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1. SAFETY REGULATIONS AND INFORMATION

Read these operating instructions carefully before starting work on the device. Observe the following warnings to prevent malfunctions or danger to persons.

These operating instructions are to be regarded as part of the device. The device is only to be sold or passed on together with the operating instructions.

These operating instructions may be duplicated and distributed to inform about potential dangers and their prevention.

1.1 Hazard levels for warnings

These operating instructions use the following hazard levels to indicate potentially hazardous situations and important safety regulations:



DANGER

Indicates an imminently hazardous situation which will result in death or serious injury if the specified actions are not taken. Compliance with the instructions is imperative.

WARNING

Indicates a potentially hazardous situation which can result in death or serious injury if the specified actions are not taken. Exercise extreme caution while working.

CAUTION

Indicates a potentially hazardous situation which can result in minor or moderate injury or damage to property if the specified actions are not taken

NOTE

A potentially harmful situation can occur and, if not avoided, can lead to property damage.

1.2 Staff qualifications

The device may only be transported, unpacked, installed, operated, maintained and otherwise used by suitably qualified, trained and authorized technical staff.

Only authorized specialists are permitted to install the device, to carry out a test run and to perform work on the electrical installation.

1.3 Basic safety rules

The safety hazards associated with the device must be assessed again following installation in the final product.

The locally applicable industrial safety regulations are always to be observed when working on the device.

Keep the workplace clean and tidy. Untidiness in the work area increases the risk of accidents.

Note the following when working on the device:

⇒ Do not perform any modifications, additions or conversions on the device without the approval of ebm-papst.

1.4 Voltage

- Check the device's electrical equipment at regular intervals; see Chapter 6.2 Safety inspection.
- ⇒ Replace loose connections and defective cables immediately.



DANGER

Electrically charged device

Risk of electric shock

→ When working on an electrically charged device, stand on a rubber mat.







WARNING

Live terminals and connections even with device switched off

Electric shock

→ Wait five minutes after disconnecting the voltage at all poles before opening the device.

CAUTION

In the event of a fault, the rotor and the impeller will be energized

The rotor and the impeller have basic insulation.

 \rightarrow Do not touch the rotor and impeller once installed.

CAUTION

If control voltage or a stored speed set value is applied, the motor will restart automatically, e.g. after a power failure.

Risk of injury

- → Keep out of the device's danger zone.
- → When working on the device, switch off the line voltage and ensure that it cannot be switched back on.
- → Wait until the device comes to a stop.
- After working on the device, remove any tools or other objects from the device.

1.5 Safety and protective features



DANGER

Guard missing and guard not functioning

Without a guard, hands may become caught up in the device during operation for example, resulting in serious injury. Loose parts or items of clothing could be drawn in.

- → The device is a built-in component. As the owner, you are responsible for ensuring that the device is adequately safeguarded.# Operate the device only with a fixed protective device and guard grill.
- → Stop the device immediately if a protective device is found to be missing or ineffective.

1.6 Electromagnetic radiation

Interference from electromagnetic radiation is possible, e.g. in conjunction with open- and closed-loop control devices.

If impermissible radiation levels occur following installation, appropriate shielding measures have to be taken by the user.

NOTE

Electrical or electromagnetic interference after installing the device in customer equipment.

→ Verify that the entire setup is EMC-compliant.

1.7 Mechanical movement



DANGER

Rotating device

Risk of injury to body parts coming into contact with the rotor or the impeller.

- → Secure the device against accidental contact.
- → Before working on the system/machine, wait until all parts have come to a standstill.

WARNING

Rotating device

Long hair and dangling items of clothing, jewelry and the like can become entangled and be pulled into the device. Injuries can result

- → Do not wear any loose-fitting or dangling clothing or jewelry while working on rotating parts.
- → Protect long hair with a cap.

1.8 Emissions

WARNING

Depending on the installation and operating conditions, the sound pressure level may exceed 70 dB(A).

Risk of noise-induced hearing loss

- → Take appropriate technical safety measures.
- → Protect operating personnel with appropriate safety equipment such as hearing protection.
- → Also observe the requirements of local agencies.

1.9 Hot surface



CALITION

High temperature on electronics housing

Risk of burns

→ Ensure sufficient protection against accidental contact.

1.10 Transport



NOTE

Transporting the device

→ Transport the device in its original packaging only.

1.11 Storage

- ⇒ Store the device, partially or fully assembled, in a dry place, protected against the weather and free from vibration, in the original packaging in a clean environment.
- ⇒ Protect the device against environmental effects and dirt until final installation.
- We recommend storing the device for no longer than one year in order to guarantee trouble-free operation and the longest possible service life.
- ⇒ Even devices explicitly intended for outdoor use are to be stored as described prior to commissioning.
- Maintain the storage temperature, see
 Chapter 3.5 Transport and storage conditions.





2. INTENDED USE

The device is exclusively designed as a built-in device for conveying air according to its technical data.

Any other usage above and beyond this does not conform with the intended purpose and constitutes misuse of the device.

Customer equipment must be capable of withstanding the mechanical and thermal stresses that can arise from this product. This applies for the entire service life of the equipment in which this product is installed.

Intended use also includes

- Use of the device in stationary systems only.
- Performance of all maintenance work.
- Conveying air at an ambient air pressure between 800 mbar and 1050 mbar.
- Using the device within the permitted ambient temperature range; see Chapter 3.5 Transport and storage conditions and Chapter 3.2 Nominal data.
- · Operating the device with all protective devices.
- Following the operating instructions.

Improper use

In particular, operating the device in the following ways is prohibited and could be hazardous:

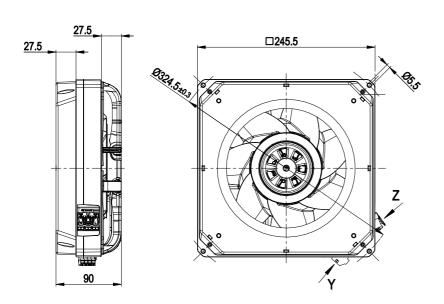
- Operating the device in an unbalanced state, e.g. due to dirt deposits or ice formation.
- Resonant operation, operation with severe vibration. This also includes vibration transmitted to the fan from the customer installation.
- Operation in medical equipment with a life-sustaining or life-support function.
- Conveying solids in the flow medium.
- · Painting the device
- · Connections (e.g. screws) coming loose during operation.
- Conveying air that contains abrasive particles.
- Conveying highly corrosive air, e.g. salt spray. Exception: devices designed for salt spray and correspondingly protected.
- Conveying air with high dust content, e.g. suctioning off sawdust.
- Operating the device close to flammable materials or components.
- · Operating the device in an explosive atmosphere.
- Using the device as a safety component or to perform safety-related functions.
- Operation with completely or partially disassembled or manipulated protective devices.
- In addition, all applications not listed among the intended uses.

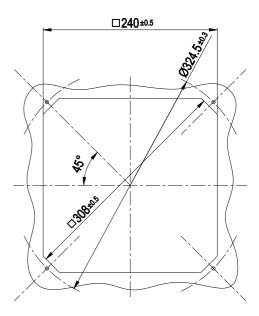




3. TECHNICAL DATA

3.1 Product drawing





Υ



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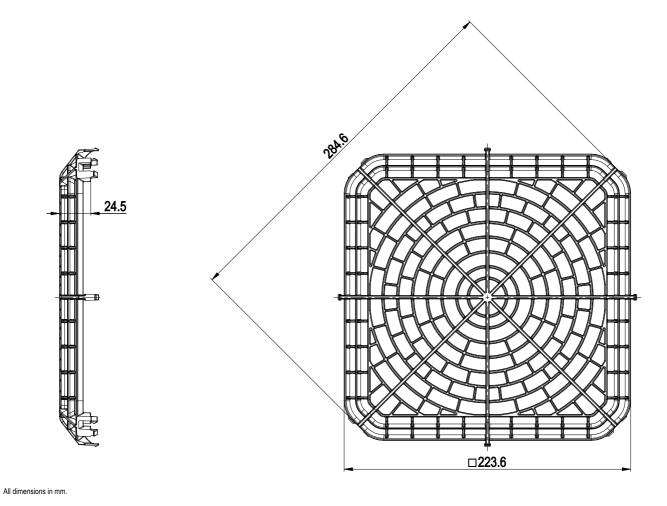


All dimensions in mm.

Mounting dimensions







Accessory part: Guard grill 25000-2-2929 on intake side, not included in scope of delivery





3.2 Nominal data

| Motor | M3G055-BI |
|-----------------------------|-----------|
| Phase | 1~ |
| Nominal voltage / VAC | 115 |
| Nominal voltage range / VAC | 100 130 |
| Frequency / Hz | 50/60 |
| Method of obtaining data | ml |
| Speed (rpm) / min-1 | 2850 |
| Power consumption / W | 65 |
| Current draw / A | 1.0 |
| Max. back pressure / Pa | 180 |
| Min. ambient | -25 |
| temperature / °C | |
| Max. ambient | 60 |
| temperature / °C | |

ml = Max. load \cdot me = Max. efficiency \cdot fa = Free air cs = Customer specification \cdot ce = Customer equipment

3.3 Technical description

| Size 200 mm Motor size 55 Rotor surface Thick-film passivated Terminal box material PA plastic Electronics housing material PA plastic Housing material PA plastic Housing material PP plastic Number of blades 7 Direction of rotation Clockwise, viewed toward rotor Degree of protection IP54 Insulation class "B" Moisture (F) / H1 Environmental (H) protection class Installation position Any Condensation Any Condensation Mode S1 Motor bearing Ball bearing Technical features Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | | | |
|--|-----------------------|--------------------------------|--|--|
| Motor size Rotor surface Treminal box material Electronics housing material Impeller material Impeller material PA plastic PP plastic Number of blades Tinsulation class Moisture (F) / Environmental (H) protection class Installation position Condensation drainage holes Motor bearing Technical features Motor current according to IEC 60990 (measuring circuit Fig. 4, TN) Die-cast aluminum | Weight | 2 kg | | |
| Rotor surface Terminal box material Electronics housing material Impeller material Impeller material PA plastic PP plastic Number of blades Tirection of rotation Degree of protection Insulation class Insulation position Condensation drainage holes Motor bearing Technical features Rotick Tirection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Size | 200 mm | | |
| Terminal box material Electronics housing material Impeller material Housing material PA plastic PP plastic Number of blades Tobirection of rotation Degree of protection Insulation class Moisture (F) / Environmental (H) protection class Installation position Condensation drainage holes Mode Motor bearing Technical features Fig. Any Control input 0-10 VDC / PWM Control input 0-10 VDC / PWM Control interface with SELV potential safely disconnected from the mains Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Motor size | 55 | | |
| Electronics housing material Impeller material Housing material PA plastic Number of blades 7 Direction of rotation Degree of protection Insulation class Moisture (F) / Environmental (H) protection class Installation position Condensation drainage holes Mode S1 Motor bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Rotor surface | Thick-film passivated | | |
| Impeller material PA plastic Housing material PP plastic Number of blades 7 Direction of rotation Clockwise, viewed toward rotor Degree of protection IP54 Insulation class "B" Moisture (F) / Environmental (H) protection class Installation position Any Condensation Any Condensation Sall bearing Technical features Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Terminal box material | PA plastic | | |
| Impeller material PA plastic Housing material PP plastic Number of blades 7 Direction of rotation Clockwise, viewed toward rotor Degree of protection IP54 Insulation class "B" Moisture (F) / H1 Environmental (H) protection class Installation position Any Condensation Any Condensation Wone, open rotor drainage holes Mode S1 Motor bearing Ball bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN) | Electronics housing | Die-cast aluminum | | |
| Housing material Number of blades 7 Direction of rotation Degree of protection IP54 Insulation class Moisture (F) / Environmental (H) protection class Installation position Condensation drainage holes Mode Motor bearing Technical features P plastic Any Condensation Any Condensation drainage holes Mode S1 Motor bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | material | | | |
| Number of blades Direction of rotation Degree of protection IP54 Insulation class Moisture (F) / Environmental (H) protection class Installation position Condensation drainage holes Mode Motor bearing Technical features Dutput 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Impeller material | PA plastic | | |
| Direction of rotation Degree of protection Insulation class Moisture (F) / Environmental (H) protection class Installation position Condensation drainage holes Mode Motor bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Housing material | PP plastic | | |
| Degree of protection IP54 Insulation class "B" Moisture (F) / H1 Environmental (H) protection class Installation position Any Condensation drainage holes Mode S1 Motor bearing Ball bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Number of blades | 7 | | |
| Insulation class Moisture (F) / Environmental (H) protection class Installation position Condensation drainage holes Mode S1 Motor bearing Ball bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Direction of rotation | Clockwise, viewed toward rotor | | |
| Moisture (F) / Environmental (H) protection class Installation position Condensation drainage holes Mode Motor bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Degree of protection | | | |
| Environmental (H) protection class Installation position Condensation drainage holes Mode S1 Motor bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Insulation class | "B" | | |
| protection class Installation position Condensation drainage holes Mode S1 Motor bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Moisture (F) / | H1 | | |
| Installation position Condensation drainage holes Mode S1 Motor bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | , , | | | |
| Condensation drainage holes Mode S1 Motor bearing Ball bearing - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | protection class | | | |
| Mode S1 Motor bearing Ball bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | • | | | |
| Mode S1 Motor bearing Ball bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | None, open rotor | | |
| Motor bearing Ball bearing - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | | | |
| - Output 10 VDC, max. 1.1 mA - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | • | | |
| - Tach output - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | • | | |
| - Power limiter - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | Technical features | | | |
| - Motor current limitation - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | | | |
| - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | | | |
| - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | | | |
| - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | | | |
| safely disconnected from the mains - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | | | |
| - Thermal overload protection for electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | · | | |
| electronics/motor Touch current according to IEC 60990 (measuring circuit Fig. 4, TN | | | | |
| Touch current <= 3.5 mA according to IEC 60990 (measuring circuit Fig. 4, TN | | • | | |
| according to IEC 60990 (measuring circuit Fig. 4, TN | Touch current | | | |
| 60990 (measuring circuit Fig. 4, TN | | - 0.0 m/t | | |
| circuit Fig. 4, TN | | | | |
| - ' | | | | |
| 3y3tGiii) | system) | | | |

| Electrical hookup | Terminal strip | |
|---------------------------|---|--|
| Motor protection | Electronic motor protection | |
| with cable | Variable | |
| Protection class | I (with customer connection of protective earth) | |
| Conformity with standards | EN 60335-1; CE | |
| Approval | UL 1004-7 + 60730-1; CSA C22.2 No. 77 + CAN/CSA-E60730-1 | |



With regard to cyclic speed loads, note that the rotating parts of the device are designed for a maximum of one million load cycles. If you have special questions, consult ebm-papst for support.

Information on surface quality

⇒ Use the device in accordance with its degree of protection.

The surfaces of the products conform to the generally applicable industrial standard. The surface quality may change during the production period. This has no effect on strength, dimensional stability and dimensional accuracy.

The color pigments in the paints used perceptibly react to UV light over the course of time. The product is to be protected against UV radiation to prevent the formation of patches and fading. Changes in color are not a reason for complaint and are not covered by the warranty. UV radiation in the frequency range and the intensity of natural solar radiation has no effect on the technical properties of the products.

3.4 Mounting data

Any further mounting data required can be taken from the product drawing or Section Chapter 4.1 Mechanical connection.

| Strength class of | 8.8 |
|-------------------|-----|
| screws | |

For screw clearance, see Chapter 3.1 Product drawing

⇒ Secure the screws against unintentional loosening (e.g. use self-locking screws).

3.5 Transport and storage conditions

| Max. permitted ambient temp. for motor (transport/ storage) | + 80 °C |
|--|---------|
| Min. permitted ambient temp. for motor (transport/ storage) | - 40 °C |

3.6 Electromagnetic compatibility

| EMC immunity to | According to EN 61000-6-2 (industrial |
|------------------|---------------------------------------|
| interference | environment) |
| EMC interference | According to EN 61000-6-4 (industrial |
| emission | environment) |





Subject to change

4. CONNECTION AND STARTUP

4.1 Mechanical connection



CAUTION

Risk of cutting and crushing when removing device from packaging



- → Carefully remove the device from the packaging by grasping hold of the frame. Never subject to any impact.
- → Wear safety shoes and cut-resistant safety gloves.



NOTE

Damage to the device from vibration

Bearing damage, shorter service life

- → The fan must not be subjected to force or excessive vibration from sections of the installation.
- → If the fan is connected to air ducts, the connection should be isolated from vibration, e.g. using compensators or similar elements
- → Ensure stress-free attachment of the fan to the substructure.
- The fan may not be handled in the area around the inlet nozzle during transport and installation.
 - There is a risk of damage to the impeller.
- Check the device for transport damage. Damaged devices are not to be installed.
- Install the undamaged device in accordance with your application.



CAUTION

Possible damage to the device

If the device slips during installation, serious damage can result.

- → Ensure that the device is securely positioned at its place of installation until all fastening screws have been tightened.
- The fan must not be strained on fastening.

4.2 Electrical connection



DANGER

Voltage on the device

Electric shock

- → Always connect a protective earth first.
- \rightarrow Check the protective earth.



DANGER

Faulty insulation

Risk of fatal injury from electric shock

- → Use only cables that meet the specified installation regulations for voltage, current, insulation material, capacity, etc.
- → Route cables so that they cannot be touched by any rotating parts.



Danger

Electrical charge (>50 μ C) between phase conductor and protective earth connection after switching off supply with multiple devices connected in parallel.

Electric shock, risk of injury

→ Ensure sufficient protection against accidental contact. Before working on the electrical hookup, short the supply and PE connections.

CAUTION

Voltage

The fan is a built-in component and has no disconnecting switch.

- → Only connect the fan to circuits that can be switched off with an all-pole disconnection switch.
- → When working on the fan, secure the system/machine in which the fan is installed so as to prevent it from being switched back on.

NOTE

Water ingress into wires or cables

Water ingress at the customer end of the cable can damage the

→ Make sure the end of the cable is connected in a dry environment.



Only connect the device to circuits that can be switched off with an all-pole disconnection switch.

4.2.1 Requirements

- Check whether the information on the nameplate matches the connection data.
- ⇒ Before connecting the device, make sure the power supply matches the device voltage.
- Only use cables designed for the current level indicated on the nameplate.

For determining the cross-section, note the sizing criteria according to EN 61800-5-1. The protective earth must have a cross-section equal to or greater than that of the phase conductor. We recommend the use of 105 °C cables. Ensure that the minimum cable cross-section is at least

AWG 26 / 0.13 mm².

Protective earth contact resistance according to EN 60335

Compliance with the resistance specifications according to EN 60335 for the protective earth connection circuit must be verified in the end application. Depending on the installation situation, it may be necessary to connect an additional protective earth conductor by way of the extra protective earth terminal provided on the device.

4.2.2 Reactive currents



Because of the EMC filter integrated for compliance with EMC limits (interference emission and immunity to interference), reactive currents can be measured in the supply line even when the motor is at a standstill and the line voltage is switched

- The values are typically in the range < 50 mA
- At the same time, the effective power in this operating state (operational readiness) is typically < 2 W.

4.2.3 Residual current circuit breaker (RCCB)



If the use of a residual current device (RCD) is required in your installation, only pulse-current sensitive and/or AC/DC-sensitive residual current devices (type A or B) are permissible. As with variable frequency drives, residual current devices cannot provide personal safety while operating the device. When the device power supply is switched on, pulsed charging currents from the capacitors in the integrated EMC filter can lead to the instant tripping of residual current devices. We recommend the use of residual current circuit breakers





(RCCB) with a trip threshold of 300 mA and delayed tripping (super-resistant, characteristic K).

4.2.4 Locked-rotor protection



Due to the locked-rotor protection, the starting current (LRA) is equal to or less than the nominal current (FLA).

4.3 Connection via terminal strip

4.3.1 Connecting wires to terminals



WARNING

Live terminals and connections even with device switched off

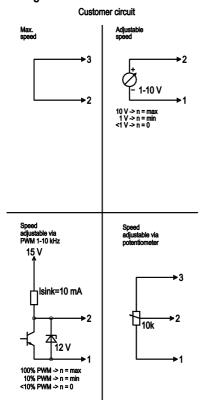
Electric shock

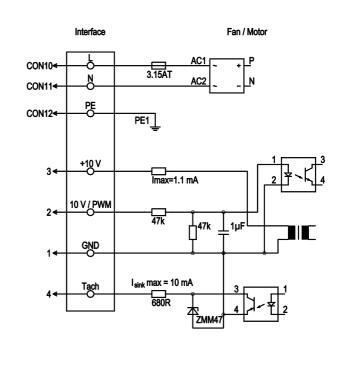
- → Wait five minutes after disconnecting the voltage at all poles before opening the device.
- ⇒ Insert the wires into the terminals, see Chapter 4.4 Connection diagram.





4.4 Connection diagram





Drawing preliminary!

| No. | Conn. | Designation | Color | Function/assignment | |
|-----|-------|----------------|--------|---|--|
| | CON10 | L | black | Power supply 115 VAC, 50-60 Hz, see nameplate for voltage range | |
| | CON11 | N | blue | Neutral conductor | |
| | CON12 | PE | green/ | Protective earth | |
| | | | yellow | | |
| | 1 | GND | blue | GND connection for control interface | |
| | 2 | 0- 10V PWM | yellow | Control input 0-10 V or PWM, electrically isolated | |
| | 3 | 10V/ max 1.1mA | red | Voltage output 10 VDC 1.1 mA, electrically isolated, short-circuit-proof | |
| | 4 | Tach | white | Tach output: Open collector, 1 pulse per revolution, electrically isolated, Isink max = 10 mA | |



4.5 Checking connections

- ⇒ Ensure isolation from supply (all phases).
- ⇒ Make sure a restart is impossible
- ⇒ Check the cables for proper fit.

4.6 Switching on the device

The device may only be switched on if it has been installed properly and in accordance with its intended use, including the required safety mechanisms and professional electrical hookup. This also applies for devices which have already been equipped with plugs and terminals or similar connectors by the customer.



WARNING Hot motor housing

Risk of fire

- → Ensure that no combustible or flammable materials are located close to the fan.
- ⇒ Before switching on, check the device for visible external damage and make sure the protective devices are functional.
- Check the fan's air flow paths for foreign matter and remove any foreign matter found.
- Apply the nominal supply voltage.
- ⇒ Start the device by changing the input signal.



NOTE

Damage to the device from vibration

Bearing damage, shorter service life

- → Low-vibration operation of the fan must be ensured over the entire speed control range.
- → Severe vibration can arise for instance from inexpert handling, transportation damage and resultant imbalance or be caused by component or structural resonance.
- Speed ranges with excessively high vibration levels and possibly resonant frequencies must be determined in the course of fan commissioning.
- → Either run through the resonant range as quickly as possible with speed control or find another remedy.
- → Operation with excessively high vibration levels can lead to premature failure.

4.7 Switching off the device

Switching off the device during operation:

- ⇒ Switch off the device via the control input.
- Do not switch the motor (e.g. in cyclic operation) on and off via power supply.

Switching off the device for maintenance:

- ⇒ Switch off the device via the control input.
- Do not switch the motor (e.g. in cyclic operation) on and off via power supply.
- Disconnect the device from the power supply.
- When disconnecting, be sure to disconnect the ground connection last.

5. INTEGRATED PROTECTIVE FEATURES

The integrated protective functions cause the motor to switch off automatically in the event of the faults described in the table.

| Fault | Safety feature description/ function |
|--------------------------------|---|
| Rotor position detection error | An automatic restart follows. |
| Blocked rotor | ⇒ After the blockage is |
| | removed, the motor restarts |
| | automatically. |

6. MAINTENANCE, MALFUNCTIONS, POSSIBLE CAUSES AND REMEDIES

Do not perform any repairs on your device. Send the device to ebmpapst for repair or replacement.



WARNING

Live terminals and connections even with device switched off

Electric shock

→ Wait five minutes after disconnecting the voltage at all poles before opening the device.

CAUTION

If control voltage or a stored speed set value is applied, the motor will restart automatically, e.g. after a power failure.

Risk of injury

- → Keep out of the device's danger zone.
- → When working on the device, switch off the line voltage and ensure that it cannot be switched back on.
- → Wait until the device comes to a stop.

I ...

→ After working on the device, remove any tools or other objects from the device.



If the device is out of use for some time, e.g. when in storage, we recommend switching it on for at least two hours to allow any condensation to evaporate and to move the bearings.

| Malfunction/fault | Possible cause | Possible remedy |
|-------------------------------|-----------------------------|---|
| Impeller not running smoothly | Imbalance in rotating parts | Clean the device; replace it if imbalance persists after cleaning. Make sure no weight clips are removed during cleaning. |
| Motor not turning | Mechanical blockage | Switch off, isolate from supply and remove mechanical blockage. |
| | Line voltage faulty | Check line voltage, restore power supply, apply control signal. |
| | Faulty connection | Isolate from supply, correct connection; see connection diagram. |





| Motor/electronics overtemperature | Deficient cooling | Improve cooling. Let the device cool down. To reset the error message, switch off the line voltage for at least 25 s and then switch it on again. |
|--------------------------------------|----------------------------------|---|
| | Ambient temperature too high | Reduce the ambient temperature. Reset by reducing control input to 0. |
| | Impermissible point of operation | Correct the operating point. Let the device cool down. |



In the event of further malfunctions, contact ebm-papst.

6.1 Cleaning

To ensure a long service life, check the fans regularly for proper operation and soiling. The frequency of checking is to be adapted accordingly depending on the degree of soiling.



DANGER

Risk of injury from rotating fan.

- → Only clean when not in motion. Do not disconnect the fan from the power supply, just switch it off via the control input. This will prevent start-up of the fan.
- Dirt deposits on the motor housing can cause overheating of the motor.
- Soiling of the impeller can cause vibration that will shorten the service life of the fan.
- ⇒ Severe vibration can destroy the fan.
- ⇒ In such cases, switch off the fan immediately and clean it.
- The preferred method of cleaning is dry cleaning, e.g. using compressed air.
- ⇒ Do not use aggressive cleaning agents!

NOTE

Damage to the device during cleaning

Malfunction possible

- → Do not clean the device using a water jet or high-pressure cleaner.
- → Do not use any acid, alkali or solvent-basedcleaning agents
- → Do not use any pointed or sharp-edged objects for cleaning
- ⇒ Completely remove any cleaning agents used.
- If severe corrosion is visible on load-bearing or rotating parts, switch off the device immediately and replace it.
- ⇒ Repair of load-bearing or rotating parts is not permitted!
- Operate the fan for 2 hours at maximum speed so that any water that has ingressed can evaporate.
- ⇒ If cleaning does not eliminate vibrations, the fan may need to be rebalanced. To have it rebalanced, contact ebm-papst.
- The fan is equipped with maintenance-free ball bearings. The lifetime lubrication of the ball bearings is designed for a service life of 40,000 hours.
- If bearing replacement is necessary after that period, contact ebmpanst
- ⇒ Adapt the maintenance intervals to the actual level of dust exposure.

6.2 Safety inspection

NOTE

High-voltage test

The integrated EMC filter has Y capacitors. The tripping current is exceeded when AC testing voltage is applied.

→ Test the device with DC voltage when you perform the legally required high-voltage test. The voltage to be used corresponds to the peak value of the AC voltage required by the standard.

| What to check | How to check | How often | What action? |
|---|-------------------|----------------------------|----------------------------------|
| Contact protection cover for intactness or damage | Visual inspection | At least every 6 months | Repair or replacement of device |
| Device for damage | Visual inspection | At least every 6 months | Replace device |
| Fastening the cables | Visual inspection | At least every 6 months | Fasten |
| Fastening the protective earth terminal | Visual inspection | At least every 6 months | Fasten |
| Insulation of cables for damage | Visual inspection | At least every 6 months | Replace cables |
| Impeller for wear/deposits/ corrosion and damage | Visual inspection | At least every 6 months | Clean impeller or replace device |
| Abnormal bearing noise | acoustic | At least every 6 months | Replace device |

6.3 Disposal

For ebm-papst, environmental protection and resource preservation are top priority corporate goals.

ebm-papst operates an environmental management system which is certified in accordance with ISO 14001 and rigorously implemented around the world on the basis of German standards.

Right from the development stage, ecological design, technical safety and health protection are fixed criteria.

The following section contains recommendations for ecological disposal of the product and its components.

6.3.1 Country-specific legal requirements



NOTE

Country-specific legal requirements

Always observe the applicable country-specific legal regulations with regard to the disposal of products or waste occurring in the various phases of the life cycle. The corresponding disposal standards are also to be heeded.





6.3.2 Disassembly

Disassembly of the product must be performed or supervised by qualified personnel with the appropriate technical knowledge. The product is to be disassembled into suitable components for disposal employing standard procedures for motors.



WARNING

Heavy parts of the product may drop off. Some of the product components are heavy. These components could drop off during disassembly.

This can result in fatal or serious injury and material damage.

→ Secure components before unfastening to stop them falling.

6.3.3 Component disposal

The products are mostly made of steel, copper, aluminum and plastic. Metallic materials are generally considered to be fully recyclable. Separate the components for recycling into the following categories:

- Steel and iron
- Aluminum
- · Non-ferrous metal, e.g. motor windings
- Plastics, particularly with brominated flame retardants, in accordance with marking
- Insulating materials
- Cables and wires
- Electronic scrap, e.g. circuit boards

Only ferrite magnets and not rare earth magnets are used in external rotor motors from ebm-papst Mulfingen GmbH & Co. KG.

⇒ Ferrite magnets can be disposed of in the same way as normal iron and steel

Electrical insulating materials on the product, in cables and wires are made of similar materials and are therefore to be treated in the same manner

The materials concerned are as follows:

- Miscellaneous insulators used in the terminal box
- Power cables
- Cables for internal wiring
- Electrolytic capacitors

Dispose of electronic components employing the proper procedures for electronic scrap.



→ Please contact ebm-papst for any other questions on disposal.





Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

ebm-papst:

K3G200-AD11-02