

CP2725AC48TEZ – FB2 Compact Power Line High Efficiency Rectifier

Input: 100 – 120/220 – 240V_{AC}; Output: 2725W @ 52V_{DC}; 5 V_{DC} @ 4W



The CP2725AC48TEZ-FB2 Rectifier has an extremely wide programmable output voltage capability and fold-back current limiting features. High-density front-to-back airflow is designed for minimal space utilization and is highly expandable for future growth. This custom rectifier incorporates both RS485 and dual-redundant I²C communications busses that allow it to be used in a broad range of applications. Feature set flexibility makes this rectifier an excellent choice for a set of applications requiring operation over a wide output voltage range.

Applications

• Wide band power amplifiers

Features

- Efficiency 95%
- Compact 1RU form factor providing 30 W/in³
- 2725W @ 52V from nominal 220 240V_{AC}
- 1200W from nominal 100 120V_{AC} (for Vo > 30V_{DC})
- Output voltage programmable from 18V 58V_{DC}
- PMBus compliant dual I²C and RS485 serial busses
- Power factor correction (meets EN/IEC 61000-3-2 and EN
 - 60555-2 requirements)
- Output overvoltage and overload protection
- AC Input overvoltage and undervoltage protection
- Over temperature warning and protection

- Redundant, parallel operation with active load sharing
- Redundant +5V Aux power
- Remote ON/OFF
- Hot insertion/removal (hot plug)
- Four front panel LED indicators
- UL* Recognized to UL60950-1, CAN/ CSA⁺ C22.2 No. 60950-1, and VDE⁺ 0805-1 Licensed to IEC60950-1
- CE mark meets 2006/95/EC directive[§]
- Internally controlled Variable speed fan
- RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863
- Special Foldback Curve

* UL is a registered trademark of Underwriters Laboratories, Inc.

† CSA is a registered trademark of Canadian Standards Association.

§ This product is intended for integration into end – user equipment. All the required procedures for CE marking of end – user equipment should be followed. (The CE mark is placed on selected products.)

** ISO is a registered trademark of the International Organization of Standards.

 $[\]ddagger$ VDE is a trademark of Verband Deutscher Elektrotechniker e.V.

Technical Specifications



Electrical Specifications

Input

| Pa | rameter | Min | Тур | Max | Units | Notes |
|-------------------------|---|------------------|----------------------------|-------------------------|-----------------|--|
| Low – I | peration operation oltage Range line Configuration line Configuration | 90 200 305 | 100, 110, 120 220 – 240 | 90 200 140 265 | V _{AC} | |
| Input Freque | ency | 47 | | 66 | Hz | |
| Input Current | | | | 12 13.5 | | At 110 V _{AC} At 240 V _{AC} |
| Inrush Trans | Inrush Transient | | 25 | 30 | Apk | Measured at 25°C for all line conditions; does not include X – Capacitors charging. |
| Input Leakag | ge Current | | 2.5 | 3.5 | mΑ | Measured at 265V _{AC} , 60Hz |
| Power Facto | | 0.96 | 0.98 | | | From 50% to 100% (2725W @ HL, 1200W @ LL) load |
| | 20 – 90% of FL | 93 | 95 | | % | With or'ing function, aux 5V output, dual/redundant |
| Efficiency ¹ | >38V | 85 | | | % | l²C and RS485 communications and POE isolation >20% load Test condition: input; 240V _{AC} , 60hz, output; 52V _{DC} |
| Holdup | | | 20 30 | | ms | 48V _{DC} , Measurement starts at zero crossing of the ac voltage, and voltage decayed to 40V. For loads below 1200W. |
| Ride thru | | 1/2 | 1 | | cycle | Tested at nominal 115V and 230V. Complies to CISPR24 standards |
| Power Fail W | /arning ² | 3 | 5 | | ms | Alarm issued via PFW signal going LO 5 ms prior to the main output decaying below 40V _{DC} . |

Main Output

| Parameter | Min | Тур | Max | Units | Notes |
|---|--------------|---------------|------------|--|--|
| Output Power | 1200 2725 | | | W | Above $30V_{DC}$ from nominal $90 - 120V_{AC}$ upto 55° C. Above $52V_{DC}$ from nominal $200 - 265V_{AC}$ upto 55° C |
| Default Set point | | 48 | | V _{DC} | Output floats with respect to frame ground. |
| Overall Regulation ³ | -1 -2 | | +1 +2 | % | 0 – 45°C, minimum load 2.5A > 45°C |
| Output Voltage Set Range | 18 | | 58 | V _{DC} | Analog margining and RS485 |
| Output voltage set Range | 18 | | 58 | V _{DC} | Set by I ² C |
| Output current | 1 1 | | 23 52.4 | А | 1200W @ 52V @ 90-120V _{AC} . 2725W @ 52V @ 200-240V _{AC} . |
| Current Share V₀>42V V₀<42V | -5 -10 | | 5 10 | %FL | Compared to the average output current delivered by a set of Rectifiers. Loads > 50% FL |
| Output Ripple RMS (5Hz to 20MHz) Peak-to-Peak (5Hz to 20MHz) | | 60 | 100 500 | mV _{rms} mV _{p-p} | Measured with 20MHz bandwidth under any condition of loading. Minimum load is 1A |
| External Bulk Load Capacitance | 0 | | 5000 | μF | External capacitance can be increased but the rectifier will not meet its turn – ON rise time requirement. |
| Turn – on Delay Rise Time – Standard (PMBus) – Telecom (RS485) ⁴ Overshoot | | 5 100 5 | 2 | s ms s % | Monotonic Turn_On from 30% to 100% of Vnom above - 5°C operation. Monotonic Turn_On from 60% to 100% of Vnom below -5°C operation. |
| Load Step Response ΔΙ ΔV Response Time | | 2.0 2 | 50 | %FL V _{DC} ms | DI/Dt slew rate 1A/µs. Settling time to within regulation requirements. Minimum load of 2.5 amperes required. |

 $^1\!At$ 52V $_{DC}$, 240V $_{rms}$ and 25°C.

²Internal protection circuits may override the PFW signal and may trigger an immediate shutdown.

³Includes all variations due to specified load range, drift, and environmental conditions.

⁴Below -5°C, the rise time is approximately 5 minutes to protect the bulk capacitors.



Main Output (continued)

| | | Param | | | | | Min | Тур | o Ma | | nits | | | | lotes | | | |
|------------------------|-----------------|-----------|----------|----------------------|------------------|---------|----------------------|-----------------|---------------------|--------------|----------|-----------------|----------|----------|---------|---------|--------|------|
| | | r limit – | _ | | | | 2725 | | | | W | | | | | | | |
| | | r limit – | | | | | 1200 | | | | W | | | | | | | |
| | The o | /erload | currer | nt limi [.] | t three | shold s | should | | | | e the lo | oad er | nvelop | e shov | vn her | e | | |
| | | | | | | | Power curve | | | urve | 2 | | | | | | | |
| | | Vo(V) | 18 | 26 | 30 | 32 | 36 | 40 | 44 | 48 | 49 | 50 | 51 | 52 | 54 | 56 | 58 | |
| | | lo(A) | 20.7 | 35.1 | 42.3 | 43.4 | 45.8 | 48.2 | 50.6 | 52.4 | 52.4 | 52.4 | 52.4 | 52.4 | 50.5 | 48.7 | 47.0 | |
| | | | Vo | (V) | | | | | | | | | | | | | | |
| | | | 60 58 | | | 1 | 1 | | | | | | | | 1 | | | |
| | | | 55 | | | | | \ | | | | | | | | | | |
| | | | | | | | | \mathbf{X} | | | | | | | | | | |
| | | | 50 | | ÷ | | | | | | | | | | | | | |
| | | | | | | | | | \mathbf{N} | | | | | | | | | |
| Permissible | | | 45 | · | † | 1 | <u>.</u> | | \mathbf{X} | | | | 1 | | | | | |
| Load Boundary | | | 40 | l | | | | | N | <u> </u> | | | | | | | | |
| Boundary | | | | | | - | | | | \mathbf{i} | | | | | | | | |
| | | | 35 | | ÷ | ÷ | | | | > | · | / | | | | | | |
| | | | 20 | | | | | | | | | | | | | | | |
| | | | 30 | | | 1 | | | | | | | | | | | | |
| | | | 25 | | ļ | ļ | | | | | | | | | | | | |
| | | | | | | | | | | | | | | ne power | 1 | | | |
| | | | 20 | | | + | | | | | | | - High B | ne powe | curve | | | |
| | | | | | | | | | | | | | | | | Io(A) | | |
| | | | 15 | 0 | 1 | .0 | 20 | 0 23 | 30 |) | 40 |) | 50 | 52.4 | 60 | | | |
| | | | | | | | | | | | | | | | | | | _ |
| | | Vo(V) | 18 | 26 | 30 | 32 | 36 | 40 | 44 | 48 | 49 | 50 | 51 | 52 | 54 | 56 | 58 | |
| | | lo(A) | 20.7 | | 40.0 | 37.5 | • | | 27.3 | - | - | 24.0 | 23.5 | · | 22.2 | • | | |
| | | act tern | | | | | | | | | | | | | | | rol | |
| | | ace which | | | | | | | | | | | | | | | | |
| | Syster Up | n Powe | | | | | to be p | | | | | | | | | | p. Uni | ts |
| Over – voltag | | | SHC | ulu st | ayin c | Jurren | t limit [·] | ог ар | | lately | 20 Sec | onus. | to gua | Iante | eresta | II L. | | |
| Delayed | | | | | | 6 | 50 | V_{DC} | 200 | Omsec | : delay | ed shu | utdow | n to b | e impl | emen | ted. | |
| Immed | iate La | tchoff | | | | | 55 | V_{DC} | Inst | tantar | neous | shutdo | own a | bove t | his po | int. | | |
| | | | | | | | empts | may | be im | pleme | ented | within | a one | e min | ute wi | ndow | prior | tc |
| | | | | latch | ed shu | utdow | 'n | | | | | | | | | | | |
| Over – temp | eratur | e | | | | | | | Im | oleme | nted p | orior to | o com | mence | ement | ofan | от | |
| Warning | | C | | | 5 | 5 | | °C | | | n | | 00111 | | | oran | 01 | |
| - | | | | | | | | | | | | | | | | | | |
| Shutdown | | | | | 2 | 0 | | °C | | | e max | imum | rating | g of th | e devi | ce beir | ng | |
| | vorable | 2 | | Tom | oratu | uro by | steres | is of | | vimat | | 1° C n | ovida | d hot | woon | chute | lown | 2 |
| $\lambda u to - rocci$ | | - | | | | пепу | SUCIUS | 5 01 | appio | viiliare | eiy iC | , c pi | ovide | u pet | ween | Shutt | | d |
| Auto – recov | | | | resta | rt. | | | | | | | | | | | | | |
| Nuto – recov | | s that e | xceed | resta the ei | | be by 5 | 5% will | hiccur | o cont | inuou | sly at a | freau | lency | ofapp | roxim | ately c | nce e | ٩Ve |
| | event For vo | ltage se | et – po | the ei ints be | nvelop elow 4 | 2V, a t | rackin | g Unḋ | er Vol [.] | tage s | hutdo | wn oc | cursa | t 2 vol | ts belo | w set | -point | t. l |

Auxiliary Output

| Parameter | Min | Тур | Max | Units | Notes |
|-------------------------|-------|-----|------|---------------------|---------------------------------|
| Output Voltage Setpoint | | 5 | | V _{DC} | |
| Output Current | 0.005 | | 0.75 | A | |
| Overall Regulation | -10 | | +5 | % | Within ±5% when load is < 0.5A. |
| Ripple and Noise | | 50 | 100 | mV _{pk-pk} | 20MHz bandwidth |
| Over – voltage Clamp | | | 7 | V _{DC} | |
| Over – current Limit | 110 | | 175 | %FL | |

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Environmental, EMC, Reliability Specifications

Environmental

| Parameter | Min | Тур | Max | Units | Notes | | | |
|---|-----------------------------|--|---------------|--|---|--|--|--|
| Ambient Temperature Operating Derating | -40 ⁵ | יקע ו ו | 55 2 | °C °C | Air inlet from sea level to 5,000 feet. Per 1,000 feet above 5,000 feet. | | | |
| Storage Temperature | -40 | | 85 | °C | | | | |
| Humidity | 5 | | 95 | % | Relative humidity, non – condensing | | | |
| Altitude | -60 -200 | | 4000 13000 | m ft | For operation above 2500m (5000 ft.), maximum operating temperature is derated by 2°C per 305m (1000 ft.). | | | |
| Shock and Vibration | | | | | IPC9592 sections 5.2.8 – 5.2.13 | | | |
| Earthquake Rating | 4 | | | Zone | Per Telcordia GR-63-CORE, all floors, when installed in CP Shelf. | | | |
| Acoustic Noise | | 55 | | dBA | Noise is proportional to fan speed, load and ambient temperature. | | | |
| Harmonic Emissions | Per EN/I | EC61000-3 | -2 | | | | | |
| Radiated Emissions ⁶ | Exceeds | FCC and C | ISPR22 (E | EN55022 | ?) – Class A by a 6dB margin | | | |
| Conducted Emissions – ac | Class A 1 | xceeds FCC and CISPR22 (EN55022) :lass A Telcordia GR-1089-CORE - Class A y a 6dB margin | | | | | | |
| ESD | Error fre | Error free per EN/IEC 61000-4-2 Level 3 (6 kV contact discharge, 8 kV air discharge). | | | | | | |
| Radiated Immunity | Error fre | e per EN/IE | C 61000- | 4-3 Leve | el 3 (10 V/m). | | | |
| Electrical Fast Transient Burst | Error fre | e per EN/IE | C 61000- | 4-4 Leve | el 3 (2 kV, 5 kHz repetition rate) | | | |
| Lightning Surge, Error Free Damage Free | | | | | non mode, 2 kV differential mode). and differential mode) | | | |
| Line sags and interruptions | for 2 sec | | utput sha | ll stay al | erruption or 25% sag (115V, 230V – nominal for UUT) bove 40V _{DC} at full load. [Note: An input sag below 80V]. | | | |
| Conducted Immunity | Error fre | e per EN/IE | C 61000- | 4-6 Leve | el 3 (10V _{rms}). | | | |
| Reliability (calculated) | | 450,000 | | Hours | At ambient of 25°C at full load per Telcordia SR-332, issue 2, Reliability Prediction for Electronic Equipment, Method I Case III. | | | |
| Isolation | | | | | | | | |
| Input – Chassis/Signals Input – Output Output – Chassis Output – Chassis/Signals | 1500 3000 500 2250 | | | V _{rms} V _{rms} V _{DC} V _{DC} | Per EN60950. Consult factory for testing to this requirement Internal Lineage standard, GR_947 POE compliant Rectifier, Per IEEE802.3. | | | |
| Service Life | | 10 | | Years | 25°C ambient, full load excluding fans. | | | |

⁵Designed to start and work at an ambient as low as -40°C, but may not meet operational limits until above -5°C

⁶Radiated emissions compliance was met using a Lineage Power shelf. This shelf includes output common and differential mode capacitors that assist in meeting compliance.



Control and Status

The Rectifier provides three means for monitor/control: analog, PMBus™, or the OmniOn Galaxy – based RS485 protocol.

Details of analog control and the PMBus[™] based protocol are provided in this data sheet. OmniOn will provide separate application notes on the Galaxy RS485 based protocol for users to interface to the rectifier. Contact your local OmniOn representative for details.

Signal Reference

Unless otherwise noted, all signals are referenced to

Logic_GRD. See the Signal Definitions Table at the end of this document for further description of all the signals.

Logic_GRD is isolated from the main output of the power supply for PMBus communications. Communications and the 5V standby output are not connected to main power return (Vout(-)) and can be tied to the system digital ground point selected by the user. (Note that RS485 communications is referenced to Vout(-), main power return of the power supply).

Logic_GRD is capacitively coupled to Frame_GRD inside the power supply. The maximum voltage differential between Logic_GRD and Frame_GRD should be less than 100V_{DC}.

Control Signals

Enable: Controls the main 48V_{DC} output when either analog control or PMBus protocols are selected, as configured by the Protocol pin. This pin must be pulled low to turn **ON** the rectifier. The rectifier will turn **OFF** if either the **Enable** or the **ON/OFF** pin is released. This signal is referenced to Logic_GRD. In RS485 mode this pin is ignored.

ON/OFF: This is a shorter pin utilized for hot – plug applications to ensure that the rectifier turns **OFF** before the power pins are disengaged. It also ensures that the rectifier turns **ON** only after the power pins have been engaged. Must be connected to V_OUT (-) for the rectifier to be ON.

Margining: The $48V_{DC}$ output can be adjusted between $18 - 58V_{DC}$ by a control voltage on the Margin pin. This control voltage can be generated either from an external voltage source, or by forming a voltage divider between 3.3V and Logic_GRD, as shown in Fig. 1. The power supply includes the high side pull-up $10k\Omega$ resistor to $3.3V_{DC}$. Connecting a resistor between the margin pin and Logic_GRD will complete the divider.

An open circuit, or a voltage level > $3.0V_{DC}$, on this pin sets the main output to the factory default setting of $48V_{DC}$.

Hardware margining is only effective until software commanded output voltage changes are not executed. Software commanded output voltage settings permanently override the hardware margin setting until power to the internal controller is interrupted, for example if input power or bias power is recycled.

The controller always restarts into its default configuration, programmed to set the output as instructed by the margin pin. Subsequent software commanded settings permanently override the margin pin. Adding a resistor between margin and Vout(-) is an ideal way of changing the factory set point of the rectifier to whatever voltage level is desired by the user.

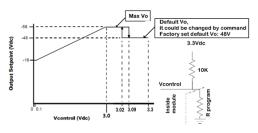


Figure 1. Diagram showing how output can be margined using Vcontrol adjustment.

Module Present Signal: This signal has dual functionality. It can be used to alert the system when a rectifier is inserted. A 500 Ω resistor is present in series between this signal and Logic_GRD. An external pull – up should not raise the voltage on the pin above 0.25V_{DC}. When the voltage on this pin exceeds $1V_{DC}$, the write_protect feature of the EEPROM is enabled.



8V_INT: Single wire connection between modules, Provides bias to the DSP of an unpowered module.

Reset: This is a PCA9541 multiplexer function utilized during PMBus communications. If momentarily grounded (Logic_GRD), the multiplexer would reset itself.

Protocol: Establishes the communications mode of the rectifier, between analog/PMBus and RS485 modes. For RS485, connect a $10k\Omega$ pull – down resistor from this pin to V_OUT(-). For analog/PMBus leave the pin open. Do not tie this signal pin to V_OUT(-) because that connection configures the internal DSP into a reprogrammed state.

Unit Address: Each module has an internal $10k\Omega$ resistor pulled up between unit_address and $3.3V_{DC}$. A resistor between unit_address and Vout(-) sets the appropriate unit address.

. .

| | | | I ² C ad | dress |
|-----------|-----------------------|--------------------|---------------------|-------|
| Rectifier | Resistor Value | Nominal voltage | Al | A0 |
| 1 | 30K | 2.477 | 0 | 0 |
| 2 | 14K | 1.925 | 0 | 1 |
| 3 | 6K | 1.243 | 1 | 0 |
| 4 | 2.5K | 0.654 | 1 | 1 |

Shelf Address: By applying the required voltage between the shelf address pin and Vout(-), up to 8 different shelves and so up to 32 different modules can be addressed using either the PMBus or OmniOn Galaxy based RS485 protocol.

PMBus addressing is limited to a maximum of 8 modules and so the software decodes the shelf address setting into either shelf 0 or shelf 1 in PMBus applications. If more than two shelves are paralleled, the user must separate the I²C lines so that address conflicts do not occur.

| Shelf_address | 1 | 2 | 3 | 4 |
|------------------|------|------|------|------|
| Maximum voltage | 3.45 | 2.97 | 2.56 | 2.14 |
| Nominal voltage | 3.30 | 2.86 | 2.4 | 1.96 |
| Minimum voltage | 3.00 | 2.60 | 2.18 | 1.73 |
| Address bit – A2 | 0 | 1 | 0 | 1 |

| Shelf_address | 5 | 6 | 7 | 8 |
|------------------|------|------|------|------|
| Maximum voltage | 1.70 | 1.25 | 0.80 | 0.25 |
| Nominal voltage | 1.50 | 1.10 | 0.60 | 0.01 |
| Minimum voltage | 1.29 | 0.84 | 0.30 | 0 |
| Address bit – A2 | 0 | 1 | 0 | 1 |

Status Signals

Power Capacity: A HI on this pin indicates that the rectifier delivers high line rated output power; a LO indicates that the rectifier is connected to low line configured for 1200W operation.

Power Fail Warning: This signal is HI when the main output is being delivered and goes LO for the duration listed in this data sheet prior to the output decaying below the listed voltage level.

Fault: This signal goes LO for any failure that requires rectifier replacement. These faults may be due to:

- Fan failure
- Over temperature warning
- Over temperature shutdown
- Over voltage shutdown
- Internal Rectifier Fault

Digital Feature Descriptions

PMBus™ compliance: The power supply is fully compliant to the Power Management Bus (PMBus™) rev1.2 requirements with the following exceptions:

The power supply continuously updates its STATUS and ALARM registers to the latest state in order to capture the 'present' state of the power supply. There are a number of indicators, such as those indicating a communications fault (PEC error, data error) that do not get cleared until specifically instructed by the host controller sending a clear_faults command. A 'bit' indicator notifies the user if the STATUS and ALARM registers changed since the last 'read' by the host controller.

For example, if a voltage surge causes a momentary shutdown for over voltage the power supply will automatically restart if the 'auto_restart' feature is invoked. During the momentary shutdown the power supply issues an Alert# indicating to the system controller that a status change has occurred. If the system controller reads back the STATUS and ALARM registers while the power supply is shut down it will get the correct fault condition. However, inquiry of the state of the power supply after the restart event would indicate that the power supply is functioning correctly. The STATUS and ALARM indicators did not freeze at the original shutdown state and so the reason for the original Alert# is erased. The restart 'bit' would be set to indicate that an event has occurred.



The power supply also clears the STATUS and ALARM registers after a successful read back of the information in these registers, with the exception of communications error alarms. This automated process improves communications efficiency since the host controller does not have to issue another clear_faults command to clear these registers.

Dual, redundant buses: Two independent I²C lines provide true communications bus redundancy and allow two independent controllers to sequentially control the power supply. For example, a short or an open connection in one of the I²C lines does not affect communications capability on the other I²C line. Failure of a 'master' controller does not affect the power supplies and the second 'master' can take over control at any time.

Using the PCA9541 multiplexer: Transition between the two I²C lines is provided by the industry standard PCA9541 I²C master selector multiplexer. Option 01 of the device code is supplied which, upon start-up, connects channel 0 to the power supply. In this fashion applications using only a single I²C line can immediately start talking across the bus without first requiring to reconfigure the multiplexer.

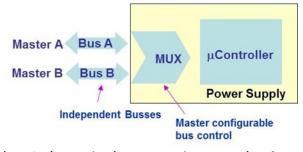


Figure 2: Diagram showing conceptual representation of the dual I²C bus system.

Control can be taken over at any time by a specific 'master' even during data transmission to the other 'master'. The 'master' needs to be able to handle incomplete transmissions in the multi-master environment in case switching should commence in the middle of data transmission. **Master/Slave:** The 'host controller' is always the MASTER. Power supplies are always SLAVES. SLAVES cannot initiate communications or toggle the Clock. SLAVES also must respond expeditiously at the command of the MASTER as required by the clock pulses generated by the MASTER.

Clock stretching: The power supply may initiate clock stretching if it is busy. The 'slave' may keep the clock LO until it is ready to receive instructions. The maximum clock stretch interval is 25ms.

The host needs to refrain from issuing the next clock signal until the clock is released, or it needs to delay the next clock pulse beyond the clock stretch interval of the power supply.

Note that clock stretching occurs after the 9^{th} (ACK) bit, the exception being the START command.

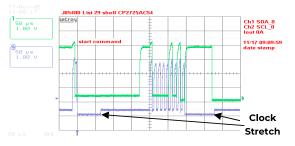


Figure 3: Example waveforms showing clock stretching.

Communications speed: Both 100kHz and 400kHz clock rates are supported. The power supplies default to the 100kHz clock rate.

Packet Error Checking: The power supply will not respond to commands without the trailing PEC. The integrity of communications is compromised if packet error correction is not employed. There are many functional features, including turning OFF the main output, that require validation to ensure that the correct command is executed.

PEC is a CRC – 8 error – checking byte, based on the polynomial $C(x) = x^8 + x^2 + x + 1$, in compliance with PMBusTM requirements. The calculation is based in all message bytes, including the originating write address and command bytes preceding read instructions. The PEC is appended to the message by the device that supplied the last byte.



SMBusAlert#: The power supply can issue SMBAlert# driven from either its internal micro controller (μ C) or from the PCA9541 I²C bus master selector. That is, the SMBAlert# signal of the internal μ C funnels through the PCA9541 master selector that buffers the SMBAlert# signal and splits the signal to the two SMBAlert# signal pins exiting the power supply. In addition, the PCA9541 signals its own SMBAlert# request to either of the two SMBAlert# signals when required.

Non-supported commands: Non supported commands are flagged by setting the appropriate STATUS bit and issuing an SMBAlert# to the 'host' controller.

Data out-of-range: The power supply validates data settings and sets the data out-of-range bit and SMBAlert# if the data is not within acceptable range.

SMBAlert# triggered by the µC: The µC driven SMBAlert# signal informs the 'master/host' controller that either a STATE or ALARM change has occurred. Normally this signal is HI. The signal will change to its LO level if the power supply has changed states and the signal will be latched LO until the power supply receives a 'clear' instruction as outlined below. If the alarm state is still present after the 'clear_faults' command has been received, then the signal will revert back into its LO level again and will latch until a subsequent 'clear' signal is received from the host controller.

The signal will be triggered for any state change, including the following conditions;

- V_{IN} under or over voltage
- V_{out} under or over voltage
- I_{OUT} over current
- Over Temperature warning or fault
- Fan Failure
- Communication error
- PEC error
- Invalid command
- Internal faults

The power supply will clear the SMBusAlert# signal (release the signal to its HI state) upon the following events:

- Completion of a 'read_status' instruction
- Receiving a CLEAR_FAULTS command
- The main output recycled (turned OFF and then ON) via the ENABLE signal pin
- The main output recycled (turned OFF and then ON) by the OPERATION command

SMBAlert# triggered by the PCA9541: If clearing the Alert# signal via the clear_faults or read back fails, then reading back the Alert# status of the PCA9541 will be necessary followed by clearing of the PCA9541 Alert#.

The PCA9541 can issue an Alert# even when single bus operation is selected where the bus master selector has not been used or addressed. This may occur because the default state of the PCA9541/01 integrated circuit issues Alert# to both I²C lines for all possible transitioning states of the device. For example, a RESET caused by a glitch would cause the Alert# to be active.

If the PCA9541 is not going to be used in a specific application (such as when only a single I²C line is utilized), it is imperative that interrupts from the PCA9541 are de-activated by the host controller. To deactivate the interrupt registers the PCA9541 the 'master' needs to address the PCA9541 in the 'write' mode, the interrupt enable (IE) register needs to be accessed and the interrupt masks have to be set to HI '1'. (Note: do not mask bit 0 which transmits Alert# from the power supply). This command setting the interrupt enable register of the PCA9541 is shown below;

| Star | t | | U | nit Ad | dress | | | ACK | |
|--------------|---|---|----|--------|-------|-------|-----|-----|----|
| 1 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | 1 |
| S | 1 | 1 | 1 | 0 | A2 | A1 | A0 | 0 | А |
| Command Code | | | de | ACK | IE | Regis | ter | St | ор |
| | 0 | | | 1 | | 0 | | | |

| 8 | 1 | 8 | |
|------|---|------|---|
| 0x00 | A | 0x0E | Р |
| | | | |

There are two independent interrupt enable (IE) registers, one for each controller channel (I²C-0 and I²C-1). The interrupt register of each channel needs to be configured independently. That is, channel I²C-0 cannot configure the IE register of I²C-1 or vise-versa.



This command has to be initiated to the PC9541 only once after application of power to the device. However, every time a restart occurs the PCA9541 has to be reconfigured since its default state is to issue Alert# for changes to its internal status.

If the application did not configure the interrupt enable register the Alert# line can be cleared (deactivated), if it has been activated by the PCA9541, by reading back the data from the interrupt status registers (Istat).

Refer to the PCA9541 data sheet for further information on how to communicate to the PCA9541 multiplexer.

Please note that the PCA9541 does not support Packet Error Checking (PEC).

Re-initialization: The I²C code is programmed to reinitialize if no activity is detected on the bus for 5 seconds. Re-initialization is designed to guarantee that the I²C μ Controller does not hang up the bus. Although this rate is longer than the timing requirements specified in the SMBus specification, It had to be extended in order to ensure that a re-initialization would not occur under normal transmission rates. During the few μ seconds required to accomplish reinitialization the I²C μ Controller may not recognize a command sent to it. (i.e. a start condition).

Global broadcast: This is a powerful command because it can instruct all power supplies to respond simultaneously in one command. But it does have a serious disadvantage. Only a single power supply needs to pull down the ninth acknowledge bit. To be certain that each power supply responded to the global instruction, a READ instruction should be executed to each power supply to verify that the command properly executed. The GLOBAL BROADCAST command should only be executed for write instructions to slave devices.

Note: The PCA9541 I²C master selector does not respond to the GLOBAL BROADCAST command.

Read back delay: The power supply issues the SMBAlert # notification as soon as the first state change occurred. During an event a number of different states can be transitioned to before the final event occurs. If a read back is implemented rapidly by the host a successive SMBAlert# could be triggered by the transitioning state of the power supply. In order to avoid successive SMBAlert# s and read back and also to avoid reading a transitioning state, it is prudent to wait more than 2 seconds after the receipt of an SMBAlert# before executing a read back. This delay will ensure that only the final state of the power supply is captured.

Successive read backs: Successive read backs to the power supply should not be attempted at intervals faster than every one second. This time interval is sufficient for the internal processors to update their data base so that successive reads provide fresh data.

Device ID: Address bits A2, A1, A0 set the specific address of the power supply. The least significant bit x (LSB) of the address byte configures write [0] or read [1] events. In a **write** command the system instructs the power supply. In a **read** command information is being accessed from the power supply.

| | Address Bit | | | | | | | |
|------------------|-------------|---|---|---|----|----|----|-----|
| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| PCA9541 | 1 | 1 | 1 | 0 | A2 | A1 | A0 | R/W |
| Micro controller | 1 | 0 | 0 | 0 | A2 | A1 | A0 | R/W |
| External EEPROM | 1 | 0 | 1 | 0 | A2 | A1 | AO | R/W |
| Global Broadcast | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | MSB | | | | | | | LSB |

The **Global Broadcast** instruction executes a simultaneous **write** instruction to all power supplies. A **read** instruction cannot be accessed globally. The three programmable address bits are the same for all I²C accessible devices within the power supply.



PMBus[™] Commands

Standard instruction: Up to two bytes of data may follow an instruction depending on the required data content. Analog data is always transmitted as LSB followed by MSB. PEC is mandatory and includes the address and data fields.

| 1 | 8 | | 1 | 8 | 1 |
|---|---------------|-----|---|--------------|---|
| S | Slave address | Wr | Α | Command Code | А |
| 3 | Slave address | vvi | А | Command Code | A |

| Low data byto A High data byto A DEC | | | | | - | | |
|--------------------------------------|---------------|---|----------------|---|-----|---|---|
| | Low data byte | Α | High data byte | А | PEC | Α | Ρ |

Master to Slave 🔣 Slave to Master

SMBUS annotations; S – Start , Wr – Write, Sr – re-Start, Rd – Read, A – Acknowledge, NA – notacknowledged, P – Stop

Direct mode data format: The Direct Mode data format is supported, where $y = [mX + b] \times 10^{R}$. In the equation, y is the data value from the controller and x is the 'real' value either being set or returned, except for V_{IN} and Fan speed, x is the data value from the controller and y is the 'real' value.

For example, to set the output voltage to $50.45V_{DC}$, Multiply the desired set point by the m constant, 50.45 x 400=20,180. Convert this binary number to its hex equivalent: 20,180b=0x4ED4. The result is sent LSB=0xD4 first, then MSB=0x4E.

The constants are

| Function | Operation | m | b | R |
|--|-----------------|-----|----|---|
| Output voltage Output voltage shutdown | Write / read | 400 | 0 | 0 |
| Output Current | read | 5 | 0 | 0 |
| Temperature | read | 1 | 0 | 0 |
| Input Voltage | read | 1 | 75 | 0 |
| Input Power | read | 1 | 0 | 0 |
| Fan Speed setting (%) | read | 1 | 0 | 0 |
| Fan speed in RPM | read | 100 | 0 | 0 |

PMBus[™] Command set:

| Command | Hex Code | Data Field | Function |
|---------------------|-------------|---------------|-------------------------------|
| Operation | 01 | 1 | Output ON/OFF |
| Clear_Faults | 03 | 0 | Clear Status |
| Vout_command | 21 | 2 | Set Vout |
| Vout_OV_fault_limit | 40 | 2 | Set OV fault limit |
| Read_status | D0 | 10 | Read Status, Vout, Iout, T |
| LEDs test ON | D2 | 0 | Test LEDs |
| LEDs test OFF | D3 | 0 | |
| Service_LED_ON | D4 | 0 | Service LED |
| Service_LED_OFF | D5 | 0 | |
| Enable_write | D6 | 0 | Enable EEPROM write |
| Disable_write | D7 | 0 | Disable EEPROM write |
| Inhibit_restart | D8 | 0 | Latch upon failure |
| Auto_restart | D9 | 0 | Hiccup |
| Isolation_test | DA | 0 | Perform isolation test |
| Read_input_string | DC | 2 | Read Vin and Pin |
| Read_firmware_rev | DD | 3 | Firmware revisions |
| Read_run_timer | DE | 3 | Accumulated ON state |
| Fan_speed_set | DF | 3 | Fan speed control |
| Fan_normal_speed | EO | 0 | Stop fan control |
| Read_fan_speed | El | 4 | Fan control & speed |
| Stretch_LO_25ms | E2 | 0 | Production test feature |

Command Descriptions

Operation (01h): By default the Power supply is turned **ON** at power up as long as REMOTE ON is active LO. The Operation command is used to turn the Power Supply ON or OFF via the PMBus. The data byte below follows the OPERATION command.

| FUNCTION | DATA BYTE |
|----------|-----------|
| Unit ON | 0x80 |
| Unit OFF | 0x00 |

To **RESET** the power supply cycle the power supply OFF, wait at least 2 seconds, and then turn back ON. All alarms and shutdowns are cleared during a restart.

Clear_faults (03h): This command clears information bits in the STATUS registers, these include:

- Isolation OK
- Isolation test failed
- Restarted OK
- Invalid command
- Invalid data
- PEC error

Vout_Command (21h) : This command is used to change the output voltage of the power supply. Changing the output voltage should be performed simultaneously to all power supplies operating in parallel using the Global Address (Broadcast) feature.



If only a single power supply is instructed to change its output, it may attempt to source all the required power which can cause either a power limit or shutdown condition.

Software programming of output voltage overrides the set point voltage configured during power_up. The program no longer looks at the 'margin pin' and will not respond to any hardware voltage setting. The default state cannot be accessed any longer unless power is removed from the DSP.

To properly hot-plug a power supply into a live backplane, the system generated voltage should get re-configured into either the factory adjusted firmware level or the voltage level reconfigured by the margin pin. Otherwise, the voltage state of the plugged in power supply could be significantly different than the powered system.

Voltage margin range: 42V_{DC} – 58 V_{DC}.

A voltage programming example: The task: set the output voltage to 50.45V_{DC}

The constants for voltage programming are: m = 400, b and R = 0. Multiply the desired set point by the m constant, $50.45 \times 400 = 20,180$. Convert this binary number to its hex equivalent: 20,180b = 4ED4h. Transmit the data LSB first, followed by MSB, 0 x D44Eh.

Vout_OV_fault_limit (40h) : This command sets the Output Overvoltage Shutdown level.

Manufacturer-Specific PMBus[™] Commands

Many of the manufacturer-specific commands read back more than two bytes. If more than two bytes of data are returned, the standard SMBus[™] Block read is utilized. In this process, the Master issues a Write command followed by the data transfer from the power supply. The first byte of the Block Read data field sends back in hex format the number of data bytes, exclusive of the PEC number, that follows. Analog data is always transmitted LSB followed by MSB. A No – ack following the PEC byte signifies that the transmission is complete and is being terminated by the 'host'. **Read_status (D0h) :** This 'manufacturer specific' command is the basic read back returning STATUS and ALARM register data, output voltage, output current, and internal temperature data in a single read.

| 1 | | 8 | 3 | | 1 | | | 8 | | 1 |
|------|---------|-------|-------|-----------------------|-----|---|----------|---------|--------|---|
| S | Slave | add | ress | ess Wr A Command Code | | | | Code | А | |
| 1 | | 1 | | | 8 | | ן ו | | | |
| Sr | Slave | e ado | dress | Rd | A | | By | te coui | nt = 9 | А |
| | 8 1 8 | | | | Γ. | 1 | 8 | 8 | 1 | |
| Sta | tus – 2 | . / | 4 | Status | 5–1 | 4 | 4 | Aları | m – 2 | А |
| | 8 | 1 | | 8 | | 1 | T | 8 | | 1 |
| Alar | rm – 1 | А | Vol | tage L | SB | А | | /oltage | MSB | А |
| | 8 | 1 | | 8 | | 1 | | 8 | 1 | 1 |
| Cur | rrent | А | Ten | nperat | ure | A | \ | PÉC | NA | Р |

Status and alarm registers

The content and partitioning of these registers is significantly different than the standard register set in the PMBus[™] specification. More information is provided by these registers and they are accessed rapidly, at once, using the 'multi parameter' read back scheme of this document. There are a total of four registers. All errors, 0 – normal, 1 – alarm.

Status – 2

| Bit | Title | Description |
|-----|--------------------------|--|
| 7 | PEC Error | Mismatch between computed and transmitted PEC. The instruction has not been executed. Clear_Flags resets this register. |
| 6 | Will Restart | Restart after a shutdown = 1 |
| 5 | Invalid Instruction | The instruction is not supported. An ALERT# will be issued. Clear_Flags resets this register. |
| 4 | Power Capacity | High line power capacity = 1 |
| 3 | Isolation test failed | Information only to system controller |
| 2 | Restarted ok | Informs HOST that a successful RESTART occurred clearing the status and alarm registers |
| 1 | Data out of range | Flag appears until the data value is within range. A clear_flags command does not reset this register until the data is within normal range. |
| 0 | Enable pin HI | State of the ENABLE pin, HI = 1 = OFF |

Isolation test failed: The 'system controller' has to determine that sufficient capacity exists in the system to take a power supply 'off line' in order to test its isolation capability. Since the power supply cannot determine whether sufficient redundancy is available, the results of this test are provided, but the 'internal fault' flag is not set.



Status – 1

| Bit | Title | Description |
|-----|----------------|------------------------------------|
| 7 | spare | |
| 6 | Isolation test | Isolation test completed |
| 0 | OK | successfully. |
| 5 | Internal fault | The power supply is faulty |
| 4 | Shutdown | |
| 3 | Service LED | ON = 1 |
| 5 | ON | |
| 2 | | the power supply is functioning OK |
| 1 | LEDs flashing | LEDs tested test ON = 1 |
| 0 | Output ON | ON = 1 |

Alarm – 2

| Bit | Title | Description |
|-----|-------------------------------|--|
| 7 | Fan Fault | |
| 6 | No primary | No primary detected |
| 5 | Primary OT | Primary section OT |
| 4 | DC/DC OT | DC/DC section OT |
| 3 | Output voltage lower than bus | Internal regulation failure |
| 2 | Thermal sensor failed | Internal failure of a temperature sensing circuit |
| 1 | 5V out_of_limits | Either OVP or OCP occurred |
| 0 | Power Delivery | A power delivery fault occurred |

Power Delivery: The power supply compares its internal sourced current to the current requested by the current share pin. If the difference is > 10A, a fault is issued.

Alarm – 1

| Bit | Title | Description |
|-----|-----------------------------------|--|
| 7 | Unit in | An overload condition that results |
| , | power limit | in constant power |
| 6 | Primary fault | Indicates either primary failure or INPUT not present. Used in conjunction with bit – 0 and Status_1 bits 2 and 5 to assess the fault. |
| 5 | Over temp. | One of the over_temperature |
| 5 | shutdown | sensors tripped the supply |
| 4 | Over temp | Temperature is too high, close to |
| - | warning | shutdown |
| 3 | In over | Shutdown is triggered by low |
| 5 | current | output voltage < 39V _{DC} . |
| 2 | Over voltage | |
| 2 | shutdown | |
| 1 | V _{out} out_of_limits | Indication the output is not within design limits. This condition may or may not cause an output shutdown. |
| 0 | V _{in} out_of_limits | The input voltage is outside design limits |

LEDS test ON (D2h): Will turn – ON simultaneously the two front panel LEDs of the Power supply sequentially 7 seconds ON and 2 seconds OFF until instructed to turn OFF. The intent of this function is to provide visual identification of the power supply being talked to and also to visually verify that the LEDs operate and driven properly by the micro controller.

LEDS test OFF (D3h): Will turn-off simultaneously the two front panel LEDs of the Power supply.

Service LED ON (D4h) : Requests the power supply to flash-ON the Service (ok-to-remove) LED. The flash sequence is approximately 0.5 seconds ON and 0.5 seconds OFF.

Service LED OFF (D5h) : Requests the power supply to turn OFF the Service (ok-to-remove) LED.

Enable write (D6h) : This command enables write permissions into the upper ¹/₄ of memory locations for the external EEPROM. A write into these locations is normally disabled until commanded through I²C to permit writing into the protected area. A delay of about 10ms is required from the time the instruction is requested to the time that the power supply actually completes the instruction.

See the FRU-ID section for further information of content written into the EEPROM at the factory.

Disable write (D7h) : This command disables write permissions into the upper ¹/₄ of memory locations for the external EEPROM.

Unit in Power Limit or in Current Limit: When output voltage is > $36V_{DC}$ the Output LED will continue blinking.

When output voltage is < $36V_{DC}$, if the unit is in the RESTART mode, it goes into a hiccup. When the unit is ON the output LED is ON, when the unit is OFF the output LED is OFF. When the unit is in latched shutdown the output LED is OFF.

Inhibit_restart (D8h) : The Inhibit – restart command directs the power supply to remain latched off for over_voltage, over_temperature and over_current. The command needs to be sent to the power supply only once. The power supply will remember the INHIBIT instruction as long as internal bias is active.

Restart after a lachoff: To restart after a latch_off either of four restart mechanisms are available. The hardware pin **Enable** may be turned OFF and then ON. The unit may be commanded to restart via l²C through the Operation command by first turning OFF then turning ON . The third way to restart is to remove and reinsert the unit. The fourth way is to turn OFF and then turn ON ac power to the unit.



The fifth way is by changing firmware from **latch off** to **restart.** Each of these commands must keep the power supply in the OFF state for at least 2 seconds, with the exception of changing to **restart**.

A successful restart shall clear all alarm registers, set the **restarted successful** bit of the **Status_2** register.

A power system that is comprised of a number of power supplies could have difficulty restarting after a shutdown event because of the non-synchronized behavior of the individual power supplies. Implementing the latch-off mechanism permits a synchronized restart that guarantees the simultaneous restart of the entire system.

A synchronous restart can be implemented by;

- 1. Issuing a GLOBAL OFF and then ON command to all power supplies,
- 2. Toggling Off and then ON the REMOTE ON signal
- 3. Removing and reapplying input commercial power to the entire system.

The power supplies should be turned OFF for at least 20-30 seconds in order to discharge all internal bias supplies and reset the soft start circuitry of the individual power supplies.

Auto_restart (D9h) : Auto – restart is the default configuration for overvoltage, overcurrent and overtemperature shutdowns.

However, overvoltage has a unique limitation. An overvoltage shutdown is followed by three attempted restarts, each restart delayed 1 second, within a 1 minute window. If within the 1 minute window three attempted restarts failed, the unit will latch OFF. If within the 1 minute less than 3 shutdowns occurred then the count for latch OFF resets and the 1 minute window starts all over again.

This command resets the power supply into the default auto-restart configuration.

Isolation test (DAh): This command verifies functioning of output OR'ing. At least two paralleled power supplies are required. The host should verify that N+1 redundancy is established. If N+1 redundancy is not established the test can fail. Only one power supply should be tested at a time. Verifying test completion should be delayed for approximately 30 seconds to allow the power supply sufficient time to properly execute the test.

Failure of the isolation test is not considered a power supply FAULT because the N+1 redundancy requirement cannot be verified. The user must determine whether a true isolation fault indeed exists.

Read input string (DCh) : Reads back the input voltage and input power consumed by the power supply. In order to improve the resolution of the input voltage reading the data is shifted by 75V

| 1 | 7 | 1 | | | | | | 8 | | |
|--------------------|----------|-----|-------------|---|---|-----|------|--------|----------|----|
| S Slave address Wr | | | | | (| Con | nman | d Code | OxE | DC |
| 1 | 1 | | | 7 | | 1 | | | <u> </u> | 1 |
| А | Sr | | Slave Addre | | | | Rd | | | 4 |
| | - | | | 6 | 3 | | 1 1 | | | |
| | Byte Co | unt | = 4 | 4 | Á | | Volt | age | / | Á |
| | 8 | 1 | 3 | | 1 | 8 | 1 | | 1 | |
| Pow | er – LSB | А | Power – MSB | | | А | PEC | No – a | ack | Ρ |
| | | | | | | | | | | |

Read_firmware_rev [0 x DD]: Reads back the

firmware revision of all three μC in the power supply.

| 1 | 7 11 | | | | | | 1 | | |
|------------------------|--------------------|-----------------|-----|--|----|-------------------|-----|----------|---|
| S | Slave address Wr A | | | | | Command Code 0xDD | | | |
| | | | | | 1 | ٦ | | 8 | 1 |
| А | Sr | Slave Address F | | | Rd | A Byte Count = 4 | | | A |
| 8 | | | | | 1 | | | 8 | 1 |
| Primary micro revision | | | | | Α | [| DSP | revision | А |
| 8 | | | | | 1 | 8 | 8 1 | | 1 |
| | I ² C M | icro revis | ion | | Α | PI | EC | No–ack | Р |

For example; the read returns one byte for each device (i.e. 0 x 002114h). The sequence is primary micro, DSP, and I²C micro. 0x00 in the first byte indicates that revision information for the primary micro is not supported. The number 21 for the DSP indicates revision 2.1, and the number 14 for the I²C micro indicates revision 1.4.

Read_run_timer [0 x DE]: This command reads back the recorded operational ON state of the power supply in hours. The operational ON state is accumulated from the time the power supply is initially programmed at the factory. The power supply is in the operational ON state both when in standby and when it delivers main output power. Recorded capacity is approximately 10 years.



| 1 | 7 | L | 1 | 8 | | | | |
|-----|------------|-------|--------------------------|-----|------------------|----------|---|---|
| S | Slave addr | Wr | A | C | ommand C 0xDE | ode | А | |
| | | | | | | | | |
| 1 | 7 | | 1 1 8 | | | | 1 | |
| Sr | Slave Ac | ddres | ress Rd A Byte count = 4 | | | Α | | |
| | | | | | | - | | |
| | 8 | 1 | | 8 | 1 | 8 | | 1 |
| Tim | ne – LSB | А | Т | ime | Α | Time – M | А | |
| | | | | | | | | |
| | 8 | | | | 1 | | 1 | |
| | PEC | | | No | o – ac | :k | Ρ | |

Fan_speed_set (DFh) : This command instructs the power supply to increase the speed of the fan. The transmitted data byte represents the hex equivalent of the duty cycle in percentage, i.e. $100\% = 0 \times 64h$. The command can only increase fan speed, it cannot instruct the power supply to reduce the fan speed below what the power supply requires for internal control.

Fan_normal_speed (E0h): This command returns fan control to the power supply. It does not require a trailing data byte.

Read_Fan_speed (E1h) : Returns the commanded fan speed in percent and the measured fan speed in RPM from the individual fans. Up to 3 fans are supported. If a fan does not exist (units may contain from 1 to 3 fans), or if the command is not supported the unit return 0x00.

| 1 | 8 | | | | 1 | | | | 1 | |
|-------|--------------------|---|----|-------|---|----|------------------|---|-------|-----|
| S | Slave address Wr | | | Nr | Α | ٩. | Command 0xE1 | | | A |
| | | | | | | | | | | |
| 1 | | 8 | | | | 1 | | 8 | | |
| Sr | Slave address | | | Rd | | Α | A Byte count = 5 | | | А |
| | | | | | | | | | | |
| | 8 | 1 | | 8 | | 1 | 8 | 1 | 8 | 1 |
| Adjus | stment % | Α | Fa | n – 1 | | А | Fan – 2 | Α | Fan – | 3 A |
| | | | | | | | | | | |
| 8 | | | | | | | | 1 | | |

NA

P

Stretch_LO_25ms (E2h): Command used for production test of the clock stretch feature.

PEC

None supported commands or invalid data: The power supply notifies the MASTER if a non-supported command has been sent or invalid data has been received. Notification is implemented by setting the appropriate STATUS and ALARM registers and setting the SMBAlert# flag.

Fault Management

The power supply records faults in the STATUS and ALARM registers above and notifies the MASTER controller as described in the **Alarm Notification** section of the non-conforming event.

The STATUS and ALARM registers are continuously updated with the latest event registered by the rectifier monitoring circuits. A host responding to an SMBusALERT# signal may receive a different state of the rectifier if the state has changed from the time the SMBusALERT# has been triggered by the rectifier.

The power supply differentiates between **internal faults** that are within the power supply and **external faults** that the power supply protects itself from, such as overload or input voltage out of limits. The FAULT LED, FAULT PIN or I²C alarm is not asserted for EXTERNAL FAULTS. Every attempt is made to annunciate External Faults. Some of these annunciations can be observed by looking at the input LEDs. These fault categorizations are predictive in nature and therefore there is a likelihood that a categorization may not have been made correctly.

Input voltage out of range: The Input LED will continue blinking as long as sufficient power is available to power the LED. If the input voltage is completely gone the Input LED is OFF.

State Change Definition

A **state_change** is an indication that an event has occurred that the MASTER should be aware of. The following events shall trigger a **state_change**;

- Initial power up of the system when AC gets turned ON .This is the indication from the rectifier that it has been turned ON. Note that the master needs to read the status of each power supply to reset the system_interrupt. If the power supply is back-biased through the 8V_INT or the 5VSTB it will not issue an SMBALERT# when AC power is turned back ON.
- Whenever the power supply gets hot-plugged into a working system. This is the indicator to the system (MASTER) that a new power supply is on line.
- Any changes in the bit patterns of the STATUS and ALARM registers are a STATUS change which triggers the SMBALERT# flag. Note that a host-issued command such as CLEAR_FAULTS will not trigger an SMB.



Hot plug procedures

Careful system control is recommended when hot plugging a power supply into a live system. It takes about 15 seconds for a power supply to configure its address on the bus based on the analog voltage levels present on the backplane. If communications are not stopped during this interval, multiple power supplies may respond to specific instructions because the address of the hot plugged power supply always defaults to xxxx000 (depending on which device is being addressed within the power supply) until the power supply configures its address.

The recommended procedure for hot plug is the following: The system controller should be told which power supply is to be removed. The controller turns the service LED ON, thus informing the installer that the identified power supply can be removed from the system. The system controller should then poll the module_present signal to verify when the power supply is re-inserted. It should time out for 15 seconds after this signal is verified. At the end of the time out all communications can resume.

Predictive Failures

Alarm warnings that do not cause a shutdown are indicators of potential future failures of the power supply. For example, if a thermal sensor failed, a warning is issued but an immediate shutdown of the power supply is not warranted.

Another example of potential predictive failure mechanisms can be derived from information such as fan speed when multiple fans are used in the same power supply. If the speed of the fans varies by more than 20% from each other, this is an indication of an impending fan wear out.

The goal is to identify problems early before a protective shutdown would occur that would take the power supply out of service.

External EEPROM

A 64k-bit EEPROM is provided across the I²C bus. This EEPROM is used for both storing FRU_ID information and for providing a scratchpad memory function for customer use.

Functionally the EEPROM is equivalent to the ST M34D64 part that has its memory partitioned into a write protected upper ¹/₄ of memory space and the lower ³/₄ section that cannot be protected. FRU_ID is written into the write protected portion of memory.

Write protect feature: Writing into the upper ¼ of memory can be accomplished either by hardware or software.

The power supply pulls down the write_protect (Wp) pin to ground via a 500Ω resistor between the 'module_present' signal pin and Logic_GRD (see the Module Present Signal section of Input Signals). Writing into the upper ¼ of memory can be accomplished by pulling HI the module_present pin.

An alternative, and the recommended approach, is to issue the Enable_write command via software.

Page implementation: The external EEPROM is partitioned into 32 byte pages. For a write operation only the starting address is required. The device automatically increments the memory address for each byte of additional data it receives. However, if the 32 byte limit is exceeded the device executes a wrap – around that will start rewriting from the first address specified. Thus byte 33 will replace the first byte written, byte 34 the second byte and so on. One needs to be careful therefore not to exceed the 32 byte page limitation of the device.



Table 1: FRU_ID

The upper quarter of memory starting from address 6144 shall be reserved for factory ID and factory data.

| Memory Location Decimal | Memory Location (HEX) | Length (bytes) | Format | Static Value type | Description | Notes/Example |
|-------------------------------|-----------------------------|-------------------|--------|-------------------------|---|---|
| 6144d | 0x1800 | 12 | ASCII | Fixed | | CP2725AC54TE |
| 6156d | 0x180C | 10 | ASCII | Fixed | | 123456789x or C123456789 |
| 6166d | 0x1816 | 6 | ASCII | Variable | revision | x:xxxx controlled by PDI series # |
| 6172d | 0x181C | 6 | ASCII | Variable | | |
| 6178d | 0x1822 | 14 | ASCII | Variable | OmniOn – energy – Serial_No | 01KZ51018193 <u>xx</u> 01 Year of manufacture – 2001 KZ factory, in this case Matamoros 51 week of manufacture 018193xx serial # mfg choice |
| 6192d | 0x1830 | 40 | ASCII | Variable | OmniOn – Manufacturing location | "Matamoros, Tamps, Mexico" |
| 6232d | 0x1858 | 8 | ASCII | | spare | |
| 6240d | 0x1860 | 2 | HEX | Fixed | spare | |
| 6242d | 0x1862 | 158 | ASCII | Fixed | Customer Information | These fields are reserved for use by the customer. |
| 6400d | 0x1900 | 5 | HEX | Fixed | M, B, & R for voltage read | |
| 6405d | 0x1905 | 5 | HEX | | M, B, & R for current read | |
| 6410d | 0x190A | 5 | HEX | | M, B, & R temp read | |
| 6415d | 0x190F | 5 | HEX | | spare | M & B are 2 bytes each sent as MSB and |
| 6420d | 0x1914 | 5 | HEX | | M, B, & R for voltage set | then LSB. R is one byte. These are |
| 6425d | 0x1919 | 5 | HEX | | M, B, & R for input voltage read | stored as two's complement. |
| 6430d | 0x191E | | HEX | | | See the section on Direct Mode |
| 6431d | 9x191F | 5 | HEX | Fixed | | Constants Stored in the EEPROM for |
| 6436d | 0x1924 | 5 | HEX | | in, b, a it for fair percent dajust | the constants stored in these fields |
| 6441d | 0x1929 | 5 | HEX | Fixed | M, B, & R for fan RPM read | |
| 6446d | 0x192E | 5 | HEX | Fixed | M, B, & R for converter input voltage read | |

Notes: Memory locations 0x00 to 0x17FF and 0x1A00 to 0x2000 are blank (0xFF). Locations 0x1800 to 0x19FF contain FRUID, locations not specified are filled with 0's. Checksum is the complement of the sum of locations 0x1800 to 0x19FF (chksum = 0xFF – sum(0x1800 – 0x19FF)), excluding serial number field (checksum will always be the same since all fields are fixed except serial number).

Table 2: Alarm and LED state summary

| | Pow | er Suppl | y LED St | ate | м | onitorir | ng Signals | |
|--|----------------|----------------|----------|--------|----|----------|------------|-------------------|
| Condition | AC OK Green | DC OK Green | | | | οτω | PFW | Module Present |
| OK | 1 | 1 | 0 | 0 | HI | HI | HI | LO |
| Thermal Alarm (5°C before shutdown) | 1 | 1 | 1 | 0 | H | LO | HI | LO |
| Thermal Shutdown | 1 | 0 | 1 | 1 | LO | LO | LO | LO |
| Defective Fan | 1 | 0 | 0 |] | LO | HI | LO | LO |
| Blown AC Fuse in Unit | 1 | 0 | 0 | 1 | LO | HI | LO | LO |
| AC Present but not within limits | Blinks | 0 | 0 | 0 | HI | HI | 4 | LO |
| AC not present ¹ | 0 | 0 | 0 | 0 | HI | HI | LO | LO |
| Boost Stage Failure | 1 | 0 | 0 | 1 | LO | HI | LO | LO |
| Over Voltage Latched Shutdown | 1 | 0 | 0 | 1 | LO | HI | LO | LO |
| Over Current | 1 | Blinks | 0 | 0 | HI | HI | LO | LO |
| Non – catastrophic Internal Failure ² | 1 | 1 | 0 | 1 | LO | HI | HI | LO |
| Missing Module | | | | | | | | HI |
| Standby (remote) | 1 | 0 | 0 | 0 | HI | HI | LO | LO |
| Service Request (PMBus mode) | 1 | 1 | Blinks | 0 | HI | HI | HI | LO |
| Communications Fault (RS485 mode) | 1 | 1 | 0 | Blinks | HI | HI | HI | LO |

'This signal is correct if the rectifier is back biased from other rectifiers in the shelf .

²Any detectable fault condition that does not cause a shutting down. For example, ORing FET failure, boost section out of regulation, etc.

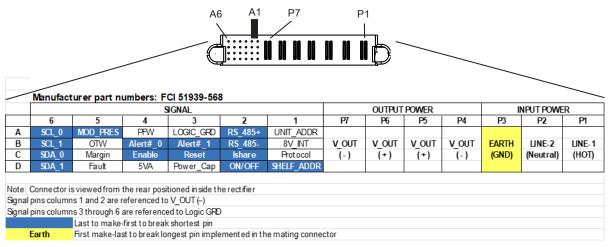
³Signal transition from HI to LO is output load dependent

⁴The PFW signal changes states when the boost voltage decays and not when the AC is out of regulation.



Output Connector

Mating Connector: right angle PWB mate – all pins: AMP 1450572-1, right angle PWB mate except pass-thru input power: AMP 6450378-1



Signal Definitions

All hardware alarm signals (Fault, PFW, OTW, Power Capacity) are open drain FETs. These signals should be pulled HI to either 3.3V or 5V. Maximum sink current 5mA. An active LO signal (< 0.4V_{DC}) state. All signals are referenced to Logic GRD unless otherwise stated. Contact your Lineage Power representative for more details.

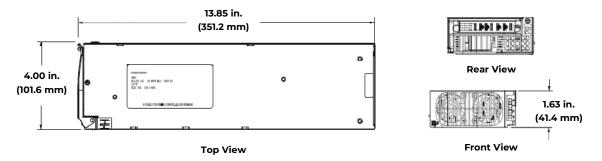
| Function | Label | Туре | Description |
|-------------------------------|-----------------------|-------------|---|
| Output Enable | Enable | | If shorted to LOGIC_GRD, the Rectifier output is enabled when using I ² C mode of operation. May also be toggled to reset a latched OFF Rectifier. Function not available in RS485 mode. |
| Power Fail Warning | PFW | • | An open drain FET; normally HI, indicating output power is present. Changes to LO at least 5msec before the output voltage decays below 40V _{DC} . |
| I ² C Interrupt | Alert#_0 Alert#_1 | Output | Interrupt signal via I ² C lines indicating that service is requested from the host controller. This signal pin is pulled up to 3.3V via a 10k Ω resistor and switches to active LO when an interrupt occurs. |
| Rectifier Fault | Fault | | Indicates that an internal fault exists. An open drain FET; normally HI, changes to LO. |
| Module Present | MOD_PRES | Output | Short pin, see Status and Control description for further information on this signal. |
| ON/OFF | ON/OFF | input | Short pin, connects last and breaks first; used to activate and deactivate output during hot – insertion and extraction, respectively. Ref: Vout (-) |
| Protocol select | Protocol | mput | See Status and Control description for further information on this signal. Ref: Vout(-). |
| Margining | Margin | mput | Allows changing of output voltage through an analog voltage input or via resistor divider. |
| Over – Temperature Warning | OTW | Output | An open drain FET; normally HI, changes to LO approximately 5°C prior to thermal shutdown. |
| Power Capacity | POWER_ CAP | Output | Open drain FET; Used to indicate Rectifier operation mode; HI indicates 2725W operation and LO indicates 1200W operation. |
| Rectifier address | Unit_addr | Input | Voltage level addressing of Rectifiers within a single shelf. Ref: Vout (-). |
| Shelf Address | Shelf_addr | Input | Voltage level addressing of Rectifiers within multiple shelves. Ref: Vout (-). |
| Back bias | 8V_INT | Bi – direct | Diode OR'ed 8V _{DC} drain; used to back bias microprocessors and DSP of failed failed Rectifier from operating Rectifiers. Ref: Vout (-). |
| Mux Reset | Reset | | Resets the I ² C lines to I ² C line 0. |
| Standby power | 5VA | Output | 5V at 0.75A provided for external use by either adjacent power supplies or the using system. |
| Current Share | Ishare | Bi – direct | A single wire interface between each of the power unit forces them to share the load current. Ref: Vout (-). |
| I ² C Line 0 | SCL_0, SDA_0 | Input | I²C line 0. |
| I ² C Line 1 | SCL_1, SDA_1 | Input | I ² C line 1. |
| I ² C Interrupt | Alert#_0, Alert#_1 | Output | Goes active LO |
| RS485 Line | RS_485+ RS_485- | Bi – direct | RS485 line. |



Front Panel LEDs

| | Analog Mode | l²C Mode | RS485 Mode |
|----------|--|--|--|
| □~ | ←─── | ON: Input ok Blinking: Input out of limits | |
| | < | ON: Output ok Blinking: Overload | > |
| □ | ON: Over – temperature Warning | ON: Over – temperature Warning Blinking: Service | ON: Over – temperature Warning |
| ! | ← c | N: Fault → | ON: Fault Blinking: Not communicating |

Dimensions



Faceplate color shall be dark grey with a green

Physical

| Packaged weight | 5.4/2.45 lbs/kgs | | |
|-----------------|---|--|--|
| Unpacked weight | 4.8/2.18 lbs/kgs | | |
| Heat release | 100 Watts or 341 BTUs @ 80% load, 153 Watts or 522 BTUs @ 100% load | | |

Ordering Information

| Item | Description | Ordering Code |
|-------------------|---|---------------|
| CP2725AC48TEZ-FB2 | 2725W $_{\odot}$ 52V, 5V _{DC} /0.75A, RoHS Compliant, conformal coated | 1600158245A |



Change History (excludes grammar & clarifications)

| Revision | Date | Description of Changes |
|----------|------------|--------------------------------|
| 1.0 | 02/09/2023 | Initial release |
| 1.1 | 12/21/2023 | Updated as per OmniOn template |



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