search bar, enter your required product, for example, Door control evaluation board
- 3. Once you have found the product page, navigate to the order section
- 4. To order the product from Infineon directly or from the distribution partner, click **Order online**



#### 1 System offering

> Home > Products	> Evaluatio	n Boards >	
Overview Diagrams		Order	
Parametrics		Sales Product Name	
Documents		OPN 9 Info	
3 Order	1	Product Status	active and preferred
Design Support		Infineon Package name	
Training		Standard Package name	
Support	4	Order online	्चि/ Buy online
	- 1	Completely lead free	
		Halogen free	
		RoHS compliant	no
		Packing Size	1
		Packing Type	CONTAINER
		Moisture Level	
		Moisture Packing	NON DRY

#### Figure 5 Navigation on the web page to order the board

#### How to get the application software examples and device drivers

To download an embedded software package:

- **1.** Go to https://softwaretools.infineon.com/software
- 2. In the search field, enter the name of the embedded software package
- 3. Click **Request**, as shown in Figure 6
- **4.** Click the cart
- 5. Click Request
- 6. Fill the questionnaire, accept the license terms, and click **Submit request**, as shown in Figure 7
- 7. A few minutes later, the software package is available for download in the **My Space** tab page under **My Software**. There, click **Details** and then **Download**



## **1** System offering

Cinfineon	Developer Center	Technical Support 8 myInfineon 👻 문 Cart
	My Space Tools Software	
	Infineon Example This is an example package. Embedded Software Application & Algorithms Middleware (Device Drivers & Libraries) Select your operating system	Code Example
	All Systems 🗸	
	Version: 1.0	
	Embedded-Software (generic) (zip) File size: 15.64 MB Related links	▲ Downloads may be restricted. If so, please request access first.           Request         Yes           Download         Unit

Figure 6

Software package within the Infineon Developer Center



#### **1** System offering

infineon	Developer	Center		Technical Support 8	문 Cart (1)
	My Space	Tools Software			
	ŗ				$\oslash$
	0 _		_ 2		- 3
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	Check	out: Additional information	Information		
	Please fill the	questionnaire(s) to proceed with your order.			
	Infir	eon Example			
		What is the name of your company?			
	2	What is your application type?			
		e.g. 150W Water Pump, 380W engine cooling fan,			
	3	what is your project status?			
		e.g. pre development, series project, feasibility study,			
	4	What is your role?			
		e a Engineer Marketing Sales			
	5	How did you become aware of this offer			
	6	Evaluation License Agreement			
		Infineon Technologies AG EVALUATION SOFTWARF LICENSE AGREEMENT			I
		BY INSTALLING OR HAVING INSTALLED THE SOFTWA	RE, LICENSEE AGREES TO BE BOUND BY THE	TERMS AND CONDITIONS OF THIS	
		AGREEMENT. IF LICENSEE DOES NOT AGREE TO ALL USE THE SOFTWARE BUT IMMEDIATELY DELETE IT (T	FERMS AND CONDITIONS OF THIS AGREEMEN O THE EXTENT THAT IT WAS DOWNLOADED A	IT, LICENSEE (INCLUDING YOU) SHALL N LREADY).	TOT
		1. DEFINITIONS			
		I accept the license agreement			
				Sub	nnit request

#### Figure 7

#### Requesting download of software package

#### How to get the MOTIX<sup>™</sup> Multi half-bridge IC configuration wizard

You can install the tool from the Infineon Developer Center Launcher, which you can download here.

From there, in Step 3, under **Tools**, search for MOTIX<sup>™</sup> Multi half-bridge IC configuration wizard.

Once installed, in Step 5, under **Manage Tools** and hovering over the MOTIX<sup>™</sup> Multi half-bridge IC configuration wizard box, click **Start**. In the new window that appears, to start the tool, click TLE9166EQ EVALBOARD.



#### **1** System offering



Figure 8 MOTIX<sup>™</sup> Multi half-bridge IC configuration wizard

## **1.3** Benefits of the system offering

This integrated platform is designed to streamline the evaluation process, providing the necessary tools to effectively test, analyze, and harness the capabilities of Infineon's system solution for door control. The following explains how to combine components for maximum benefit.

Evaluation board + application software: Enables rapid prototyping and development. The application software examples have been developed to run on this evaluation board, so they only have to be compiled and flashed into the Traveo<sup>™</sup> II. All the required microcontroller peripherals (*general purpose input output* (*GPIO*), *PWM*, *SPI*)\* are configured for the correct pin mapping and functionality. The Infineon products on the evaluation board are the best fit for a door control application. The application software examples have been developed so that the correct application load type is connected to the correct output stage\*. This serves as an inspiration for door modules system partitioning. Moreover, the application software examples showcase how the device drivers can be integrated in a bigger project and how their functions can be used to control the hardware.

#### *Note:* \* = Infineon door control evaluation board application software - Advanced



#### 1 System offering



Figure 9

#### Evaluation board + Application software

**Evaluation board + configuration wizard**: Enables run-time evaluation. The *GUI* enables you to configure the charge pump of MOTIX<sup>™</sup> SBC TLE9562 and configure the MOTIX<sup>™</sup> Bridge TLE9166EQ with the uIO-stick. The configuration of the MOTIX<sup>™</sup> Bridge TLE9166EQ can be changed during run-time to monitor the values of the device registers. There is no need to re-flash or reboot any microcontroller to make any changes



#### Figure 10 Evaluation board + configuration wizard

**Device driver + other microcontroller platform**: The MOTIX<sup>™</sup> TLE9166EQ and MOTIX<sup>™</sup> TLE9562 device drivers are a microcontroller-independent software library that provides an easy-to-use *API* to control the MOTIX<sup>™</sup> Bridge TLE9166EQ and MOTIX<sup>™</sup> SBC TLE9562. The device drivers are designed to be integrated into various microcontroller platforms and provide a set of functions to configure and read the status of the TLE9166EQ and TLE9562



Figure 11

Device driver + other microcontroller platform



2 Setting up the Infineon door control evaluation board

## 2 Setting up the Infineon door control evaluation board

#### Box delivery content

The Door control evaluation board is delivered together with a USB-C cable to connect the board to a PC, and a QR code on the box to access exclusive content for the board, such as *PCB* design files

#### Initial board setup

The door control evaluation board comes with a pre-flashed Introduction to the Infineon door control evaluation board application software - basic. To ensure that the initial setup works as expected, follow these steps:

**1.** Check whether the default jumper position is set. The default jumper position is highlighted in purple in the figure below



#### Figure 12 Default jumper position

2. After checking the default jumper position, follow the steps given in the table and relevant components as highlighted in the figure below:

Table 2	Steps for setting up the evalua	ion board
---------	---------------------------------	-----------

Steps	Designator	Label	Description
a	X3, X4	V <sub>BAT</sub> , GND	Connect the board to a 12 V power supply using banana connectors (X3, X4) on the board.



## 2 Setting up the Infineon door control evaluation board

Table 2			
Steps	Designator	Label	Description
b	D5	V <sub>BAT</sub>	V <sub>BAT</sub> supply LED D5 indicated that positive supply voltage has been applied on the board
C	D4	Vs	V <sub>s</sub> LED D4 indicates that there is a positive voltage after the reverse polarity protection, which is applied to the devices of the board
d	D10	V <sub>CC1</sub>	V <sub>CC1</sub> LED D10 indicated that MOTIX <sup>™</sup> SBC TLE9562 device is active and LDO of the MOTIX <sup>™</sup> SBC TLE9562 is supplying the 5 V supply for Traveo <sup>™</sup> II and MOTIX <sup>™</sup> Bridge TLE9166EQ
e	D14, D15	Debugging LED interface	If the above supply indication are observed as described then, now you can see the LEDs D15, D14 permanently ON. For more information on the functionality of the pre- flashed application software, refer to Introduction to the Infineon door control evaluation board application software - basic
f	D13, D12	Debugging LED Interface	LED D13, D12 blinking, which indicates that pre-flashed application software is working correctly. For more information on the functionality of the pre- flashed application software, refer to Introduction to the Infineon door control evaluation board application software - basic



2 Setting up the Infineon door control evaluation board



Figure 13 Supply connector and LEDs

#### **Exclusive content**

To access exclusive content, click https://softwaretools.infineon.com/projects/create.



## 3 In detail: Infineon door control evaluation board

## 3.1 Technical data

Table 3

Technical data is specified in the table below. The current capability for supply and motor phases is limited by the default assembly of banana plugs for battery supply and the motor phase connector. Higher current capability can be reached by adjusting the battery and motor connectors.

If working with higher currents than the specified maximum ratings, the relevant safety measures must be applied.

Parameter	Value	
Supply voltage	Specified by design Typ. 12 V (max. 28 V)	
Supply current	Max. 10 A	
Pin ports	5 V	
Board size	150 mm x 110 mm	

## 3.2 Functional description

**Technical data** 

## 3.2.1 MOTIX<sup>™</sup> bridge TLE9166EQ

## 3.2.1.1 Power stage of MOTIX<sup>™</sup> bridge TLE9166EQ

The integrated power stages of MOTIX<sup>™</sup> bridge TLE9166EQ are connected to the output screw connector X33. The high-side MOSFET driver is connected to X33 via Q3 and EC mirror control driver via Q4. The drain of the Q4 MOSFET can be connected to OUT10 using jumper X34. For more information, refer to Jumpers. Additionally, the placement option for D16 at SH to GND and gate source capacitance C92 is available for the high-side MOSFET driver.





Power stage of MOTIX<sup>™</sup> bridge TLE9166EQ



## 3.2.1.2 Jumpers



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Jumpers

Table 4	Jumpers	
Designator	Label	Description
X34	OUT10 configuration	Set jumper to connect the OUT10 signal of MOTIX <sup>™</sup> Bridge TLE9166EQ either to the output connector X33 or input of Q4. The jumper is set to output connector X33 by default.
X22	СМ	Set jumper to connect MOTIX <sup>™</sup> Bridge TLE9166EQ CM signal to TRAVEO <sup>™</sup> II microcontroller port P6_2 (pin 20). The jumper is set by default.
X22	PWM	Set jumper to connect MOTIX <sup>™</sup> Bridge TLE9166EQ PWM signal to TRAVEO <sup>™</sup> II microcontroller port P7_4 (pin 33). The jumper is set by default.
X22	SDO	Set jumper to connect MOTIX <sup>™</sup> Bridge TLE9166EQ SDO signal to TRAVEO <sup>™</sup> II microcontroller port P13_0 (pin 52). The jumper is set by default.
X22	SDI	Set jumper to connect MOTIX <sup>™</sup> Bridge TLE9166EQ SDI signal to TRAVEO <sup>™</sup> II microcontroller port P13_1 (pin 53). The jumper is set by default.
X22	SCLK	Set jumper to connect MOTIX <sup>™</sup> Bridge TLE9166EQ SCLK signal to TRAVEO <sup>™</sup> II microcontroller port P13_2 (pin 54). The jumper is set by default.
X22	CSN	Set jumper to connect MOTIX <sup>™</sup> Bridge TLE9166EQ CSN signal to TRAVEO <sup>™</sup> II microcontroller port P13_3 (pin 55). The jumper is set by default.

## 3.2.1.3 Signal pin headers

Different measurement signals of MOTIX<sup>™</sup> Bridge TLE9166EQ are routed to X31 and X32 pin headers for the easy access of measurement.





#### Figure 16

Signal pin headers

## 3.2.1.4 Assembly options

Values for these optional additional placements must be determined depending on the application. The typical components and values can be found in Chapter 3.3.3.



### Figure 17 Assembly options

#### Table 5Additional placements

·		
Designator	Description	
C92	Gate-drain capacitor high-side MOSFET	
D16	Clamping diode at SH of the high-side driver	
R47	To avoid measurement voltage saturation on the CM pin	



## 3.2.2 MOTIX<sup>™</sup> SBC TLE9562

## **3.2.2.1** Power stage of MOTIX<sup>™</sup> SBC TLE9562

Four MOSFET half bridges are controlled by MOTIX<sup>™</sup> SBC TLE9562 and are connected to the X69 screw connector. Every HBx (Q5, Q6, Q7 and Q8) integrates a half bridge, consisting of two N-channel MOSFETS inside the package.

Externally to each HBx: Gate resistors (R59,...,R65) on GHx and GLx are connected. Additionally, the placement option for the SH to GND capacitor is available for each HBx. The outputs of the half bridges Q5, Q6, Q7 and Q8 are routed respectively to SH1, SH2, SH3, SH4 at the screw connector.

Along with the HBx, MOTIX<sup>™</sup> SBC TLE9562 also has four high-side switches, which can be used over the X51 connector.



Figure 18 Power stage of MOTIX<sup>™</sup> SBC TLE9562

## 3.2.2.2 Jumpers







Table 6	Jumpers	
Designator	Label	Description
X64	V <sub>CC1</sub>	Set jumper to connect supply to V <sub>CC1</sub> indication LED. Jumper is set by default
X68	CRC	Set jumper to pull down the CRC pin of MOTIX <sup>™</sup> SBC TLE9562 to activate CRC functionality. Jumper is set by default
X67	INT_N/TEST	Set jumper to pull down the INT_N/Test pin of MOTIX <sup>™</sup> SBC TLE9562 to activate software development mode. Jumper is set by default
X36	SDO	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 SDO signal to Traveo <sup>™</sup> microcontroller port P18_0 (pin 67). Jumper is set by default
X36	SDI	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 SDI signal to Traveo <sup>™</sup> microcontroller port P18_1 (pin 68). Jumper is set by default
X36	SCLK	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 SCLK signal to Traveo <sup>™</sup> microcontroller port P18_2 (pin 69). Jumper is set by default
X36	CSN	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 CSN signal to Traveo <sup>™</sup> microcontroller port P18_3 (pin 70). Jumper is set by default
X36	PWM1/CRC	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 PWM1/CRC signal to Traveo <sup>™</sup> microcontroller port P7_0 (pin 29). Jumper is set by default
X36	PWM3	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 PWM3 signal to Traveo <sup>™</sup> microcontroller port P7_2 (pin 31). Jumper is set by default
X36	TXDLIN	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 TXDLIN signal to Traveo <sup>™</sup> microcontroller port P0_0 (pin 2). Jumper is set by default
X36	RXDLIN	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 RXDLIN signal to Traveo <sup>™</sup> microcontroller port P0_1 (pin 3). Jumper is set by default
X36	RST	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 RST signal to Traveo <sup>™</sup> microcontroller port P2_3 (pin 9). Jumper is set by default
X36	INT_TEST	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 INT_TEST signal to Traveo <sup>™</sup> microcontroller port P0_3 (pin 5). Jumper is set by default
X36	WK4/SYNC	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 WK4/SYNC signal to Traveo <sup>™</sup> microcontroller port P5_0 (pin 14). Jumper is set by default
X36	TXDCAN	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 TXDCAN signal to Traveo <sup>™</sup> microcontroller port P3_0 (pin 11). Jumper is set by default
X36	RXDCAN	Set jumper to connect MOTIX <sup>™</sup> SBC TLE9562 RXDCAN signal to Traveo <sup>™</sup> microcontroller port P3_1 (pin 10). Jumper is set by default

## 3.2.2.3 Test points





Table 7 Test points

Signal	Designator	Description
V <sub>CC1</sub>	X35	Test points to measure the digital supply voltage of TRAVEO <sup>™</sup> II and MOTIX <sup>™</sup> Bridge TLE9166EQ
GND	X24	Test points to connect to ground
SH1, SH2, SH3, SH4	X56, X57, X58, X59	Test points to measure the motor phase voltages

## 3.2.2.4 Signal pin headers

Various measurement signals of MOTIX<sup>™</sup> SBC TLE9562 are routed to X50 pin headers for the easy access of measurement.





Signal pin headers





## 3.2.2.5 Pushbuttons



#### Figure 22 Pushbuttons

Table 8	Push buttons
Designator	Description
S3	WK1: Wake input trigger push button for MOTIX <sup>™</sup> SBC TLE9562, Trigger is connected to the HS1 of the MOTIX <sup>™</sup> SBC TLE9562
S4	WK2: Wake input trigger push button for MOTIX <sup>™</sup> SBC TLE9562, Trigger is connected to the V <sub>S</sub> of the MOTIX <sup>™</sup> SBC TLE9562
S5	WK3: Wake input trigger push button for MOTIX <sup>™</sup> SBC TLE9562, Trigger is connected to the V <sub>S</sub> of the MOTIX <sup>™</sup> SBC TLE9562

## 3.2.2.6 LEDs







Table 9 LEDs	
Designator	Description
D10	Indicates the digital supply $V_{CC1}$ of TRAVEO <sup>TM</sup> II and MOTIX <sup>TM</sup> bridge TLE9166EQ is active

## 3.2.2.7 LIN

The integrated *LIN* transceiver of MOTIX<sup>™</sup> SBC TLE9562 is connected to a X70 PCB terminal block. To connect the Traveo<sup>™</sup> II lines with the transceiver, refer to MOTIX<sup>™</sup> SBC TLE9562 and TRAVEO<sup>™</sup> II connections





## 3.2.2.8 CAN

The X66 PCB terminal block can be used to connect the CAN\_P and CAN\_N cables. To connect the Traveo<sup>™</sup> II lines with the transceiver, refer to MOTIX<sup>™</sup> SBC TLE9562 and TRAVEO<sup>™</sup> II connections. The *CAN* termination resistors R78 and R73 are mounted by default.

Additionally, the capacitor C65 is mounted between the resistors. A placement option is available to solder a common mode choke L2. If L2 is placed, the 0  $\Omega$  resistors R72 and R79 must be removed.





CAN connector and pinout



## 3.2.2.9 Assembly options

Values for these optional additional placements must be determined depending on the application. The typical components and values can be found in Chapter 3.3.3.



#### Figure 26 Assembly options

#### Table 10Additional placements

Designator	Description
C48, C49, C50, C51	SH-GND capacitor
L2	CAN common mode choke. If placed, remove R72 and R79

## 3.2.3 TRAVEO<sup>™</sup> II

## 3.2.3.1 Jumpers



#### Figure 27



Table 11 Jumpers		
Designator	Description	
X78	Set jumper to connect the potentiometer to V <sub>CC1</sub> supply. Jumper is set by default. For more information, refer to Potentiometer	
X74	Set jumper to connect the potentiometer output to the analog pin P6_1 of the TRAVEO <sup>™</sup> II microcontroller. Jumper is set by default. For more information, refer to Potentiometer	
X76	Set jumpers to connect <i>GPIO</i> s to <i>LED</i> s. Jumpers are set by default. For more information, refer to LEDs	

## 3.2.3.2 Test points



Figure 28 Test points

## Table 12 Test points

Signal	Designator	Description
V <sub>CC1</sub>	X85	Test points to measure the digital supply voltage of TRAVEO <sup>™</sup> II and MOTIX <sup>™</sup> bridge TLE9166EQ
GND	X82	Test points to connect to ground



## 3.2.3.3 Push button



Figure 29 Push button

## Table 13 Push button

Designator	Description
S1	RESET: Reset push button for TRAVEO <sup>™</sup> II microcontroller

## 3.2.3.4 LEDs





LEDs



Table 14 LEDs		
Designator	Description	
D11	Can be connected to GPIO P12_4 (pin 49) with jumper X76, as described in Jumpers	
D12	Can be connected to GPIO P12_3 (pin 48) with jumper X76, as described in Jumpers	
D13	Can be connected to GPIO P12_2 (pin 47) with jumper X76, as described in Jumpers	
D14	Can be connected to GPIO P12_1 (pin 46) with jumper X76, as described in Jumpers	
D15	Can be connected to GPIO P12_0 (pin 45) with jumper X76, as described in Jumpers	

## 3.2.3.5 Potentiometer

A potentiometer is available on the board. It is supplied via  $V_{CC1}$  over jumper X78. The output of the potentiometer is connected to the port P6\_1 (pin 19) of the TRAVEO<sup>TM</sup> II over jumper X74.



Figure 31 Placement and pinout of the potentiometer

## 3.2.3.6 Traveo<sup>™</sup> pin headers

Additional unused pins of the TRAVEO<sup>™</sup> II are routed to X88, X86 and X87 pin headers for the easy access of measurement.





Figure 32 Signal pin headers

## 3.2.4 Power supply

## 3.2.4.1 Supply connectors



#### Figure 33 Supply connector

Table 15 Connectors	Table 15	Connectors
---------------------	----------	------------

Functionality	Designator	Description
V <sub>BAT</sub> , GND	X3, X4	Banana jacks for power supply (red) and ground (black)



## 3.2.4.2 Jumpers



#### Figure 34 Jumpers

Table 16 Jumpers		
Designator Description		
X6	Set jumper to connect supply to $V_{\rm S}$ indication LED. Jumper is set by default	
Х7	Set jumper to connect supply to $V_{BAT}$ indication LED. Jumper is set by default	

## 3.2.4.3 Test points



Figure 35 Test points

Table 17	Test points

	•		
Signal	Designator	Description	
V <sub>BAT</sub>	X2	Test point to measure supply voltage	
Vs	X1	Test point to measure supply voltage of MOTIX <sup>™</sup> Bridge TLE9166EQ and MOTIX <sup>™</sup> SBC TLE9562 after the reverse polarity protection	
GND	X5	Test points to connect to ground	



## 3.2.4.4 LEDs



#### Figure 36 LEDs

able 18 LEDs		
Designator	Description	
D4	Indicates that supply voltage, $V_{\rm S}$ is active for the board after reverse recovery protection	
D5	Indicates that there is a positive voltage at $V_{\rm BAT}$	

## 3.2.5 ulO-stick

## 3.2.5.1 ulO connector



#### Figure 37 uIO connector

#### Table 19Connectors

Functionality	Designator	Description
ulO	X52	Connector for uIO stick, direct interface of MOTIX <sup>™</sup> bridge TLE9166EQ and MOTIX <sup>™</sup> SBC TLE9562 to the PC configuration tool. For more information, refer to uIO-stick Interface



## 3.2.5.2 Jumper

MOTIX<sup>™</sup> Bridge TLE9166EQ and MOTIX<sup>™</sup> SBC TLE9562 can be configured using available configuration wizard over uIO-stick interface without involving TRAVEO<sup>™</sup> II microcontroller. Use the following available jumpers to connect the uIO-stick to either MOTIX<sup>™</sup> SBC TLE9562 or MOTIX<sup>™</sup> bridge TLE9166.

To use this interface for MOTIX<sup>™</sup> bridge TLE9166EQ, first disconnect the device from the microcontroller by removing X36 jumpers. Now, connect jumper between X89 and X91 pin header. Information on the different signals on the pin header is shown on the picture below or on the board. Use the connector X52 to connect the board to the PC using the uIO-stick.



Figure 38

## Using the uIO-Stick connector to configure MOTIX<sup>™</sup> devices over the configuration wizard

To use this interface for the MOTIX<sup>™</sup> SBC TLE9562 device, first disconnect device from microcontroller by removing X22 jumpers. Then, connect the jumper between X91 and X92 pin headers. The information of the different signals on the pin header is given on the picture below or on the board. Use the connector X52 to connect board to the PC over the uIO-stick.

## 3.2.5.3 Test point



#### Figure 39 Test points

## Table 20Test points

Signal	Designator	Description
GND	X53	Test points to connect to ground



## 3.2.6 Debugger

## 3.2.6.1 Connector

The on-board debug circuit (CY8C5868LTI-LP039) connects the PC with the TRAVEO<sup>™</sup> II using a USB-C connector. The debug circuit can be used for flashing and debugging embedded software, as in the application software examples. When connected to a PC, it connects as KitProg3 USB-UART, provides an *SWD* interface and a virtual COM port. KitProg3 supports CMSIS-DAP Bulk and HID mode, as well as arm DAPLink mode, the mode can be switched with push button S2, push to button will cycle through the different modes

The board can be used with other SWD linkers using the SWD connector. For that, the jumper bridges X10 must be removed to disconnect the on-board debug circuit from the TRAVEO<sup>™</sup> II.

The tracebox connector can only be used while the on-board circuit is disconnected.

*Tip:* If the KitProg3 is not recognized by the PC, click **MODE** to switch the debug circuit to CMSIS-DAP mode.



#### Figure 40 Connectors and available signals

Connectors

#### Table 21

Designator	Description
X18	Debugging interface to connect external debugger.
X11	Connector for the tracebox.
	Designator X18 X11



Table 21	(continued) Conne	ctors
Functionality	Designator	Description
USB	X21	USB-C connector to connect the on-board debugger to a PC for debugging and virtual COM port

The table below provides the information of the TRAVEO<sup>™</sup> II microcontroller pinout for signals connected to SWD, tracebox, and PSoC<sup>™</sup> connectors.

Table 22	TRAVEO <sup>™</sup> II microcontroller pinout for debuggers interface
----------	---

Signal	TRAVEO <sup>™</sup> II Port (pin)	
TV_XRES	XRES_L_N (Pin 85)	
TV_SWDCLK	P23_5 (pin 97)	
TV_SWDIO	P23_6 (pin 98)	
TV_UART_TX	P17_1 (pin 65)	
TV_UART_RX	P17_2 (pin 66)	
TB_TV_UART_TX	P22_0 (pin 91)	
TB_TV_UART_RX	P22_1 (pin 92)	
TB_TV_SPI_MOSI (X86 - MOSI)	P19_0 (pin 77)	
TB_TV_SPI_MISO (X86 - MISO)	P19_1 (pin 78)	
TB_TV_SPI_CLK (X86 - CLK)	P19_2 (pin 79)	
TB_TV_SPI_CS (X86 - CSN)	P19_3 (pin 80)	

### 3.2.6.2 Jumpers

Use these jumpers to connect PSoC<sup>™</sup> based on-board debugger to flash Traveo<sup>™</sup>II microcontroler.

*Note:* If you are using an external debugger with the SWD connector, these jumpers must be removed



#### 3 In detail: Infineon door control evaluation board



#### Figure 41 Jumpers

Luman ore

Table 22

Table 25		
Designator	Signal	Description
X10	TV_SWDIO	Set jumper to connect PSoC <sup>™</sup> signal SWDIO to TRAVEO <sup>™</sup> II microcontroller port P23_6 (pin 98). Jumper is set by default.
X10	TV_SWDCLK	Set jumper to connect PSoC <sup>™</sup> signal SWDCLK to TRAVEO <sup>™</sup> II microcontroller port P23_5 (pin 97). Jumper is set by default.
X10	TV_XRES	Set jumper to connect PSoC <sup>™</sup> signal XRES to TRAVEO <sup>™</sup> II microcontroller port XRES_L_N (Pin 85). Jumper is set by default.
X10	TV_UART_TX	Set jumper to connect PSoC <sup>™</sup> signal UART_TX to TRAVEO <sup>™</sup> II microcontroller port P17_1 (pin 65). Jumper is set by default.
X10	TV_UART_RX	Set jumper to connect PSoC <sup>™</sup> signal UART_RX to TRAVEO <sup>™</sup> II microcontroller port P17_2 (pin 66). Jumper is set by default.

## 3.2.6.3 Test point



#### Figure 42 Test points

Table 24 Test points

Signal	Designator	Description
V <sub>BUS</sub>	X19	Test point to measure supply voltage of on-board debugger circuit
GND	X20, X23	Test points to connect to ground

## 3.2.6.4 Signal pin headers

Different measurement signals of PSoC<sup>™</sup> are routed to X12 pin headers for the easy access of measurement.









## 3.2.6.5 Pushbutton



#### Figure 44 Push button

#### Table 25 Push buttons

Designator	Description
S2	Mode switch: Push button to switch the debug circuit to CMSIS-DAP mode



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Figure 45 LEDs

Table 26LEDsDesignatorDescriptionD6Indicates the supply of the on-board debugger circuit, V<sub>BUS</sub> is activeD7Status of the KitProg3

## 3.2.6.7 Assembly option

Values for these optional additional placements must be determined depending on the application. The typical components and values can be found in the BOM in Chapter 3.3.3.



#### 3 In detail: Infineon door control evaluation board



#### Figure 46 Assembly options

#### Table 27Additional placements

Designator	Description
D8	Diode to supply debugger circuit from $V_{CC1}$
R10	Resistor to pull down SWDIO to GND
R11	Resistor to pull up TRAVEO <sup>™</sup> II XRES to V <sub>CC1</sub>
R27	Resistor to pull down P5LP_SIO_VREF signal to ground

#### 3.3 **Design Files**

#### Schematics Door control evaluation board 3.3.1





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Figure 48

Door control evaluation board, sheet 3









Door control evaluation board, sheet 4



Figure 50

Door control evaluation board, sheet 5







Door control evaluation board, sheet 6





Figure 52

Door control evaluation board, sheet 7



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Door control evaluation board layer 1 (top layer, signal)





Door control evaluation board layer 2 (middle layer, GND )







Door control evaluation board layer 3 (middle layer, signal)





Door control evaluation board layer 4 (bottom layer, power)



#### 3.3.3 Bill of material Door control evaluation board

Mostly automotive-qualified components are used for the Door control evaluation board. The complete bill of material (BOM) is shown below and includes non-mounted components.

Due to a shortage of components, some of the components listed might differ slightly from those Note: mounted.

#### Manufacturer Designator Description Quantity Manufacturer order number C1 CAP/ELCO/560uF/35V/20%/-/-55°C to 1 EEEFT1V561AP 105°C/10.30mm L X 10.30mm W X 10.50mm H/SMD/-C2, C11, C13, C15, C17, CAP/CERA/100nF/50V/10% / X7R 28 06035C104K4Z C19, C21, C23, C25, C26, (EIA) / -55°C to 125°C/0603(1608) / 2A C27, C44, C62, C63, C64, SMD / -C73, C74, C75, C76, C77, C78, C80, C81, C82, C85, C86, C88, C91 С3 CAP/ELCO/100uF/50V/20% / 1 EEEFTH101XAP Aluminiumelectrolytic / -55°C to 105°C/6.60mm L X 6.60mm W X 8.00mm H/SMD / -CAP/CERA/470nF/50V/10% / X7R C4 1 CGA3E3X7R1H4 (EIA) / -55°C to 125°C/0603/SMD / -74K080AE C5, C45 CAP/CERA/2.2uF/50V/10% / X7R (EIA) / 2 CGA5L3X7R1H2 -55°C to 125°C/1206/SMD / -25K160AB C6, C7, C8, C9, C10, C12, CAP/CERA/1uF/25V/10% / X7R (EIA) / 12 GCM188R71E10 C14, C16, C18, C20, C22, -55°C to 125°C/0603(1608) / SMD / -5KA64 C24 C28 CAP/CERA/10nF/50V/10% / X7R (EIA) / 1 06035C103K4Z -55°C to 125°C/0603(1608) / SMD / -2A CAP/CERA/4.7nF/50V/5% / X7R (EIA) / C29, C65 2 GCM188R71H4 -55°C to 125°C/0603(1608) / SMD / -72JA37 GCM188R71E22 C30, C32, C33, C34, C35, CAP/CERA/22nF/25V/5% / X7R (EIA) / 17 C36, C37, C38, C39, C40, -55°C to 125°C/0603(1608) / SMD / -3JA37 C41, C42, C43, C67, C68,

#### Table 28 **BOM Door control evaluation board**

Panasonic AVX Panasonic TDK Corporation TDK Corporation MuRata AVX MuRata MuRata C69, C70 C31, C46, C47 CAP/CERA/220nF/50V/10% / X7R 3 GCM188R71H2 MuRata (EIA) / -55°C to 125°C/0603(1608) / 24KA64 SMD / -CAP/CERA/560pF/50V/5% / X8G C48, C49, C50, C51 GCM1885G1H5 4 MuRata (Murata) / -55°C to 150°C/0603(1608) / 61JA16 SMD / -CAP/CERA/4.7uF/25V/10% / X6S (EIA) / C52, C79, C83, C84 4 GRT188C81E47 MuRata -55°C to 105°C/0603(1608) / SMD / -5KE13D (table continues...)



		• •••	Manufacturer	
Designator	Description	Quantity	order number	Manufacturer
C53	CAP/FILM/470uF/25V/20% / - / -55°C to 125°C/3.50mm C X 0.60mm W 8.50mm Dia X 13.50mm H/THT / -	1	477AVG025MFB J	Cornell Dubilier
C54, C56, C58, C60	CAP/CERA/47pF/50V/1% / X8G (Murata) / -55°C to 150°C/0603(1608) / SMD / -	4	GCM1885G1H4 70FA16	MuRata
C55, C57, C59, C61	CAP/CERA/33nF/50V/10% / X7R (EIA) / -55°C to 125°C/0603(1608) / SMD / -	4	GCM188R71H3 33KA55	MuRata
C66	CAP/CERA/1nF/50V/10% / X7R (EIA) / -55°C to 125°C/0603(1608) / SMD / -	1	GRM188R71H1 02KA01	MuRata
C71, C72, C87	CAP/CERA/10uF/10V/10% / X7T (EIA) / -55°C to 125°C/0603(1608) / SMD / -	3	ZRB18AD71A10 6KE01L	MuRata
C89, C90	CAP/CERA/10pF/50V/5% / C0G (EIA) / NP0 / -55°C to 125°C/0603(1608) / SMD / -	2	GCM1885C1H1 MuRata 00JA16	
C92	CAP/CERA/470nF/50V/10% / X5R (EIA) / -55°C to 85°C/0603(1608) / SMD / -	1	GRM188R61H4 74KA12	MuRata
D1, D16	3.0A Surface Mount Schottky Barrier Rectifier	2	B340AE-13	Diodes Incorporated
D2	Silicon Switching Diode	1	BAS21E6327HT SA1	Infineon Technologies
D3	Surface Mount Zener Diode	1	BZT52C12S-7-F	Diodes Incorporated
D4, D5, D6, D10	EXCELED Series Chip LED, Green, 560nm	4	SML- D12P8WT86C	ROHM Semiconductor s
D7, D11, D12, D13, D14, D15	Chip LED, 589nm, Yellow, Electronic Equipment Applications	6	LY Q396- P1Q2-36	OSRAM Opto Semiconductor s
D8	Surface Mount Schottky Power Rectifier,0.5A/20V	1	MBR0520LT1G	ON Semiconductor
D9	Silicon Schottky Diode	1	BAS70-02L	Infineon Technologies
L1 IND/FERR/60R/1A / - / -55°C to 125°C/ 100mR/0603(1608) / Inductor,Chip; 1.60mm L X 0.80mm W X 0.95mm H/SMD / -		1	BLM18PG600S N1D	MuRata

Table 28(continued) BOM Door control evaluation board



Table 28       (continued) BOM Door control evaluation board				
Designator	Description	Quantity	Manufacturer order number	Manufacturer
L2	IND/STD/100uH/150mA/50% / -55°C to 150°C/1.5R/1210(3225) / Filter SMD, 4-Leads, Molded Body 3.20mm L X 2.50mm W X 2.5mm H/SMD / -	1	ACT1210-101-2 P-TL00	TDK Corporation
Q1	OptiMOS <sup>™</sup> - power MOSFET for automotive applications, N-channel - Enhancement mode - Normal Level	1	IAUC120N04S6 N006	Infineon Technologies
Q2	General Purpose Transistors NPN Silicon	1	BC846ALT1G	ON Semiconductor
Q3	OptiMOS-5 N-Channel Enhancement Mode Power-Transistor, VDS 40V	1	IPZ40N04S5L-7 R4	Infineon Technologies
Q4	Standard level N-channel MOSFET,	1	BUK7Y7R6-40E X	Nexperia
Q5, Q6, Q7, Q8		4	IAUC60N04S6N 031H	Infineon Technologies
R1, R34	RES/STD/100k/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608) / SMD / -	2	CRCW0603100K FK	Vishay
R2, R3, R11, R27, R46, R66, R67, R68, R69, R70, R71, R74, R75	RES/STD/10k/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608) / SMD / -	13	CRCW060310K0 FKEA	Vishay
R4, R5, R28, R29	RES/STD/2.2k/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608) / SMD / -	4	CRCW06032K20 FK	Vishay
R6, R7, R76, R80, R81, R82, R83, R84	RES/STD/750R/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603/SMD / -	8	CRCW0603750 RFK	Vishay
R8	RES/STD/4.7k/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608) / SMD / -	1	CRCW06034K70 FK	Vishay
R9, R10	RES/STD/49.9k/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608) / SMD / -	2	CRCW060349K9 FK	Vishay
R12, R14, R16, R17, R18, R19, R20, R21, R22, R23, R25, R31, R33, R40, R41, R42, R43, R44, R45, R47, R49, R50, R51, R52, R53, R54, R55, R56, R57, R77, R86, R87, R88, R89, R90, R91, R92, R93	RES/STD/1k/100mW/1% / 100ppm/K / -55°C to 155°C/0603(1608) / SMD / -	38	RC0603FR-071K L	Yageo



Designator	Description	Quantity	Manufacturer order number	Manufacturer
R13, R24	RES/STD/15k/100mW/5% / 100ppm/K / -55°C to 155°C/ 0603(1608) / SMD / -	2	RC0603JR-0715 KL	Yageo
R15, R26	RES/STD/30k/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608) / SMD / -	2	CRCW060330K0 FK	Vishay
R30, R32, R72, R79	RES/STD/0R / - / 0% / - / -55°C to 155°C/0603(1608) / SMD / -	4	CRCW06030000 Z0EA	Vishay
R35	RES/PTC / - / 800mW / - / - / - / 1812/SMD / -	1	MF-MSMF030-2	Bourns
R36, R39	RES/STD/5.1k/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608) /SMD/-	2	CRCW06035K10 FK	Vishay
R37, R38	RES/STD/22R/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608)/SMD/ -	2	CRCW060322R 0FK	Vishay
R48	RES/STD/47R/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608)/SMD/ -	1	RC0603FR-0747 RL	Yageo
R58, R59, R60, R61, R62, R63, R64, R65	RES/STD/10R/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608)/SMD/ -	8	CRCW060310R 0FKEA	Vishay
R73, R78	RES/STD/60.4R/100mW/1% / 100ppm/K / -55°C to 155°C/ 0603(1608)/SMD / -	2	CRCW060360R 4FK	Vishay
R85	RES/VAR/10k/50mW/20% / - / -10°C to 70°C/THT, 2.5 mm pitch, 5 Pins, 11.80 mm L X 11.40 mm W X 15 mm H body/THT / -	1	RK09K1130A6S	ALPS
S1, S2, S3, S4, S5	Micro Miniature Push button Switch	5	FSM2JSMA	Tyco Electronics
U1	Programmable System-on-Chip (PSoC)	1	CY8C5868LTI- LP039	Cypress Semiconductor
U2	MOTIX <sup>™</sup> bridge	1		
U3	Bridge SBC Family, PLGM	1	TLE9562-3QXC	Infineon Technologies
U4	Family of TRAVEO™ T2G microcontrollers targeted at automotive systems	1	CYT2B95CACQ0 AZEGS	Infineon Technologies

## Table 28(continued) BOM Door control evaluation board



Designator	Description	Quantity	Manufacturer order number	Manufacturer
W1	Test Point, Compact, Surface Mount, Finish- Silver Plate	1	182-8848	RS Pro
X1, X2, X5, X19, X20, X35, X56, X57, X58, X59, X82, X83	Banana Test Connector, 4 mm, Socket, PCB Mount, 24 A, 60 VDC, Silver Plated Contacts, Red	12	5019	Keystone Electronics Corp.
Х3	Banana Test Connector, 4 mm, Socket, PCB Mount, 24 A, 60 VDC, Silver Plated Contacts, Black	1	24.243.1	Multicomp
X4	Jumper, 1x2-Positions, Pitch 2,54mm, Body 5, 08x2, 54mm, black, Au, with handle	1	24.243.2	Multicomp
X6, X7, X13, X14, X15, X16, X17, X25, X26, X27, X28, X29, X30, X37, X38, X39, X40, X41, X42, X43, X44, X45, X46, X47, X48, X49, X54, X71, X72, X73, X75, X77, X79, X80, X81, X84, X85, X93, X94, X95, X96, X97, X98	Through hole .025 SQ Post Header, 2.54mm pitch, 2 pin, vertical, single row	43	SNT-100-BK-G- H	Samtec
X8, X9, X64, X65, X67, X68, X74, X78	Through hole .025 SQ Post Header, 2.54mm pitch, 10 pin, vertical, double row	8	HTSW-102-07- G-S	Samtec
X10	Connector Header Surface Mount 12 position 0.050 (1.27mm)	1	TSW-105-05-L- D	Samtec
X11	WR-PHD 2.54 mm Pitch, 5Pins, THT Pin Header	1	FTSH-106-01-L- DV-K	Samtec
X12	SMT Micro Header, 1.27mm pitch, 10 pin, Vertical, Double Row, Keying Shroud with Alignment pin, DAP	1	61300511121	Wurth Elektronik
X18	WR-COM USB 3.1 Type C Horizontal, 20V Working Voltage and 5A Rated Current	1	FTSH-105-01-L- DV-K-A-TR	Samtec
X21	Through hole .025 SQ Post Header, 2.54mm pitch, 12 pin, vertical, double row	1	632723300011	Wurth Elektronik
X22	Through hole .025 SQ Post Header, 2.54mm pitch, 3 pin, vertical, single row	1	TSW-106-07-L- D	Samtec
X23, X24, X34, X53	Through hole .025 SQ Post Header, 2.54mm pitch, 16 pin, vertical, single row	4	HTSW-103-07- G-S	Samtec

#### Table 28 (continued) BOM Door control evaluation board



Designator	Description	Quantity	Manufacturer order number	Manufacturer
X31, X32	PCB Terminal Block, Nominal Current 13.5 A, Nominal Voltage 200V, 3.5mm Pitch, 14 Pins	2	TSW-116-07-L-S	Samtec
X33	Through hole .025 SQ Post Header,12.54mm pitch, 26 pin, vertical, double row1		1751361	Phoenix Contact
X36	Through hole .025 SQ Post Header,1TSW-1132.54mm pitch, 14 pin, vertical, singleDrow		TSW-113-07-L- D	Samtec
X50	Terminal Block, 4 Pole, 5mm Pitch, Low Profile Screw Terminal	al Block, 4 Pole, 5mm Pitch, 1 TSW-114-07-L-S Profile Screw Terminal		Samtec
X51, X69	SMT, .025 Shrouded SQ POST IDC Headers , 2.54mm pitch, 16-pin Vertical, Double row	2	CTB5000/4 Camden Bo	
X52	PCB terminal block, nominal current: 16 A, rated voltage : 400 V, 2 Positions	1	HTST-108-01-L- DV	Samtec
X66, X70	Through hole .025 SQ Post Header, 2.54mm pitch, 10 pin, vertical, double row	2	1792863	Phoenix Contact
X76	Through hole .025 SQ Post Header, 2.54mm pitch, 4 pin, vertical, single row	1	TSW-105-08-G- D	
X86	Through hole .025 SQ Post Header, 2.54mm pitch, 20 pin, vertical, double row	1	TSW-104-07-L-S Samtec	
X87, X88	Through hole .025 SQ Post Header, 2.54mm pitch, 6 pin, vertical, single row	2	TSW-110-07-L- D	Samtec
X89, X92	Through hole .025 SQ Post Header, 2.54mm pitch, 7 pin, vertical, single row	ost Header, 2 TSW-106-07-L-S Samtec tical, single		Samtec
X91	Surface Mount Compact Crystal Unit	1	TSW-107-07-L-S	Samtec
Y1	CAP/ELCO/560uF/35V/20%/-/-55°C to 105°C/10.30mm L X 10.30mm W X 10.50mm H/SMD/-	1	NX3225GA-16.0 00M-STD- CRG-2	Nihon Dempa Kogyo



#### 4 Additional information

## 4 Additional information

- IAR Embedded Workbench for ARM: https://www.iar.com/products/architectures/arm/iar-embedded-workbench-for-arm/
- Infineon developer center: https://softwaretools.infineon.com/welcome
- Infineon MOTIX<sup>™</sup> Bridge TLE9166EQ datasheet. Refer to product page: https://www.infineon.com/cms/de/ product/power/motor-control-ics/brushed-dc-motor-control-ics/multi-half-bridge-ics/tle9166eq/
- Infineon MOTIX<sup>™</sup> TLE9562-3QX datasheet: https://www.infineon.com/dgdl/Infineon-TLE9562-3QX-DataSheet-v01\_00-EN.pdf?fileId=5546d4627883d7e00178ca35b1603873
- Infineon PSoC<sup>®</sup> 5LP: CY8C58LP Family Datasheet: https://www.infineon.com/dgdl/Infineon-PSOC(R)\_5LP\_CY8C52LP\_FAMILY\_DATASHEET\_PROGRAMMABLE\_SYSTEM-ON-CHIP\_(PSOC(R))-DataSheetv16\_00-EN.pdf?fileId=8ac78c8c7d0d8da4017d0ec56e153b1a
- Infineon TRAVEO<sup>™</sup> T2G 32-bit Automotive MCU: https://www.infineon.com/dgdl/Infineon-TRAVEO\_T2G\_CYT2B9\_Series-DataSheet-v10\_00-EN.pdf?fileId=5546d462749a7c2d01749d90a2e34dbc

#### Glossary

## Glossary

### API

application programming interface (API) A set of defined rules that enables various software components to communicate with each other.

#### CAN

controller area network (CAN)

### GPIO

general purpose input output (GPIO)

### GUI

*graphical user interface (GUI)* An interface that enables users to interact with electronic devices through icons and visual indicators.

### IC

*integrated circuit (IC)* A miniature electronic circuit built on the surface of a thin substrate of a semiconductor material.

#### LED

*light-emitting diode (LED)* A semiconductor circuit that emits light when activated.

#### LIN

local interconnect network (LIN)

#### PCB

#### printed circuit board (PCB)

A board that mechanically supports and electrically connects electronic components using conductive tracks, pads, and other features etched from copper sheets laminated onto a non-conductive substrate.

#### PWM

pulse-width modulation (PWM)

A technique to encode an analog value into the duty cycle of a pulsing signal with arbitrary amplitude.

#### SPI

#### serial peripheral interface (SPI)

A synchronous serial communication interface specification used for inter-chip communication, primarily in embedded systems.

#### SWD

#### serial wire debug (SWD)

A communication interface and protocol used for debugging and programming embedded systems, particularly microcontrollers and other integrated circuits.





5 Abbreviations

## 5 Abbreviations

Table 29 Abbreviations		
Abbreviation	Meaning	
A	Ampere	
BDC	Brushed direct current	
ВОМ	Bill of material	
СМ	Current measurement	
CMSIS	Common microcontroller software interface standard	
СОМ	Communication	
DAP	Debug access port	
EC	Electrochromatic	
EWARM	Embedded workbench ARM	
GH	Gate-high	
GND	Ground	
НВ	Half bridge	
HS	High-side	
LS	Low-side	
PC	Personal computer	
SDL	Sample driver library	
ТВ	Tracebox	
UART	Universal asynchronous receiver transmitter	
ulO	Universal input output	
USB-C	Universal serial bus type-c	
V	Voltage	
V <sub>cc</sub>	Voltage common collector	
Vs	Supply voltage	
V <sub>BAT</sub>	Battery voltage	
WK	Wake	



**Revision history** 

## **Revision history**

Document version	Date of release	Description of changes
Rev. 2.00	2024-10-15	<ul> <li>Document updated; content restructured; chapters on system offering included</li> </ul>
		Document renamed from "Door control evaluation board user guide"
Rev. 1.10	2024-03-01	Chapters Implementation of an Device Driver into IAR Embedded     Workbench and Application software added
		Typos corrected
Rev. 1.00	2023-08-11	Initial release

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