

The ESS Sabre® ES9027PRO is a 32-bit 8 Channel digital-to-analog converters (DAC) that target high end consumer devices, professional audio applications. It was designed to create the new generation of the world's highest performing audio DAC series.

The ES9027PRO has 8 integrated DACs which use ESS' patented Hyperstream® IV DAC Architecture. Using the Dual modulator architecture, it delivers unprecedented SABRE PRO™ audio sound quality and specifications, including a +124dB DNR and -114dB THD+N per channel.

The ES9027PRO SABRE® DAC improves on previous designs to include:

- TDM & SPI support for more options in connectivity
- Lower power consumption than previous generations, including the Hyperstream IV DAC Modulator
- New Hardware mode for simplified programming

TDM, DSD, DoP, and I²S, LJ, RJ master/slave interfaces are supported in synchronous or asynchronous modes. S/PDIF is supported in asynchronous mode.

The ES9027PRO has 7 built-in pre-programmed digital filters which allow for the most discerning user to tune the SABRE sound to their own personal sound signature.

FEATURE	DESCRIPTION
Patented 32-bit Hyperstream® IV Architecture DAC Technology	32-bit audio DAC with high dynamic range & ultra-low distortion
+124dB DNR per channel -114dB THD+N per channel	Unprecedented dynamic range and ultra-low distortion
High sample rates	Up to PCM 768kHz & native DSD1024
Customizable filter characteristics	7 predefined digital filters optimized for latency or sound color for each channel to allow for a unique sound signature
Multiple Input formats are available	I ² S, LJ, RJ, TDM, DSD, DoP and S/PDIF
I ² C, SPI, and Hardware interface control	Configured by microcontroller or other I ² C / SPI source, or pins through Hardware Mode
Incorporated Self-calibration option	Paired with ES9312 regulator, ability for self calibration
Lower Power Consumption than Previous Gen.	Simplifies power supply design
Standardized Packaging	7mm x 7mm, 48 pin QFP/QFN for reduced PCB board space
Patented 32-bit Hyperstream® IV Architecture DAC Technology	32-bit audio DAC with high dynamic range & ultra-low distortion

Applications

- Professional Digital Audio Workstations (DAW) audio playback
- Personal Audio Devices, Media Streamers & A/V Receivers
- High End Audiophile Equipment
- Any equipment the requires the very best SABRE PRO™ audio digital-to-analog conversion



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Functional Block Diagram

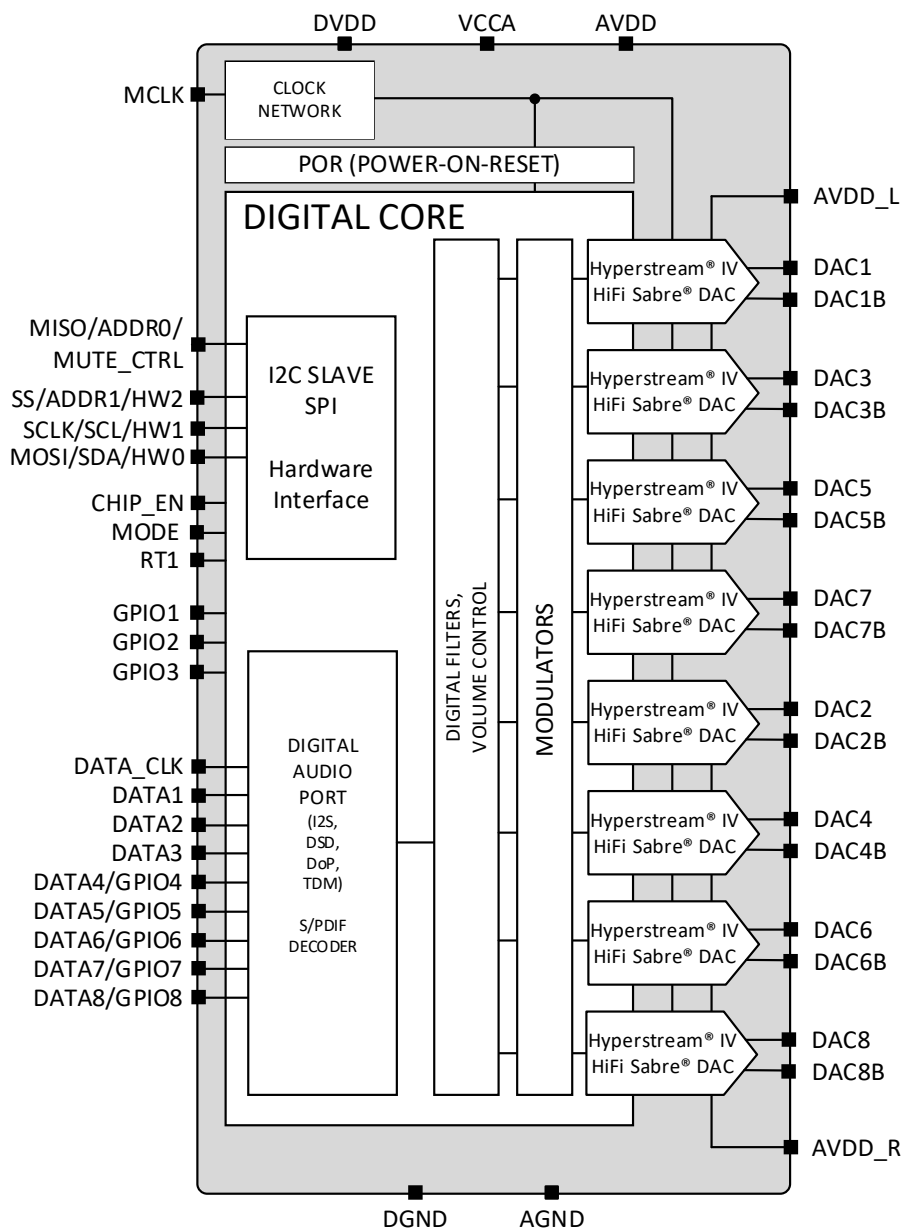


Figure 1 - Functional Block Diagram



ES9027PRO Pinout

48 QFN/QFP Pinout¹

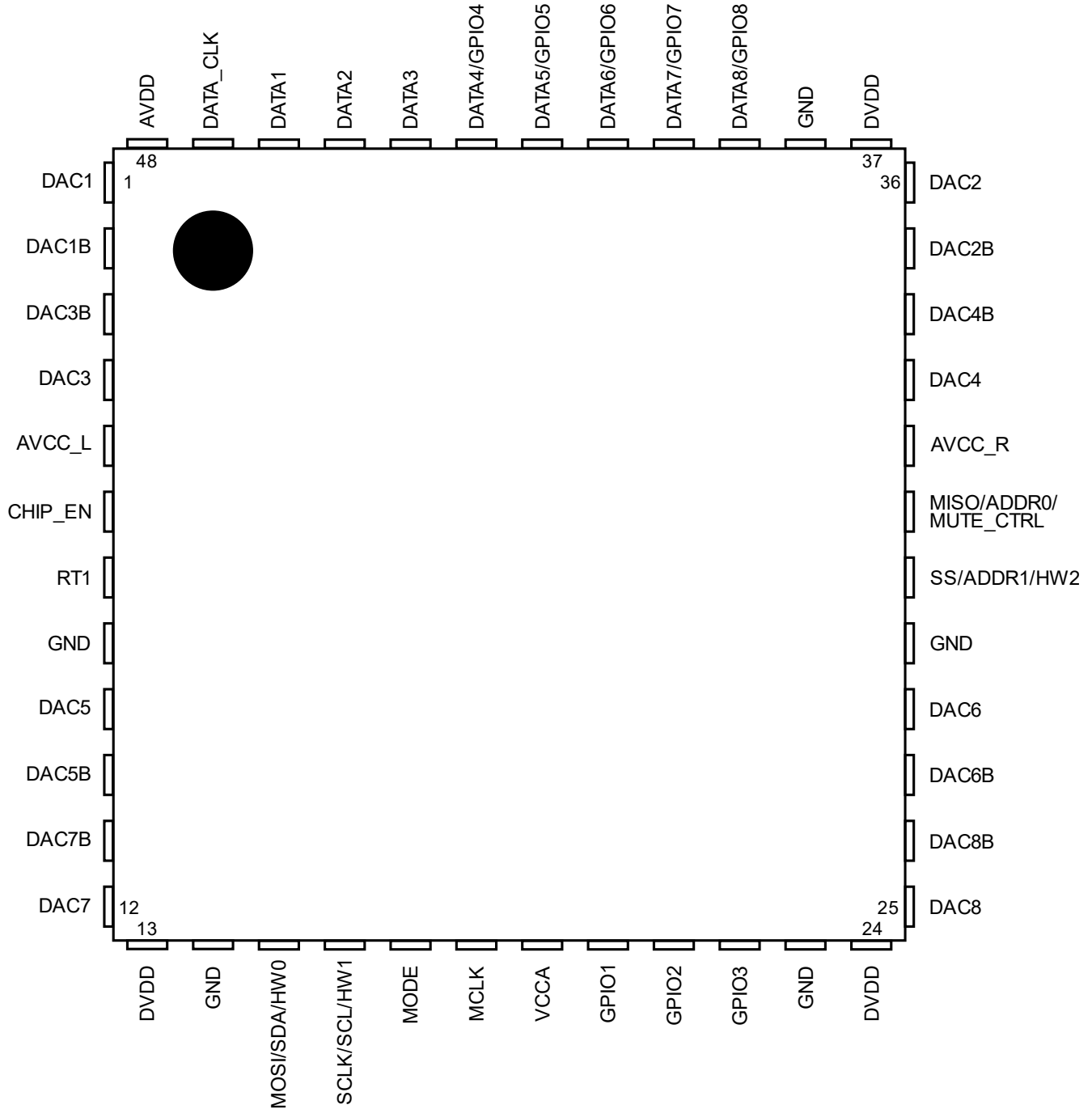


Figure 2 - 48 QFN/QFP Pinout

¹ Pin 49 is package pad and should be connected to Ground



48 QFN/QFP Pin Descriptions

Pin	Name	Pin Type	Reset State	Pin Description
1	DAC1	AO	Ground	Differential Positive Output for Channel 1
2	DAC1B	AO	Ground	Differential Negative Output for Channel 1
3	DAC3B	AO	Ground	Differential Negative Output for Channel 3
4	DAC3	AO	Ground	Differential Positive Output for Channel 3
5	AVCC_L	Power	Power	3.3V DAC analog output stage reference supply for the Left side
6	CHIP_EN	I	HiZ	Active-high Chip Enable
7	RT1	I	HiZ	Reserved. Must be connected to GND for normal operation.
8	GND	Ground	Ground	Ground
9	DAC5	AO	Ground	Differential Positive Output for Channel 5
10	DAC5B	AO	Ground	Differential Negative Output for Channel 5
11	DAC7B	AO	Ground	Differential Negative Output for Channel 7
12	DAC7	AO	Ground	Differential Positive Output for Channel 7
13	DVDD	Power	Power	Digital Core Supply, 1.2V
14	GND	Ground	Ground	Ground
15	MOSI	I	HiZ	SPI Main Out Sub In pin, controlled by MODE
	SDA			I ² C Serial Data pin, controlled by MODE
	HW0			Hardware 0 interface pin, controlled by MODE
16	SCLK	I	HiZ	SPI Serial Clock pin, controlled by MODE
	SCL			I ² C Serial Clock pin, controlled by MODE
	HW1			Hardware 1 interface pin, controlled by MODE
17	MODE	I	HiZ	I ² C /SPI Control selection or HW mode
18	MCLK	I	HiZ	Oscillator input
19	VCCA	Power	Power	Analog Supply, 3.3V
20	GPIO1	I/O	HiZ	General I/O w/extended functions
21	GPIO2	I/O	HiZ	General I/O w/extended functions
22	GPIO3	I/O	HiZ	General I/O w/extended functions
23	GND	Ground	Ground	Ground
24	DVDD	Power	Power	Digital Supply, 1.2V
25	DAC8	AO	Ground	Differential Positive Output for Channel 8
26	DAC8B	AO	Ground	Differential Negative Output for Channel 8
27	DAC6B	AO	Ground	Differential Negative Output for Channel 6
28	DAC6	AO	Ground	Differential Positive Output for Channel 6
29	GND	Ground	Ground	Ground
30	SS	I	HiZ	SPI Slave Select pin, controlled by MODE
	ADDR1			I ² C Address 1 pin, controlled by MODE
	HW2			Hardware 2 interface pin, controlled by MODE
31	MISO	I	HiZ	SPI Main In Sub Out pin, controlled by MODE
	ADDR0			I ² C Address 0 pin, controlled by MODE
	MUTE_CTRL			Hardware Mute Control pin, controlled by MODE
32	AVCC_R	Power	Power	3.3V DAC analog output stage reference supply for the Right side
33	DAC4	AO	Ground	Differential Positive Output for Channel 4
34	DAC4B	AO	Ground	Differential Negative Output for Channel 4
35	DAC2B	AO	Ground	Differential Negative Output for Channel 2
36	DAC2	AO	Ground	Differential Positive Output for Channel 2

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37	DVDD	Power	Power	Digital Supply, 1.2V
38	GND	Ground	Ground	Ground
39	DATA8	I/O	HiZ	Serial DATA8
	GPIO8			General I/O 8
40	DATA7	I/O	HiZ	Serial DATA7
	GPIO7			General I/O 7
41	DATA6	I/O	HiZ	Serial DATA6
	GPIO6			General I/O 6
42	DATA5	I/O	HiZ	Serial DATA5
	GPIO5			General I/O 5
43	DATA4	I/O	HiZ	Serial DATA4
	GPIO4			General I/O 4
44	DATA3	I	HiZ	Serial DATA3 pin
45	DATA2	I	HiZ	Serial DATA2 pin
46	DATA1	I	HiZ	Serial DATA1 pin
47	DATA_CLK	I	HiZ	Serial Data Clock pin
48	AVDD	Power	Power	3.3V I/O Supply
49	Package Pad ¹ (QFN package only)	-	-	Connect to ground

Table 1 - 48 QFN Pin Descriptions

*Note: AO = Analog Output, I = Digital Input, I/O = Digital Input/Output

¹ Pin 49 is the package pad. See QFN/QFP package dimensions for sizing. Connect to GND.



Feature List

The ES9027PRO is a SABRE 8 channel high performance digital to analog converter (DAC) with features and performance including the new Hyperstream IV modulator that produces a device that is well suited for all Audiophile and PRO Audio applications.

These features include TDM & SPI support as well as Hardware (HW) mode for simplifying configuration of the ES9027PRO.

TDM / I²S / LJ / RJ / DSD / DoP & S/PDIF interfaces are supported.

Sample rates up to 768kHz with PCM data and DSD rates up to DSD1024 are supported. 7 Selectable built-in digital filters are also available.

Configuration Modes

The ES9027PRO supports 2 different software modes (SPI or I²C) and supports 2 different sets of hardware modes (PCM or TDM/DSD). They are controlled by the state of the MODE Pin (Pin 17).

Mode Pin	Configuration
0	I ² C Interface
Pull Low	HW control mode (see Hardware Mode Table)
Pull High	HW control mode (see Hardware Mode Table)
1	SPI interface

Table 2 - Configuration Mode

Design Information

Hardware pins can be configured in 4 different ways. Each pin can be tied-high (1), pulled-high (Pull 1), pulled-low (Pull 0), or tied-low (0). HW0 and HW1 pins are always tied-high or tied-low. This also applies to MUTE_CTRL.

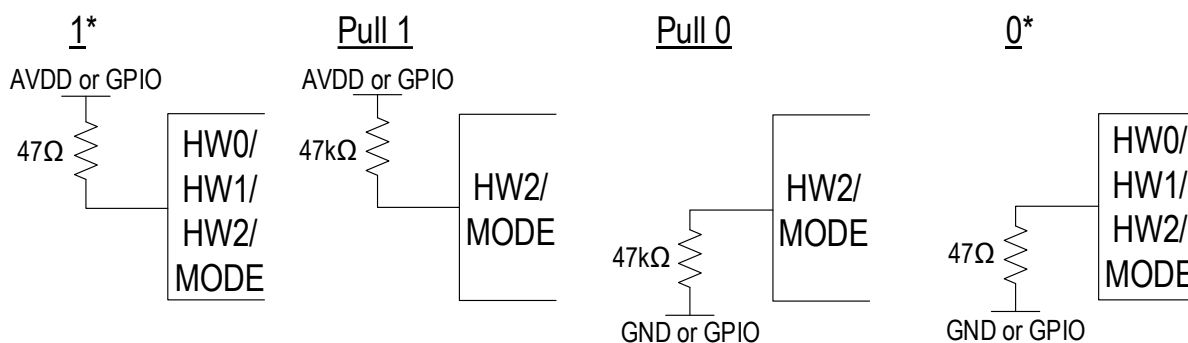


Figure 3 - Hardware Mode Pin Configurations

* Note: Hardware mode pins states 0 and 1 can be directly connected to GND or AVDD.



Software Mode

The ES9027PRO supports I²C or SPI serial communication. The ES9027PRO has read/write registers and read-only registers. Software modes are set with the MODE pin (Pin 17).

I²C Slave Interface Commands

The I²C slave interface is used when the MODE pin (Pin 17) is tied low (MODE=0). In I²C mode, ADDR1 (Pin 30) and ADDR0 (Pin 31) determine the I²C address and the R/W bit controls reading or writing.

For I²C Timing information, see Timing Characteristics.

The I²C Slave Interface can be accessed by:

- Pin 15 SDA
- Pin 16 SCL
- Pin 30 ADDR1
- Pin 31 ADDR0

I²C Slave Address = [5'b10010, ADDR1, ADDR0, R/W]

I ² C Slave Address	ADDR1	ADDR0
0x90	0	0
0x92	0	1
0x94	1	0
0x96	1	1

Table 3 - I²C Slave Addresses

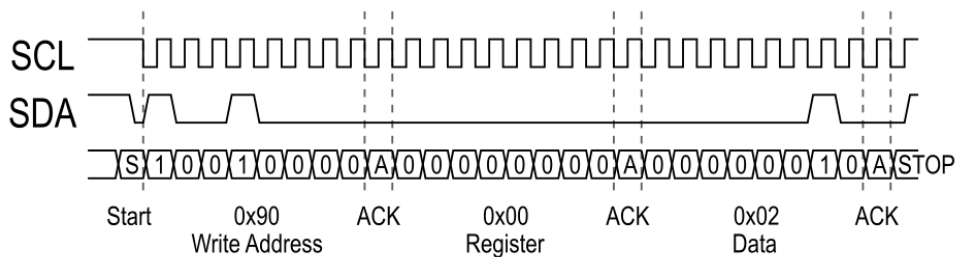


Figure 4 - I²C Write Example

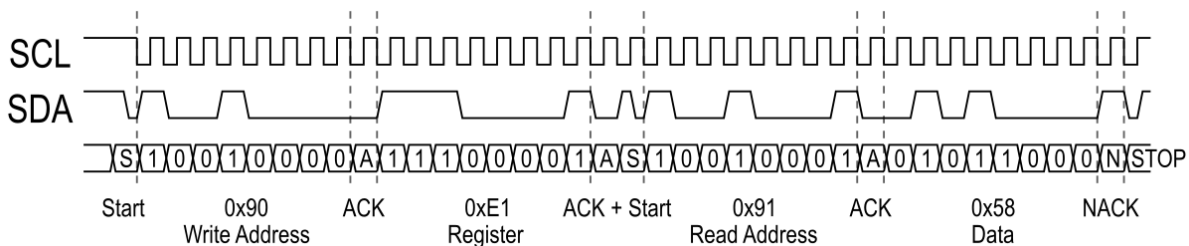


Figure 5 - I²C Read Example

Note: All bus transitions between start and stop must be part of the transaction when writing to the ESS device



SPI Slave Interface Commands

The Slave Serial Peripheral Interface (SPI) is used when the MODE pin (Pin 17) is tied high (MODE=1).

The SPI slave interface can be accessed using Pins 15, 16, 30, and 31:

- Pin 15 MOSI
- Pin 16 SCLK
- Pin 30 SS
- Pin 31 MISO

The 4-wire SPI data format is: Command (1 byte) + Address (1 byte) + Data.

SPI Commands:

- 0x01 Read
- 0x03 Write

For SPI Timing information, see Timing Characteristics.

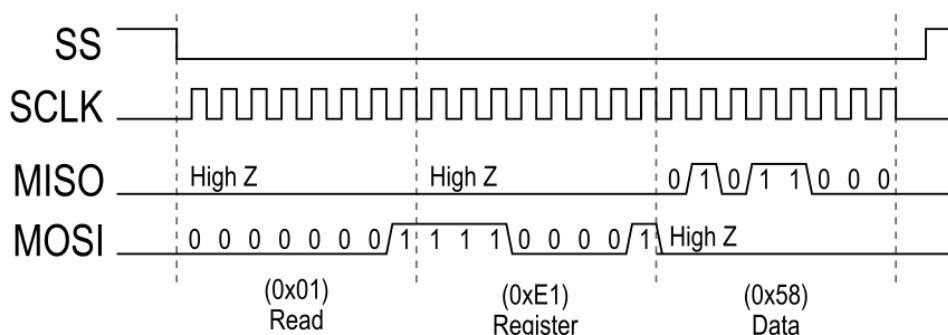


Figure 6 – SPI Single Byte Read

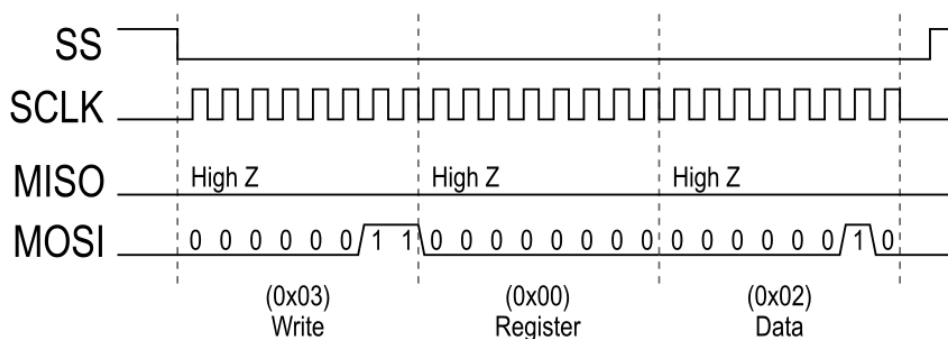


Figure 7 – SPI Single Byte Write



Hardware Mode

The ES9027PRO has 32 pre-configured modes that can be set with external pin configuration. These modes configure the DAC for different input serial data rates and set the DAC muting.

These modes are set with pins:

- MODE (Pin 17)
- HW0 (Pin 15)
- HW1 (Pin 16)
- HW2 (Pin 17)
- MUTE_CTRL (Pin 31)

Recommended Hardware Mode Startup Sequence

The hardware mode setup sequence is shown below with all hardware pins being defined after CHIP_EN is asserted.

Note: It is recommended that MUTE_CTRL is set low until CHIP_EN is asserted, then asserted last to unmute the DAC.

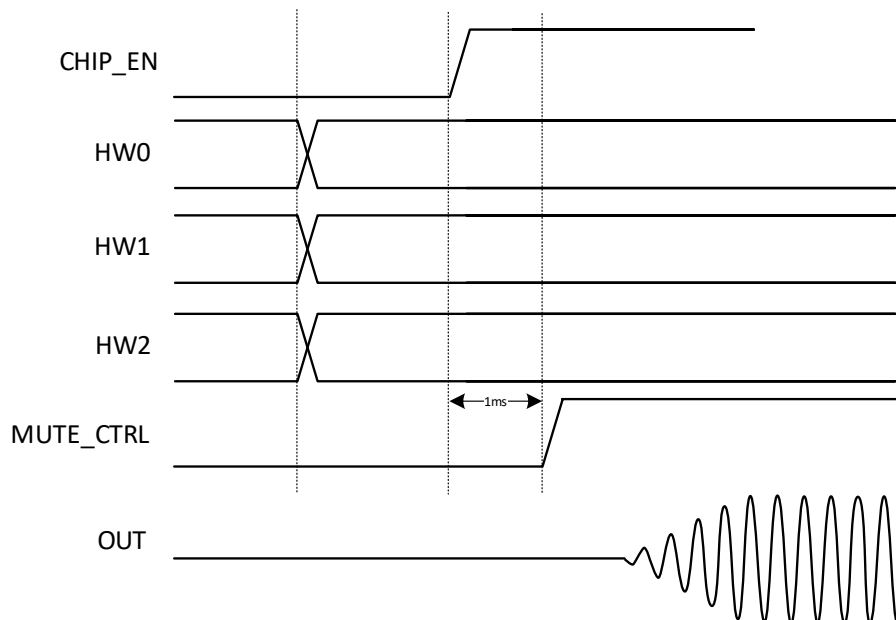


Figure 8 - Hardware Mode Startup Sequence



Hardware Mode Pin Configurations

HW#	Description	FS [kHz]	BCK [MHz]	MCLK [MHz]	MODE	HW2	HW1	HW0
32-bit PCM Master Modes								
0	I ² S Master	MCLK/128	MCLK/2 (64FS)	MCLK=128*FS ≤49.152	Pull 0	0	0	0
1	I ² S Master	MCLK/256	MCLK/4 (64FS)	MCLK=256*FS ≤49.152	Pull 0	0	0	1
2	I ² S Master	MCLK/512	MCLK/8 (64FS)	MCLK=512*FS ≤49.152	Pull 0	0	1	0
3	I ² S Master	MCLK/1024	MCLK/16 (64FS)	MCLK=1024*FS ≤49.152	Pull 0	0	1	1
4	LJ Master Mode	MCLK/128	MCLK/2 (64FS)	MCLK=128*FS ≤49.152	Pull 0	Pull 0	0	0
5	LJ Master Mode	MCLK/256	MCLK/4 (64FS)	MCLK=256*FS ≤49.152	Pull 0	Pull 0	0	1
6	LJ Master Mode	MCLK/512	MCLK/8 (64FS)	MCLK=512*FS ≤49.152	Pull 0	Pull 0	1	0
7	LJ Master Mode	MCLK/1024	MCLK/16 (64FS)	MCLK=1024*FS ≤49.152	Pull 0	Pull 0	1	1
32-bit PCM Slave Modes, SYNC								
8	I ² S Slave, SYNC, MCLK/1	8<FS<384	64FS	128*FS≤MCLK ≤49.152	Pull 0	Pull 1	0	0
9	I ² S Slave, SYNC, MCLK/2	8<FS<384	64FS	128*FS≤MCLK ≤49.152	Pull 0	Pull 1	0	1
10	I ² S Slave, SYNC, MCLK/4	8<FS<192	64FS	256*FS≤MCLK ≤49.152	Pull 0	Pull 1	1	0
11	I ² S Slave, SYNC, Auto Clock Gear ¹ (128FS)	8<FS<384	64FS	128*FS≤MCLK ≤49.152	Pull 0	Pull 1	1	1
12	LJ Slave, SYNC, MCLK/1	8<FS<384	64FS	128*FS≤MCLK ≤49.152	Pull 0	1	0	0
13	LJ Slave, SYNC, MCLK/2	8<FS<384	64FS	128*FS≤MCLK ≤49.152	Pull 0	1	0	1
14	LJ Slave, SYNC, MCLK/4	8<FS<192	64FS	256*FS≤MCLK ≤49.152	Pull 0	1	1	0
15	LJ Slave, SYNC, Auto Clock Gear ¹ (128FS)	8<FS<384	64FS	128*FS≤MCLK ≤49.152	Pull 0	1	1	1

¹ ACG (Auto Clock Gearing) will gear MCLK down to 128*FS, unless 64*FS is required, or 2*DSDCLK in DSD modes.

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HW#	Description	FS [kHz]	BCK [MHz]	MCLK [MHz]	MODE	HW2	HW1	HW0
32-bit PCM Slave Modes & S/PDIF, ASYNC								
16	S/PDIF ¹ , I ² S Slave, or DoP ² ASYNC, MCLK/1	8<FS<384	64FS	130*FS≤MCLK ≤49.152	Pull 1	0	0	0
17	S/PDIF ¹ , I ² S Slave, or DoP ² ASYNC, MCLK/2	8<FS<192	64FS	260*FS<MCLK ≤49.152	Pull 1	0	0	1
18	S/PDIF ¹ , I ² S Slave, or DoP ² ASYNC, MCLK/4	8<FS<96	64FS	520*FS≤MCLK ≤49.152	Pull 1	0	1	0
19	I ² S Slave, ASYNC, Auto Clock Gear (>130FS)	8<FS<384	64FS	130*FS≤MCLK ≤49.152	Pull 1	0	1	1
20	LJ Slave, ASYNC, MCLK/1	8<FS<384	64FS	130*FS≤MCLK ≤49.152	Pull 1	Pull 0	0	0
21	LJ Slave, ASYNC, MCLK/2	8<FS<192	64FS	260*FS<MCLK ≤49.152	Pull 1	Pull 0	0	1
22	LJ Slave, ASYNC, MCLK/4	8<FS<96	64FS	520*FS≤MCLK ≤49.152	Pull 1	Pull 0	1	0
23	LJ Slave, ASYNC, Auto Clock Gear (>130FS)	8<FS<384	64FS	130*FS≤MCLK ≤49.152	Pull 1	Pull 0	1	1
DSD & TDM LJ Slave Modes								
24	DSD Slave SYNC, MCLK/1	DSD64-512	64FS	4*FS ≤ MCLK ≤ 45.1584	Pull 1	Pull 1	0	0
25	DSD Slave SYNC, Auto Clock Gear (4*FS)	DSD64-512	64FS	4*FS ≤ MCLK ≤ 45.1584	Pull 1	Pull 1	0	1
26	DSD Slave ASYNC, MCLK/1	DSD64-512	64FS	6*FS ≤ MCLK ≤ 50	Pull 1	Pull 1	1	0
27	DSD Slave ASYNC, Auto Clock Gear (>6*FS)	DSD64-512	64FS	6*FS ≤ MCLK ≤ 50	Pull 1	Pull 1	1	1
28	TDM ³ LJ Slave SYNC, Autodetect (Slots 1 to 8)	8<FS<384	Auto (256FS, 512FS, 1024FS)	64*FS≤MCLK ≤49.152	Pull 1	1	0	0
29	TDM ³ LJ Slave SYNC, Autodetect (Slots 9 to 16)	8<FS<384	Auto (512FS, 1024FS)	128*FS≤MCLK ≤49.152	Pull 1	1	0	1
30	TDM ³ LJ Slave SYNC, Autodetect (Slots 17 to 24)	8<FS<192	Auto (1024FS)	256*FS≤MCLK ≤49.152	Pull 1	1	1	0
31	TDM ³ LJ Slave SYNC, Autodetect (Slots 25 to 32)	8<FS<192	Auto (1024FS)	256*FS≤MCLK ≤49.152	Pull 1	1	1	1

Table 4 - Hardware Mode Pin Configurations

¹ For S/PDIF in HW mode, DATA7/GPIO7 is the S/PDIF stream input. The ES9027PRO must be reset (CHIP_EN) when changing to and from S/PDIF.

² To enable DoP in HW mode, DATA8/GPIO8 pin must be high. S/PDIF will be auto detected.

³ TDM uses auto channel detect to determine the amount of channels. 8 Channels of data on a single data line is required in hardware mode to map to all 8 DACs. In software mode, 4 channels on 2 data lines is also supported.



GPIO Functions in Hardware Mode

The following GPIO pins add functionality in Hardware Modes. Unused GPIOs should be terminated to ground.

Pin	Functionality	Settings
GPIO1	Outputs Automute Status	Output 0: Automute not engaged Output 1: Automute engaged
GPIO2	SRC Locked Status	Output 0: SRC is unlocked or in SYNC mode Output 1: SRC is locked and in ASYNC mode
GPIO3	Calibration Resistor	~100kΩ
DATA6/GPIO6	Sets FILTER_SHAPE in Hardware Mode	1'b0: Minimum Phase 1'b1: Linear Phase Fast Roll-Off
DATA7/GPIO7	S/PDIF Input Stream ¹	The ES9027PRO must be reset (CHIP_EN) when changing to and from S/PDIF.
DATA8/GPIO8	Enables the DoP decoder ²	1'b0: DoP Disabled 1'b1: DoP Enabled

Table 5 - GPIO Functions in Hardware Mode

Mute Control

MUTE_CTRL (Pin 31) is used to control the muting of the output and enabling of the Automute feature while in Hardware Mode:

- 0 - Output Muted, No Automute
- 1 - Output Unmuted, No Automute
- Pull 0 - Output Muted, Automute Enabled
- Pull 1- Output Unmuted, Automute Enabled

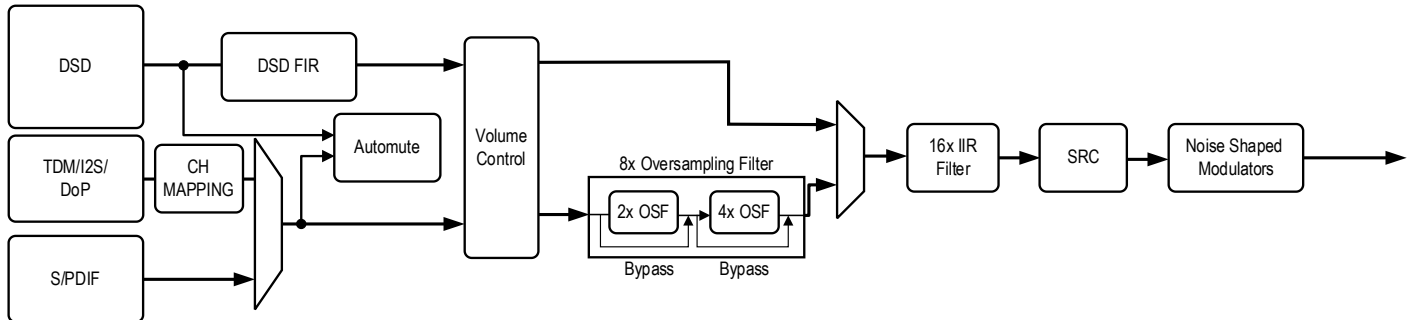
¹ S/PDIF is only supported in HW modes 16-18

² DoP is only supported in HW modes 16-18



Digital Features

Digital Signal Path



Note: Channel Mapping is only available with the TDM, I²S & DoP interface.

GPIO Configuration

GPIO_CONFIG	Function	I/O Direction
0	Analog Shutdown	N/A
1	Output 1'b0	Output
2	Output1'b1	Output
3	CLK_IDAC	Output
4	OR of All Interrupts	Output
5	Mute All DAC Channels	Input
6	Input Selection	Input
7	SRC Lock status	Output
8	CLKEN_1FS	Output
9	PWM1	Output
10	PWM2	Output
11	PWM3	Output
12	Volume min	Output
13	Automute status	Output
14	Soft Ramp finished	Output
15	Reserved	Output

Table 6 - Standard GPIO Functions

GPIOx Default states:

- GPIO1: Automute Status
- GPIO2: SRC Locked Status
- GPIO3: Calibration Resistor¹
- GPIO4-8: Analog Shutdown

¹ To use GPIO3 in a different mode than Calibration Resistor, Register 34[6] CAL_RES_ENB must be set.



Analog Shutdown

Analog Shutdown is input disabled, output is tri-stated.

Output 1'b0

Outputs a constant 1'b0.

Output 1'b1

Outputs a constant 1'b1.

CLK_IDAC

Outputs the CLK_IDAC clock. Requires DAC to be on.

OR of All Interrupts

Bitwise OR of all masked interrupts.

Relevant Registers

- Register 10 INTERRUPT VOL MIN MASKP
- Register 11 INTERRUPT AUTOMUTE MASKP
- Register 12 SS FULL RAMP MASKP
- Register 13-14 INTERRUPT MASKP
- Register 15 INTERRUPT VOL MIN MASKN
- Register 16 INTERRUPT AUTOMUTE MASKN
- Register 17 SS FULL RAMP MASKN
- Register 18-19 INTERRUPT MASKN

Mute All DAC Channels

Mute all DAC Channels

System Mode Control

Change the system mode (enable/disable datapath) via GPIO. Register 46-47[15] GPIO_DAC_MODE changes whether a 1 on the GPIO will enable or disable the datapath.

When GPIOx input is 1'b0, the system mode will be determined by Register 0[1] DAC_MODE_REG.

Relevant Registers

- Register 46-47[15] GPIO_DAC_MODE
 - 1'b0: Disable datapath when GPIOx input is 1'b1
 - 1'b1: Enable datapath when GPIOx input is 1'b1
- Register 0[1] DAC_MODE_REG

SRC Locked Status

SRC (Sample Rate Converter) locked status output. Outputs LOW if the device is in a synchronous mode, outputs HIGH if the device is in asynchronous mode and the SRC is locked.

Relevant Registers

- Register 1[6] SYNC_MODE

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- Must be = 0 (default) for the ES9027PRO to be in ASYNC mode, enabling the SRC.

CLKEN_1FS

Outputs the CLKEN_1FS clock, which is a clock with an output every 1FS.

PWM1/PWM2/PWM3

Output a configurable PWM signal. The frequency and duty cycle of the PWM signal can be calculated with the following equations:

$$frequency [Hz] = \frac{MCLK}{PWM_FREQ + 1}$$

$$Duty Cycle [\%] = \left(\frac{PWM_COUNT}{PWM_FREQ + 1} \right) \times 100$$

Relevant Registers

- Register 48 PWM1_COUNT
- Register 49-50 PWM1_FREQ
- Register 51 PWM2_COUNT
- Register 52-53 PWM2_FREQ
- Register 54 PWM3_COUNT
- Register 55-56 PWM3_FREQ

Volume min

Outputs HIGH when the DAC is muted. This can occur from manually muting, automuting, and setting the volume registers to 0xFF.

The output can be a channel specific flag, the logical AND of all flags (default), or the logical OR of all the flags.

Relevant Registers

- Register 46-47[4] GPIO_OR_VOL_MIN sets the output to be the logical AND of all channels' vol min flags.
- Register 46-47[1] GPIO_AND_VOL_MIN sets the output to be the logical OR of all channels' vol min flags.
- Register 46-47[8:6] FLAG_CH_SEL selects which of the individual DAC channel flags to output.

Automute status

Outputs HIGH when the DACs automute condition is met. The output can be a channel specific flag, the logical AND of all flags (default), or the logical OR of all the flags.

Relevant Registers

- Register 46-47[3] GPIO_OR_AUTOMUTE sets the output to be the logical OR of all channels' automute flags
- Register 46-47[0] GPIO_AND_AUTOMUTE sets the output to be the logical AND of all channels' automute flags
- Register 46-47[8:6] FLAG_CH_SEL sets the output to be one of the individual channels' flags

**Soft Ramp finished**

Outputs HIGH when the DAC is not in the process of ramping up or down. The output can be a channel specific flag, the logical AND of all flags (default), or the logical OR of all the flags.

Relevant Registers

- Register 46-47[5] GPIO_OR_SS_RAMP sets the output to be the logical OR of all channels soft ramp flags
- Register 46-47[2] GPIO_AND_SS_RAMP sets the output to be the logical AND of all channels soft ramp flags
- Register 46-47[8:6] FLAG_CH_SEL sets the output to be one of the individual channels' flags



Audio Input Formats

The ES9027PRO supports multiple serial input data formats. Input format is selected either through Hardware Mode or Software Mode.

The ES9027PRO can automatically determine the input data format by enabling Register 57[0] AUTO_INPUT_SEL, data must be provided on the DATA2 pin, to properly decode the input format. The input data format can also be selected using Register 57[2:1] INPUT_SEL.

For Hardware Mode see Table 4 - Hardware Mode Pin Configurations for inputs.

The formats include:

- PCM
 - Slave and master mode in 16, 24, 32-bit widths
 - I²S, Left Justified (LJ), and Right Justified (RJ)
 - TDM up to TDM1024 mode with 32 slots including daisy chain mode
 - Sample rates up to 768kHz (64fs mode)
 - Channel Remapping & Invert
- DoP (DSD Over PCM)
 - Slave and master mode
 - Sample rates from DoP512 (24bit, 1.4112MHz PCM)
 - Channel Remapping & Invert
- Native DSD
 - Slave and master mode
 - Sample rates from DSD64 (2.8224Mbits.sec, 64 x 44.1kHz) to DSD1024
 - Channel Remapping & Invert
- S/PDIF
 - Stereo data input



PCM (I²S/LJ)

Data is organized into 2 channels per data line. Any channel on any data line can be mapped to any DAC through the TDM_CHx_CONFIG channel mapping Register 64-71. Data is latched on the positive edge of BCLK. Data lines in hardware mode use the default configuration.

In hardware mode, PCM (I²S/LJ) data lines are fixed to the mapping shown in the table below.

In software mode, PCM (I²S/LJ) data lines can be re-mapped to any DAC.

PCM Pin Connections (default configuration):

Pin Name	Function	Description
DATA_CLK	PCM BCLK	PCM Clock (Bit Clock), Master or Slave
DATA1	PCM WS	PCM WS (Word Select/Frame Select), Master or Slave
DATA2	PCM DATA	PCM Data Channel 1 & 2
DATA3	PCM DATA	PCM Data Channel 3 & 4
DATA4	PCM DATA	PCM Data Channel 5 & 6
DATA5	PCM DATA	PCM Data Channel 7 & 8

Table 7 - PCM Pin Connections

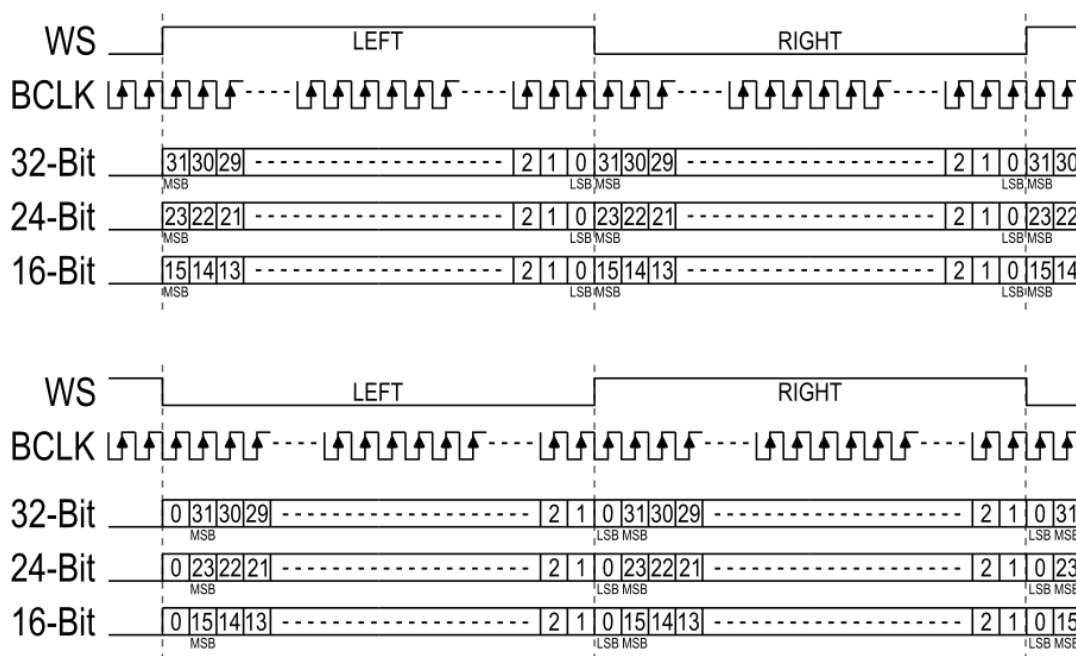


Figure 9 - LJ (top) & I²S (bottom) for 16,24, and 32-bit Word Widths

Note: RJ is only supported in software mode



TDM (Time-Division Multiplexing)

ES9027PRO supports time-division multiplexing (TDM) format, allowing more than 2 channels (or slots) to be transmitted on each data line, up to a maximum of 32 channels per data line. Typical formats are TDM128 (4chx32bit), TDM256 (8chx32bit), TDM512 (16chx32bit) and TDM1024 (32chx32bit). In this mode, the TDM_CHx_CONFIG channel mapping Registers 64-71 can be used to internally map any slot (channel) to any DAC. Data is latched on the positive edge of BCLK. Data lines in hardware mode use the default configuration.

TDM Pin Connection (default configuration):

Pin Name	Function	Description
DATA_CLK	TDM BCLK	TDM Clock, Master or Slave
DATA1	TDM WS	TDM WS (Word Select/Frame Select), Master or Slave
DATA2	TDM DATA	TDM DATA Channel 1 & 2 (default)
DATA3	TDM DATA	TDM DATA Channel 3 & 4 (default)
DATA4	TDM DATA	TDM DATA Channel 5 & 6 (default)
DATA5	TDM DATA	TDM DATA Channel 7 & 8 (default)

Table 8 - TDM Pin Connections

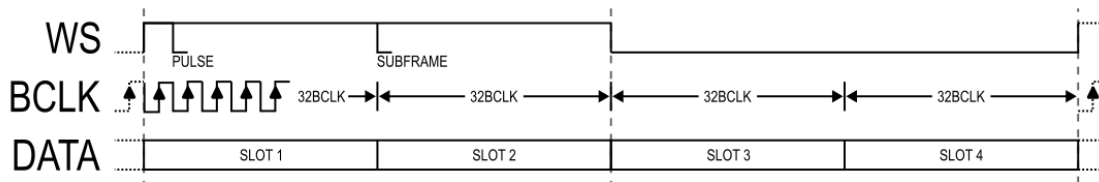


Figure 10 - TDM4 Mode

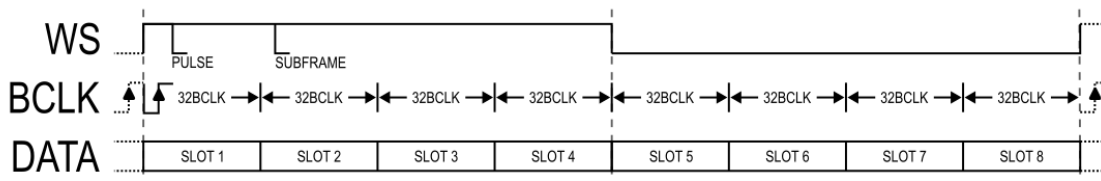


Figure 11 - TDM8 Mode

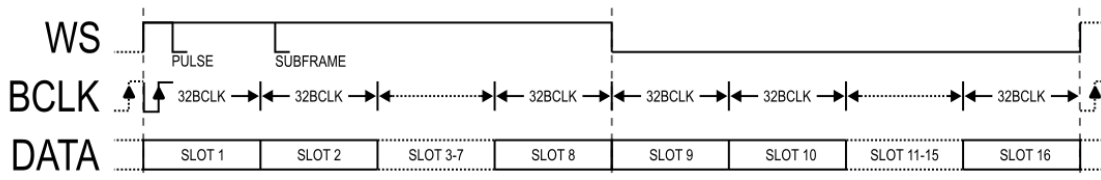


Figure 12 - TDM16 Mode



DSD¹

In DSD mode, there is a single DSD clock line, and each channel of data is an additional DSD data line. There is no internal channel mapping for DSD input, DSD data input to DATA1 is sent to Ch1, DSD data input to DATA2 is sent to Ch2, etc.

For 4 channel and 2 channel applications, the interpolation path data can be copied from DAC1+DAC2 to the other DAC pairs, see Register 0[5:2] for details.

Data lines in hardware mode use the default configuration.

DSD Pin Connections (default configuration):

Pin Name	Function	Description
DATA_CLK	DSD CLK	DSD Clock
DATA1	DSD CH1	DSD DATA Channel 1
DATA2	DSD CH2	DSD DATA Channel 2
DATA3	DSD CH3	DSD DATA Channel 3
DATA4	DSD CH4	DSD DATA Channel 4
DATA5	DSD CH5	DSD DATA Channel 5
DATA6	DSD CH6	DSD DATA Channel 6
DATA7	DSD CH7	DSD DATA Channel 7
DATA8	DSD CH8	DSD DATA Channel 8

Table 9 - DSD Pin Connections

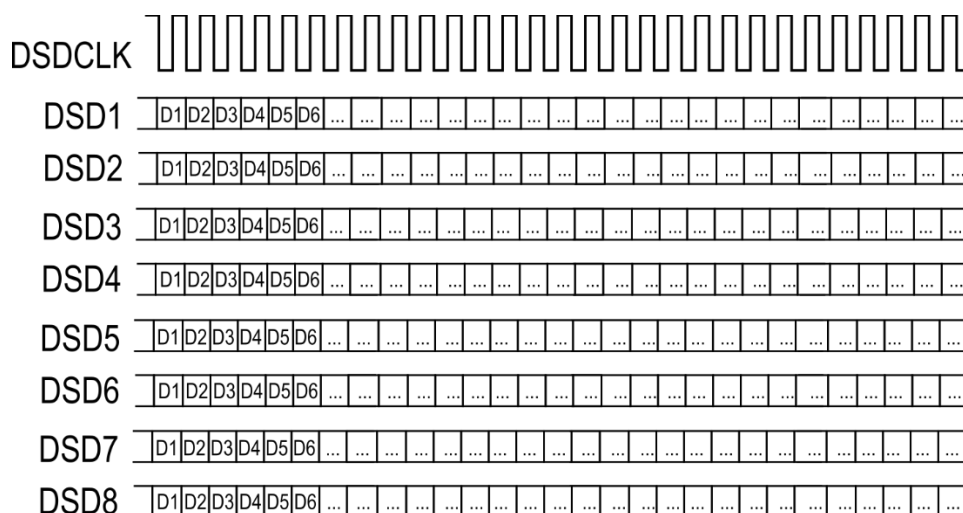


Figure 13 - DSD Format, 1bit Stream

¹ The Automute Feature is not available when using DSD mode



S/PDIF

S/PDIF is transmitted over a single signal line using dual phase encoded data, which allows for clock extraction from the data signal line.

In S/PDIF mode, there is only stereo data input. Channel 1 data will be sent to all odd channel DACs, Channel 2 data will be sent to all even channel DACs.

Note: Toggle Register 58[6] BCK_INV after switching to S/PDIF input. A reset (CHIP_EN) is not required in SW mode as it is noted in Hardware (HW) mode.



Pre-Programmed Digital Filters

The ES9027PRO has 7 pre-programmed digital filters. The latency for each filter reduces (scales) with increasing sample rates. (See Register 88[2:0] FILTER_SHAPE for configuration)

#	Filter	Description
1	Minimum Phase (default)	Version 2 of minimum phase fast roll-off (#5) with less ripple and more image rejection
2	Linear Phase Apodizing Fast Roll-Off	Full image rejection by FS/2 to avoid any aliasing, with smooth roll-off starting before 20k.
3	Linear Phase Fast Roll-Off	Sabre legacy filter, optimized for image rejection @ 0.55FS
4	Linear Phase Slow Roll-Off	Sabre legacy filter, optimized for lower latency, but symmetric impulse response
5	Minimum Phase Fast Roll-Off	Low latency, minimal pre ringing and low passband ripple, image rejection @ 0.55FS
6	Minimum Phase Slow Roll-Off	Lowest latency at the cost of image rejection
7	Minimum Phase Fast Roll-Off Low Dispersion	Provides a nice balance of the low latency of minimum phase filters and the low dispersion of linear phase filters. Minimal pre-ringing is added to achieve the low dispersion in the audio band.

Table 10 - Pre-Programmed Digital Filter Descriptions

Note: Minimum phase filters are asymmetric filters that work to minimize the pre-echo of the filter, while still maintaining an excellent frequency response and they peak earlier than linear phase filters, resulting in a lower group delay. Minimum phase filters usually feature zero cycles of pre-echo, which can result in improved audio quality.

PCM Filter Latency

The following table shows the simulated latency of each filter at 44.1kHz sampling rate. Measurements were taken from the external impulse response. The extra sample delay to get the data encoded accounts for external processing time to serialize the data stream. Latency will reduce (scale) with sampling rate.

Digital Filter	Delay(us) @ FS = 44.1kHz
Minimum Phase (default)	164us
Linear Phase Apodizing Fast Roll-Off	830us
Linear Phase Fast Roll-Off	844us
Linear Phase Slow Roll-Off	219us
Minimum Phase Fast Roll-Off	164us
Minimum Phase Slow Roll-Off	142us
Minimum Phase Fast Roll-Off Low Dispersion	301us

Table 11 - PCM Filter Latency



PCM Filter Properties

Minimum Phase					
Parameter	Conditions	MIN	TYP	MAX	UNIT
Pass band				0.46FS	Hz
Stop band	-97dB	0.55FS			Hz
Group Delay		2.90/FS		8.99/FS	s
Flatness (ripple)	0.0012				dB

Linear Phase Apodizing					
Parameter	Conditions	MIN	TYP	MAX	UNIT
Pass band				0.41FS	Hz
Stop band	-107dB	0.50FS			Hz
Group Delay			32.81/FS		s
Flatness (ripple)	0.0024				dB

Linear Phase Fast Roll-Off					
Parameter	Conditions	MIN	TYP	MAX	UNIT
Pass band				0.45FS	Hz
Stop band	-117dB	0.55FS			Hz
Group Delay			33.43/FS		s
Flatness (ripple)	0.0030				dB

Linear Phase Slow Roll-Off					
Parameter	Conditions	MIN	TYP	MAX	UNIT
Pass band	-3dB			0.44FS	Hz
Stop band	-91dB	0.75FS			Hz
Group Delay			5.87/FS		s
Flatness (ripple)					dB

Minimum Phase Fast Roll-Off					
Parameter	Conditions	MIN	TYP	MAX	UNIT
Pass band				0.46FS	Hz
Stop band	-98dB	0.55FS			Hz
Group Delay		2.91/FS		9.14/FS	s
Flatness (ripple)	0.0023				dB



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Minimum Phase Slow Roll-Off					
Parameter	Conditions	MIN	TYP	MAX	UNIT
Pass band	-3dB			0.43FS	Hz
Stop band	-91dB	0.80FS			Hz
Group Delay		2.08/FS		3.56/FS	s
Flatness (ripple)					dB

Minimum Phase Slow Roll-Off Low Dispersion					
Parameter	Conditions	MIN	TYP	MAX	UNIT
Pass band	-3dB			0.43FS	Hz
Stop band	-91dB	0.80FS			Hz
Group Delay		9.32/FS		9.93/FS	s
Flatness (ripple)					dB

Table 12 - PCM Filter Properties



PCM Filter Frequency Response

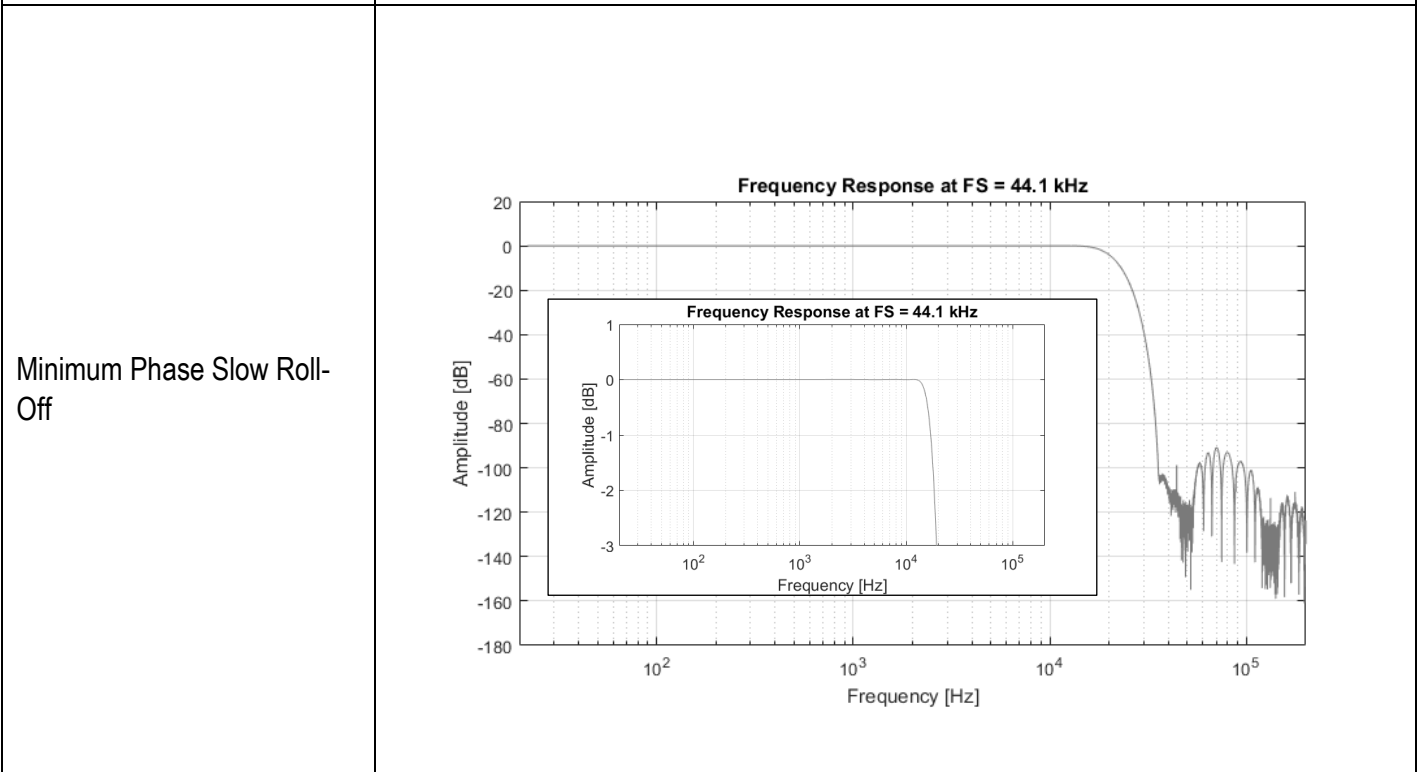
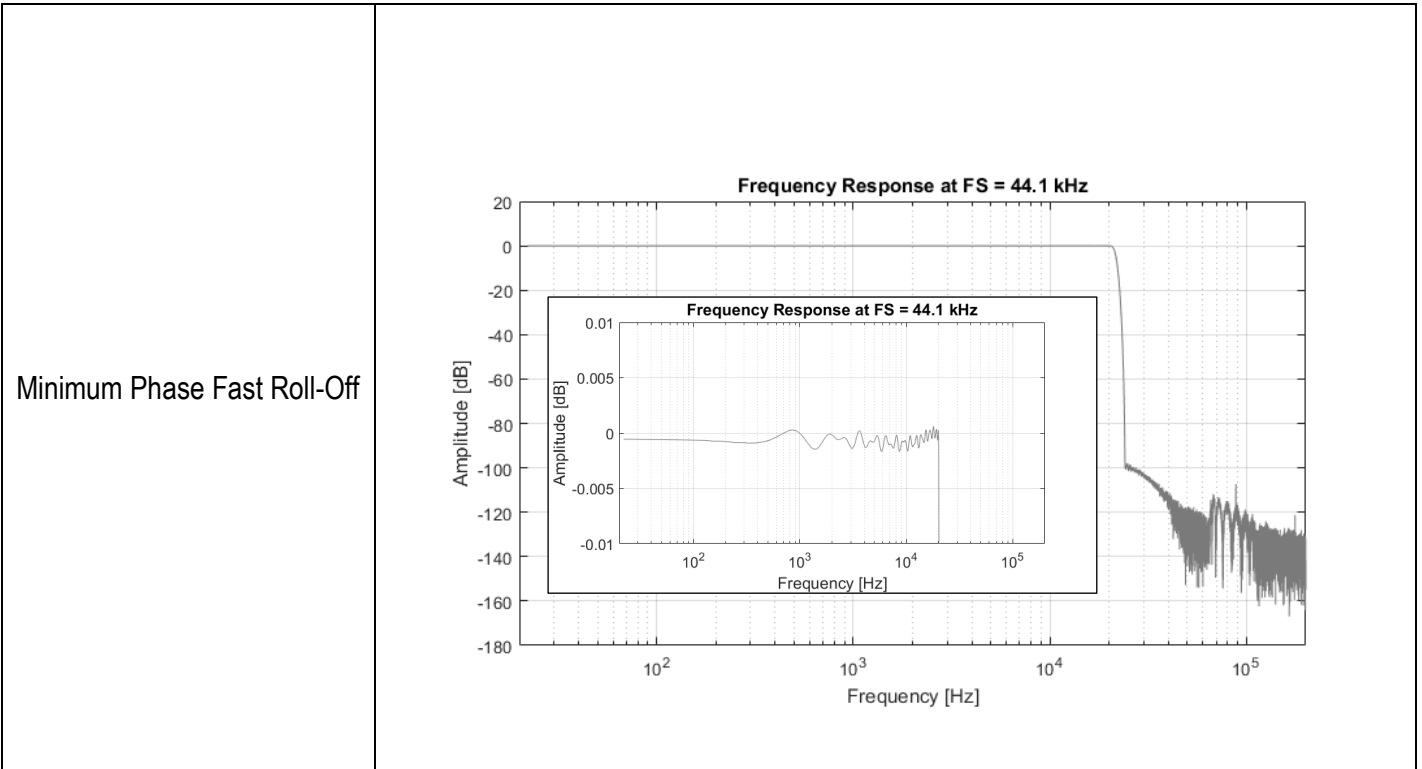
The following frequency responses were obtained from software simulations of these filters. Simulation sample rate is 44.1kHz.

Filter	Frequency Response
Minimum Phase	
Linear Phase Apodizing	



<p>Linear Phase Fast Roll-Off</p>	<p>The graph shows the frequency response for a fast roll-off filter. The main plot has a logarithmic x-axis for Frequency [Hz] from 10² to 10⁵ and a linear y-axis for Amplitude [dB] from -180 to 20. The response is flat at 0 dB until approximately 10⁴ Hz, then drops sharply to -120 dB by 10⁵ Hz. An inset plot zooms in on the 10² to 10⁵ Hz range, showing a flat line at 0 dB until about 10⁴ Hz, followed by a sharp drop to -120 dB. The inset y-axis ranges from -0.01 to 0.01 dB.</p>
<p>Linear Phase Slow Roll-Off</p>	<p>The graph shows the frequency response for a slow roll-off filter. The main plot has a logarithmic x-axis for Frequency [Hz] from 10² to 10⁵ and a linear y-axis for Amplitude [dB] from -180 to 20. The response is flat at 0 dB until approximately 10⁴ Hz, then rolls off gradually to -120 dB by 10⁵ Hz. An inset plot zooms in on the 10² to 10⁵ Hz range, showing a flat line at 0 dB until about 10⁴ Hz, followed by a gradual roll-off to -120 dB. The inset y-axis ranges from -3 to 1 dB.</p>

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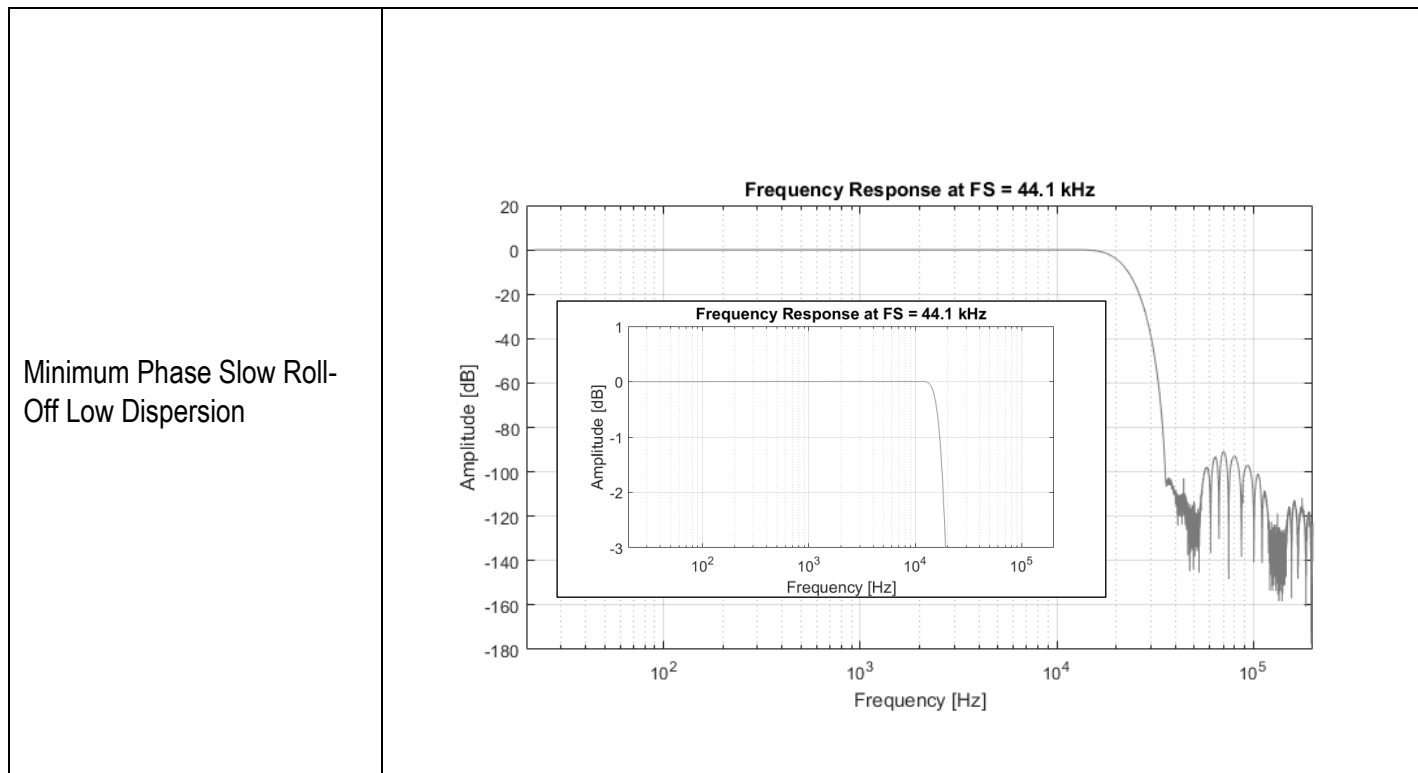


Table 13 - PCM Filter Frequency Response



PCM Filter Impulse Response

The following impulse responses were obtained from software simulations of these filters. They were measured from external impulse response. The extra sample delay to get the data encoded accounts for external processing time to serialize the data stream.

Filter	Impulse Response
<p>Minimum Phase</p>	
<p>Linear Phase Apodizing</p>	



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<p>Linear Phase Fast Roll-Off</p>	
<p>Linear Phase Slow Roll-Off</p>	
<p>Minimum Phase Fast Roll-Off</p>	



<p>Minimum Phase Slow Roll-Off</p>	
<p>Minimum Phase Slow Roll-Off Low Dispersion</p>	

Table 14 - PCM Filter Impulse Response



64FS Mode

When 64FS (MCLK/FS ratio) is required, it is necessary for the ES9027PRO to be running in 64FS Mode. 64FS Mode can be enabled by setting:

Software Register

- Register 0[6] ENABLE_64FS_MODE = 1'b1
 - Manually enables 64FS mode
 - Should be used with high samples rates 705.6kHz & 768kHz
- Register 3[7] AUTO_FS_DETECT = 1'b1
 - Auto tunes the CLK_DAC/CLK_IDAC ratio according to detected sampling frequency
 - Automatically enables 64FS mode when CLK_DAC/CLK_IDAC ratio is 64
 - Must be in SYNC mode

Note: 64FS mode is only supported in Software Mode (SW)

Minimum Phase 64FS Latency

The following table shows the simulated latency at 705.6kHz sampling rate and would be very similar at 768kHz. Measurements were taken from the external impulse response. The extra sample delay to get the data encoded accounts for external processing time to serialize the data stream. Latency delay will reduce (scale) with sampling rate.

Digital Filter	Delay(us) @ FS = 705.6 kHz
Minimum Phase 64FS	8 μ s

Table 15 - Minimum Phase 64FS Latency

Minimum Phase 64FS Properties

Minimum Phase 64FS					
Parameter	Conditions	MIN	TYP	MAX	UNIT
Pass band	-3dB			0.45FS	Hz
Stop band	-62dB	0.68FS			Hz
Group Delay		1.55/FS		2.35/FS	s
Flatness (ripple)					dB

Table 16 - Minimum Phase 64FS Properties



Minimum Phase 64FS Frequency Response

This filter gets selected automatically when $MCLK/FS = 64$. The following frequency response was obtained from software simulations with a sample rate of 705.6kHz.

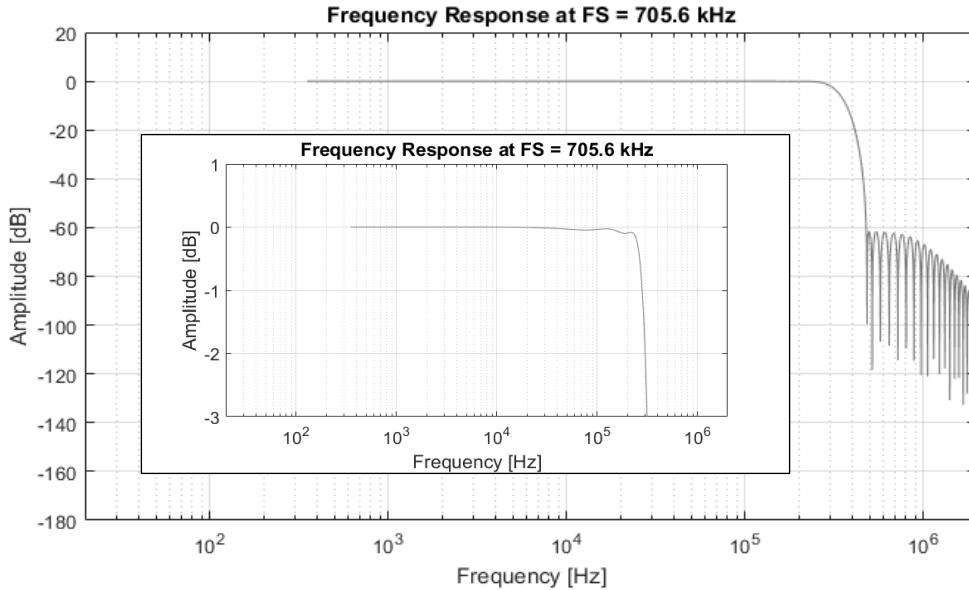


Figure 14 - Minimum Phase 64FS Frequency Response

Minimum Phase 64FS Impulse Response

The following impulse response was obtained from software simulations. It was measured from the external impulse response. The extra sample delay to get the data encoded accounts for external processing time to serialize the data stream.

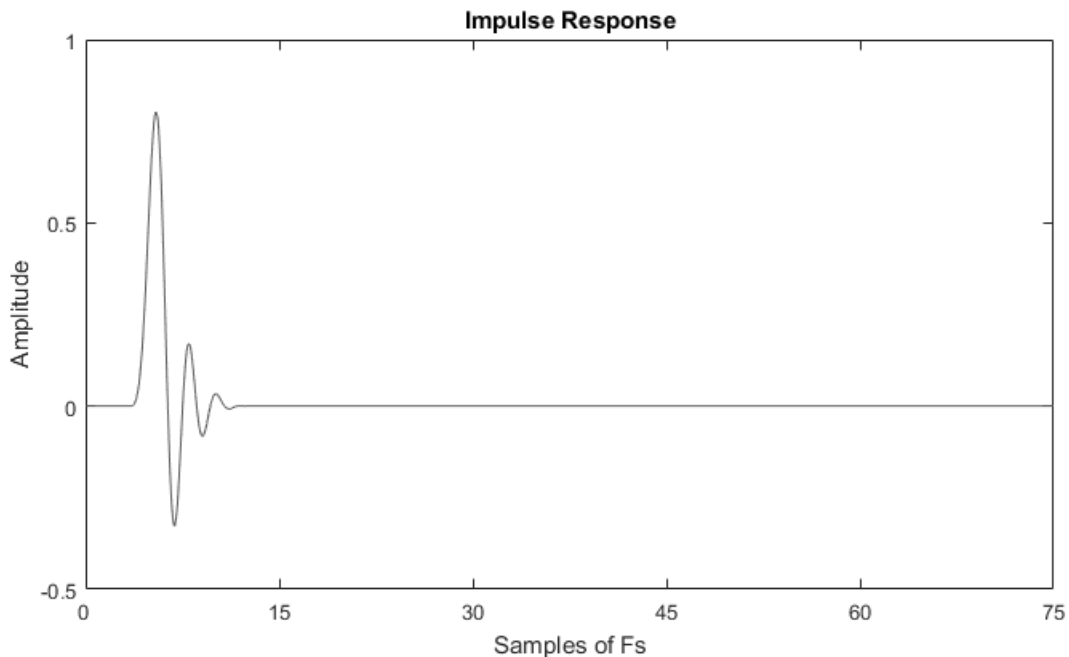


Figure 15 - Minimum Phase 64FS Impulse Response



Analog Features

Calibration Resistor

The ES9027PRO features a $\sim 100\text{k}\Omega$ calibration resistor accessible through GPIO3 (Pin 22) and terminated to ground as shown in the below figure. The calibration resistor is enabled by default in both Hardware and Software Mode and can be disabled in SW Mode with Register 34[6] CAL_RES_ENB = 1.

ESS' ES9312 features a calibration mode that can be paired with the ES9027PRO to compensate AVCCCL and AVCCR supplies. The ES9312 connects to the ES9027PRO integrated calibration resistor and adjusts the output supplies to maintain a tighter distribution on the output level in an application. See Recommended Power Supply for connections.

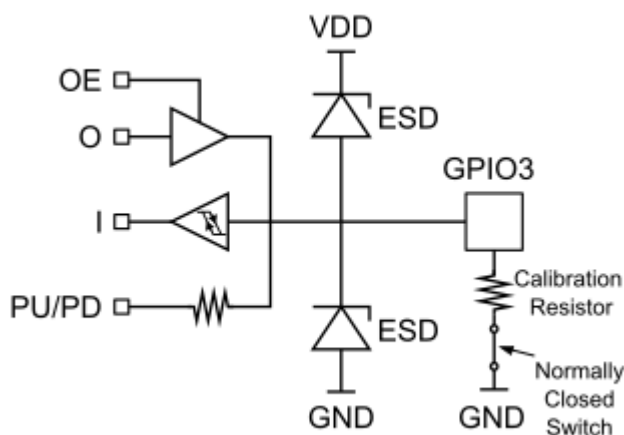


Figure 16 – GPIO3 Digital I/O with Calibration Resistor



Absolute Maximum Ratings

PARAMETER	RATING
Positive Supply Voltage <ul style="list-style-type: none"> • AVCC_L • AVCC_R • AVDD • VCCA • DVDD 	<ul style="list-style-type: none"> • +3.7V with respect to Ground • +3.7V with respect to Ground • +3.7V with respect to Ground • +3.7V with respect to Ground • +1.4V with respect to Ground
Storage temperature	-65°C to +150°C
Operating Junction Temperature	+125°C
Voltage range for digital input pins	-0.3V to AVDD (nom) +0.3V

Table 17 - Absolute Maximum Ratings

WARNING: Stresses beyond those listed under here may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied.

WARNING: Electrostatic Discharge (ESD) can damage this device. Proper procedures must be followed to avoid ESD when handling this device.

ESD Ratings

ESD Standard	Rating
Human Body Model (HBM), ANSI/ESDA/JEDEC JS-001	2kV
Charge Device Model (CDM), ANSI/ESDA/JEDEC JS-002	500V

Table 18 - ESD Ratings

IO Electrical Characteristics

PARAMETER	SYMBOL	MINIMUM	MAXIMUM	UNIT
High-level input voltage	VIH	$(AVDD / 2) + 0.4$		V
Low-level input voltage	VIL		0.4	V
High-level output voltage	VOH	$AVDD - 0.2$		V
Low-level output voltage	VOL		0.2	V

Table 19 - IO Electrical Characteristics



Switching Characteristics

Synchronous Mode

Parameter	Notes	Min.	Typ.	Max.	Unit
MCLK¹					
Frequency		44.1kHz*128	-	49.152	MHz
Duty Cycle		45	-	55	%
PCM Mode²					
WS Frequency (Word Select Clock)		8	-	384	kHz
BCLK Frequency (Bit Clock)		0.256	TDM_BIT_WIDTH)* (TDM_CH_NUM+1)*WS	24.576	MHz
WS Frequency (Word Select Clock)	64FS Mode ³	352.8	MCLK/64	768	kHz
BCLK Frequency (Bit Clock)		22.5792	MCLK	49.152	MHz
TDM Mode					
WS Frequency (Word Select Clock)	TDM4	8	-	MCLK/128	kHz
	TDM8		-	MCLK/256	kHz
	TDM16		-	MCLK/512	kHz
	TDM32		-	MCLK/1024	kHz
BCLK Frequency (Bit Clock)		(16*2*WS)	(TDM_BIT_WIDTH)* (TDM_CH_NUM+1)*WS	MCLK	MHz
DSD Mode					
DSD Clock Frequency		2.8224	-	MCLK/2	MHz

Table 20 - Synchronous Switching Characteristics

¹ MCLK is Synchronous to the digital serial audio clock

² In Hardware Mode, only 32-bit word widths are supported for both PCM and TDM.

³ 64FS mode is for 705.6/768kHz with 45.1584/49.152MHz or 352.8/384kHz with 22.5792/24.576MHz.



Asynchronous Mode

Parameter	Notes	Min.	Typ.	Max.	Unit
MCLK¹					
Frequency		44.1kHz*130	-	50	MHz
Duty Cycle		45		55	%
PCM Mode²					
WS Frequency (Word Select Clock)	64FS Mode is not supported in Async. Mode	8	-	MCLK/130 ³	kHz
BCLK Frequency (Bit Clock)		(16*2*WS)	(TDM_BIT_WIDTH)* (TDM_CH_NUM+1)*WS	49.152	MHz
TDM Mode					
WS Frequency (Word Select Clock)	TDM4	8	-	MCLK/130	kHz
	TDM8		-	MCLK/260	kHz
	TDM16		-	MCLK/520	kHz
	TDM32		-	MCLK/1040	kHz
BCLK Frequency (Bit Clock)		(16*2*WS)	(TDM_BIT_WIDTH)* (TDM_CH_NUM+1)*WS	49.152	MHz
DSD Mode					
DSD Clock Frequency		2.8224	-	MCLK/3	MHz

Table 21 - Asynchronous Switching Characteristics

¹ MCLK is Asynchronous to the digital serial audio clock.

² In Hardware Mode, only 32bit word widths are supported for both PCM and TDM.

³ MCLK must be greater than or equal to 130*FS.



Timing Characteristics

Bit-Clock (BCLK) and Word-Select (WS) Timing

Test Conditions 1 (unless otherwise noted)

TA = 25°C, AVCC_R = AVCC_L = VCCA = AVDD = +3.3V, DVDD= +1.2V, fs = 48kHz, DAC enabled, 1kHz sine full scale.

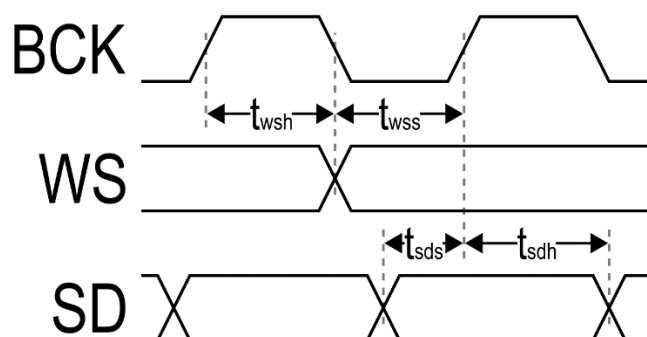


Figure 17 - Bit-Clock and Word-Select Timing

Parameter	Symbol	Min.	Typ.	Max.	Unit
WS hold time	t_{wsh}	1	-	-	ns
WS setup time	t_{wss}	2.4	-	-	ns
SD hold time	t_{sds}	3.1	-	-	ns
SD setup time	t_{sdh}	2.1	-	-	ns

Table 22 - Bit-Clock and Word-Select Timing Definitions



I²C Slave Interface Timing

The I²C slave interface is used when the MODE pin (Pin 17) is pulled low.

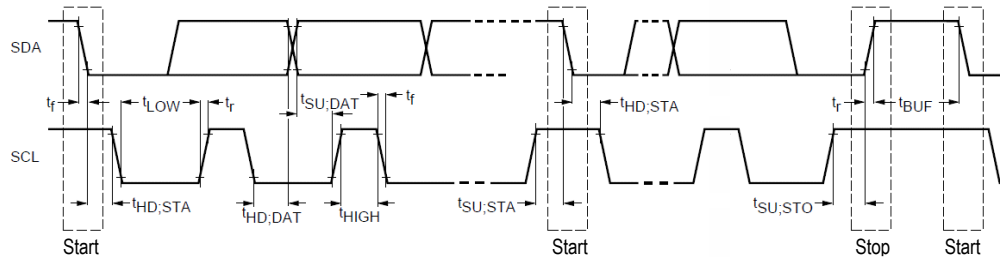


Figure 18 - I²C Slave Control Interface Timing

Parameter	Symbol	CLK Constraint	Standard-Mode		Fast-Mode		Unit
			Min	Max	Min	Max	
SCL Clock Frequency	f_{SCL}	$< CLK/20$	0	100	0	400	kHz
START Condition Hold Time	$t_{HD,STA}$		4.0	-	0.6	-	μs
LOW Period of SCL	t_{LOW}	$> 10/CLK$	4.7	-	1.3	-	μs
HIGH period of SCL ($>10/CLK$)	t_{HIGH}	$> 10/CLK$	1.0	-	0.6	-	μs
START Condition Setup Time (repeat)	$t_{SU,STA}$		4.7	-	0.6	-	μs
SDA Hold Time from SCL Falling - All Except NACK Read - NACK Read Only	$t_{HD,DAT}$		0 2/CLK	-	0 2/CLK	-	μs s
SDA Setup time from SCL Rising	$t_{SU,DAT}$		250	-	100	-	ns
Rise Time of SDA and SCL	t_r		-	1000	-	300	ns
Fall Time of SDA and SCL	t_f		-	300	-	300	ns
STOP Condition Setup Time	$t_{SU,STO}$		4	-	0.6	-	μs
Bus Free Time Between Transmission	t_{SUF}		4.7	-	1.3	-	μs
Capacitive Load for Each Bus Line	C_b		-	400	-	400	pF

Table 23 - I²C Slave/Synchronous Slave Interface Timing Definitions

Note: All bus transitions between start and stop must be part of the transaction when writing to the ESS device



SPI Slave Interface Timing

The SPI slave interface is used when MODE pin (Pin 17) is pulled high.

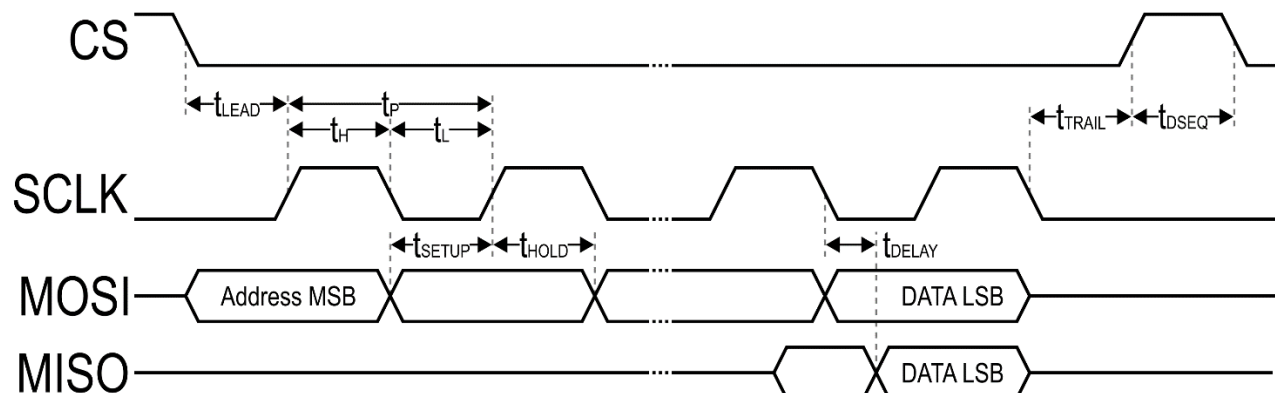


Figure 19 - SPI Slave Interface Timing

Parameter	Symbol	Min	Max	Unit
CS Lead Time (SCLK rising edge)	t_{LEAD}	5	-	ns
CS Trail Time (SCLK falling edge)	t_{TRAIL}	5	-	ns
MOSI Data Setup Time	t_{SETUP_MOSI}	-35	-	ns
MOSI Data Hold Time	t_{HOLD_MOSI}	61	-	ns
SCLK-MISO Delay Time	t_{DELAY_MISO}	-	80	ns
SCLK Period	t_{P_SCLK}	123	-	ns
SCLK High Pulse Duration	t_{H_SCLK}	95	-	ns
SCLK Low Pulse Duration	t_{L_SCLK}	61	-	ns
Sequential Transfer Delay	t_{DSEQ}	39	-	ns

Table 24 - SPI Slave Interface Timing Definitions

Recommended Operating Conditions

These are the recommended operating conditions for the ES9027PRO.

PARAMETER	SYMBOL	CONDITIONS
Operating temperature	T_A	-20°C to +85°C
AVCC_L		3.3V
AVCC_R		3.3V
AVDD		3.3V
VCCA		3.3V
DVDD		1.2V

Table 25 - Recommended Operating Conditions



Power Consumption

Power numbers are given when the device is in slave mode.

Test Condition 0: Standby, CHIP_EN=1'b0

Parameter	Min	Typ.	Max	Unit
Standby (CHIP_EN = 0)				
AVCC		<1		μA
AVDD		<1		μA
VCCA		<1		μA

Table 26 - Standby Power Consumption

Test Condition 1 (unless otherwise noted):

T_A = 25°C, AVCC_R=AVCC_L=VCCA=AVDD=+3.3V, DVDD=+1.2V, fs=48kHz, DAC enabled, 1kHz sine full scale.

Parameter	Min	Typ.	Max	Unit
Hardware Mode: 3 (MCLK = 49.152MHz) MCLK/1				
AVCC_R		22.1		mA
AVCC_L		22.1		mA
VCCA		1.2		mA
AVDD		2.1		mA
DVDD		32.0		mA
Power Consumption		197		mW
Hardware Mode: 0 (MCLK = 6.144MHz) MCLK/1				
AVCC_R		13.6		mA
AVCC_L		13.6		mA
VCCA		0.2		mA
AVDD		2.1		mA
DVDD		10.3		mA
Power Consumption		110		mW
Hardware Mode: 19 (MCLK = 50MHz) Auto Clock Gear				
AVCC_R		14.9		mA
AVCC_L		14.9		mA
VCCA		0.5		mA
AVDD		0.3		mA
DVDD		17.9		mA
Power Consumption		123		mW

Table 27 - Power Consumption with Test Condition 1



Test Condition 2 (unless otherwise noted):

T_A = 25°C, AVCC_R=AVCC_L=VCCA=AVDD=+3.3V, DVDD=+1.2V, fs=48kHz, streaming zeros, automute enabled.

Parameter	Min	Typ.	Max	Unit
Hardware Mode: 3 (MCLK = 49.152MHz) MCLK/1				
AVCC_R		9.2		mA
AVCC_L		9.2		mA
VCCA		1.2		mA
AVDD		2.2		mA
DVDD		18.4		mA
Power Consumption		95		mW
Hardware Mode: 0 (MCLK = 6.144MHz) MCLK/1				
AVCC_R		1.6		mA
AVCC_L		1.6		mA
VCCA		0.6		mA
AVDD		2.1		mA
DVDD		4.3		mA
Power Consumption		24		mW
Hardware Mode: 19 (MCLK = 50MHz) Auto Clock Gear				
AVCC_R		2.8		mA
AVCC_L		2.8		mA
VCCA		0.4		mA
AVDD		0.4		mA
DVDD		9.0		mA
Power Consumption		32		mW

Table 28 - Power Consumption with Test Condition 2

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Performance¹

Test Conditions 1 (unless otherwise noted)

T_A = 25°C, AVCC_R=AVCC_L=VCCA=AVDD=+3.3V, DVDD=+1.2V, fs=48kHz, HW mode 3 (I²S Master Mode), MCLK = 49.152MHz.

Parameter		Min	Typ.	Max	Unit
Resolution			32		Bit
Max MCLK Frequency				50	MHz
THD+N Ratio / THD Ratio @ fs = 48kHz (Differential)	0dBFS BW=20Hz-20kHz		-114 / -118		dB
THD+N Ratio / THD Ratio @ fs = 96kHz (Differential)	0dBFS BW=20Hz-40kHz		-112 / -118		dB
THD+N Ratio / THD Ratio @ fs = 192kHz (Differential)	0dBFS BW=20Hz-80kHz		-110 / -118		dB
THD+N Ratio / THD Ratio @ fs = 384kHz (Differential)	0dBFS BW=20Hz-160kHz		-108 / -118		dB
DNR (A-weighted) (8 Channel Mode - Single Channel Diff)	-60 dBFS		124		dB
DNR (A-weighted) (Stereo Mode - 4 Channel Sum Diff)			128		dB
DNR (A-weighted) (Mono Mode - 8 Channel Sum Diff)			130		dB
Voltage Output Amplitude	Full-Scale Out		0.889 * AVCC		V _{pp}
Voltage Output Offset	Bipolar Zero Out		AVCC / 2		V
Current Output Amplitude	Full-Scale Out		0.889*1000*AVCC/Rdac		mApp
Current Output Offsets	Bipolar Zero Out		1000*(AVCC/2-Vg)/Rdac		mA
Output Impedance (Per + or - Pin of Each Differential DAC Output Pair)	R _{DAC}		760 ±15%		Ω

Table 29 - Performance Data

¹ Performance numbers were measured using the ESS evaluation board V1.0



Register Overview

I²C Slave Interface

This interface uses device addresses 0x90-0x97 and contains Read/Write and Read-only registers. A system clock must be present.

Read/Write Register Addresses

Registers 0-141 (0x00 - 0x8D) are read/write registers.

Read-Only Register Addresses

Register 224-245 (0xE0 - 0xF5) are read-only registers.

Multi-Byte Registers

Multi-Byte registers must be written from LSB to MSB. Data is latched when MSB is written.

Multi-Byte registers must be read from LSB to MSB. Data is latched when LSB is read.

MSB is always stored in the highest register address.



Register Map

Addr (Hex)	Addr (Dec)	Register	7	6	5	4	3	2	1	0
0x00	0	SYSTEM CONFIG	SOFT_RESET	ENABLE_64FS_MODE	CH78_SEL		CH56_SEL	CH34_SEL	DAC_MODE_REG	RESERVED
0x01	1	SYS MODE CONFIG	ENABLE_DAC	SYNC_MODE	RESERVED		ENABLE_SPDIF_DECODE	ENABLE_DOP_DECODE	ENABLE_DSD_DECODE	ENABLE_TDM_DECODE
0x02	2	CLOCK ENABLE	RESERVED							
0x03	3	DAC CLOCK CONFIG	AUTO_FS_DETECT	SELECT_IDAC_HALF	SELECT_IDAC_NUM					
0x04	4	CLOCK CONFIG	MASTER_BCK_DIV							
0x05	5	CLK GEAR SELECT	RESERVED		SEL_CLK_GEAR		RESERVED	AUTO_CLK_GEAR	RESERVED	
0x06-0x09	6-9	RESERVED	RESERVED							
0x0A	10	INTERRUPT VOL MIN MASK P	VOL_MIN_CH8_MASKP	VOL_MIN_CH7_MASKP	VOL_MIN_CH6_MASKP	VOL_MIN_CH5_MASKP	VOL_MIN_CH4_MASKP	VOL_MIN_CH3_MASKP	VOL_MIN_CH2_MASKP	VOL_MIN_CH1_MASKP
0x0B	11	INTERRUPT AUTOMUTE MASKP	AUTOMUTE_FLAG_CH8_MASKP	AUTOMUTE_FLAG_CH7_MASKP	AUTOMUTE_FLAG_CH6_MASKP	AUTOMUTE_FLAG_CH5_MASKP	AUTOMUTE_FLAG_CH4_MASKP	AUTOMUTE_FLAG_CH3_MASKP	AUTOMUTE_FLAG_CH2_MASKP	AUTOMUTE_FLAG_CH1_MASKP
0x0C	12	SS FULL RAMP MASKP	SS_FULL_RAMP_CH8_MASKP	SS_FULL_RAMP_CH7_MASKP	SS_FULL_RAMP_CH6_MASKP	SS_FULL_RAMP_CH5_MASKP	SS_FULL_RAMP_CH4_MASKP	SS_FULL_RAMP_CH3_MASKP	SS_FULL_RAMP_CH2_MASKP	SS_FULL_RAMP_CH1_MASKP
0x0D	13	INTERRUPT MASKP	INPUT_SELECT_OVERRIDE_MASKP		TDM_VALID_EDGE_MASKP	RESERVED			BCK_WS_FAIL_MASKP	DOP_VALID_MASKP
0x0E	14	RESERVED	RESERVED							
0x0F	15	INTERRUPT VOL MIN MASKN	VOL_MIN_CH8_MASKN	VOL_MIN_CH7_MASKN	VOL_MIN_CH6_MASKN	VOL_MIN_CH5_MASKN	VOL_MIN_CH4_MASKN	VOL_MIN_CH3_MASKN	VOL_MIN_CH2_MASKN	VOL_MIN_CH1_MASKN
0x10	16	INTERRUPT AUTOMUTE MASKN	AUTOMUTE_FLAG_CH8_MASKN	AUTOMUTE_FLAG_CH7_MASKN	AUTOMUTE_FLAG_CH6_MASKN	AUTOMUTE_FLAG_CH5_MASKN	AUTOMUTE_FLAG_CH4_MASKN	AUTOMUTE_FLAG_CH3_MASKN	AUTOMUTE_FLAG_CH2_MASKN	AUTOMUTE_FLAG_CH1_MASKN
0x11	17	INTERRUPT SS FULL RAMP MASKN	SS_FULL_RAMP_CH8_MASKN	SS_FULL_RAMP_CH7_MASKN	SS_FULL_RAMP_CH6_MASKN	SS_FULL_RAMP_CH5_MASKN	SS_FULL_RAMP_CH4_MASKN	SS_FULL_RAMP_CH3_MASKN	SS_FULL_RAMP_CH2_MASKN	SS_FULL_RAMP_CH1_MASKN
0x12	18	INTERRUPT MASKN	INPUT_SELECT_OVERRIDE_MASKN		TDM_VALID_EDGE_MASKN	RESERVED			BCK_WS_FAIL_MASKN	DOP_VALID_MASKN
0x13	19	RESERVED	RESERVED							
0x14	20	INTERRUPT VOL MIN CLEAR	VOL_MIN_CH8_CLEAR	VOL_MIN_CH7_CLEAR	VOL_MIN_CH6_CLEAR	VOL_MIN_CH5_CLEAR	VOL_MIN_CH4_CLEAR	VOL_MIN_CH3_CLEAR	VOL_MIN_CH2_CLEAR	VOL_MIN_CH1_CLEAR
0x15	21	INTERRUPT AUTOMUTE CLEAR	AUTOMUTE_FLAG_CH8_CLEAR	AUTOMUTE_FLAG_CH7_CLEAR	AUTOMUTE_FLAG_CH6_CLEAR	AUTOMUTE_FLAG_CH5_CLEAR	AUTOMUTE_FLAG_CH4_CLEAR	AUTOMUTE_FLAG_CH3_CLEAR	AUTOMUTE_FLAG_CH2_CLEAR	AUTOMUTE_FLAG_CH1_CLEAR
0x16	22	INTERRUPT SS FULL RAMP CLEAR	SS_FULL_RAMP_CH8_CLEAR	SS_FULL_RAMP_CH7_CLEAR	SS_FULL_RAMP_CH6_CLEAR	SS_FULL_RAMP_CH5_CLEAR	SS_FULL_RAMP_CH4_CLEAR	SS_FULL_RAMP_CH3_CLEAR	SS_FULL_RAMP_CH2_CLEAR	SS_FULL_RAMP_CH1_CLEAR
0x17	23	INTERRUPT CLEAR	INPUT_SELECT_OVERRIDE_CLEAR		TDM_VALID_EDGE_CLEAR	RESERVED			BCK_WS_FAIL_CLEAR	DOP_VALID_CLEAR
0x18-0x19	24-25	RESERVED	RESERVED							
0x1A	26	DPLL BW	RESERVED				RESERVED			
0x1B	27		RESERVED				RESERVED			
0x1C	28		RESERVED				RESERVED			
0x1D	29		DPLL_BW				RESERVED			
0x1E-0x21	30-33	RESERVED	RESERVED							
0x22	34	DIGITAL AUTO CONTROL CONFIG	RESERVED	CAL_RES_ENB	RESERVED					
0x23-0x24	35-36	RESERVED	RESERVED							
0x25	37	GPIO1/2 CONFIG	GPIO2_CFG				GPIO1_CFG			
0x26	38	GPIO3/4 CONFIG	GPIO4_CFG				GPIO3_CFG			
0x27	39	GPIO5/6 CONFIG	GPIO6_CFG				GPIO5_CFG			
0x28	40	GPIO7/8 CONFIG	GPIO8_CFG				GPIO7_CFG			
0x29	41	GPIO OUTPUT ENABLE	GPIO8_OE	GPIO7_OE	GPIO6_OE	GPIO5_OE	GPIO4_OE	GPIO3_OE	GPIO2_OE	GPIO1_OE
0x2A	42	GPIO INPUT	GPIO8_SDB	GPIO7_SDB	GPIO6_SDB	GPIO5_SDB	GPIO4_SDB	GPIO3_SDB	GPIO2_SDB	GPIO1_SDB
0x2B	43	GPIO WK EN	GPIO8_WK_EN	GPIO7_WK_EN	GPIO6_WK_EN	GPIO5_WK_EN	GPIO4_WK_EN	GPIO3_WK_EN	GPIO2_WK_EN	GPIO1_WK_EN
0x2C	44	INVERT GPIO	INVERT_GPIO8	INVERT_GPIO7	INVERT_GPIO6	INVERT_GPIO5	INVERT_GPIO4	INVERT_GPIO3	INVERT_GPIO2	INVERT_GPIO1
0x2D	45	GPIO READ	GPIO8_READ	GPIO7_READ	GPIO6_READ	GPIO5_READ	GPIO4_READ	GPIO3_READ	GPIO2_READ	GPIO1_READ
0x2E	46	GPIO OUTPUT LOGIC	FLAG_CH_SEL		GPIO_OR_SS_RAMP	GPIO_OR_VOL_MIN	GPIO_OR_AUTOMUTE	GPIO_AND_SS_RAMP	GPIO_AND_VOL_MIN	GPIO_AND_AUTOMUTE
0x2F	47		GPIO_DAC_MODE	RESERVED						FLAG_CH_SEL
0x30	48	PWM1 COUNT	PWM1_COUNT							
0x31	49	PWM1 FREQUENCY	PWM1_FREQ							
0x32	50		PWM1_FREQ							
0x33	51	PWM2 COUNT	PWM2_COUNT							
0x34	52	PWM2 FREQUENCY	PWM2_FREQ							
0x35	53		PWM2_FREQ							
0x36	54	PWM3 COUNT	PWM3_COUNT							
0x37	55	PWM3 FREQUENCY	PWM3_FREQ							
0x38	56		PWM3_FREQ							
0x39	57	INPUT SELECTION	AUTO_CH_DETECT	ENABLE_DSD_FAULT_DETECTION	DSD_MASTER_MODE	PCM_MASTER_MODE	RESERVED	INPUT_SEL		AUTO_INPUT_SEL
0x3A	58	SERIAL MASTER ENCODER CONFIG	TDM_RESYNC	BCK_INV	RESERVED	MASTER_FRAME_LENGTH		MASTER_WS_PULSE_MODE	MASTER_WS_INVERT	MASTER_BCK_INVERT



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0x3B	59	TDM CONFIG	RESERVED				TDM_CH_NUM				
0x3C	60	TDM CONFIG1	TDM_LJ_MODE	TDM_VALID_EDGE	RESERVED						
0x3D	61	TDM CONFIG2	ENABLE_ASYNC_LOCK_MONITOR	TDM_BIT_WIDTH		RESERVED					
0x3E	62	BCK/WS MONITOR CONFIG	DISABLE_DSD_DC	DISABLE_DSD_MUTE	ENABLE_WS_MONITOR	ENABLE_BCK_MONITOR	DISABLE_PCM_DC	RESERVED			
0x3F	63	RESERVED	RESERVED								
0x40	64	TDM CH1 CONFIG	RESERVED	TDM_CH1_LINE_SEL		RESERVED			TDM_CH1_SLOT_SEL		
0x41	65	TDM CH2 CONFIG	RESERVED	TDM_CH2_LINE_SEL		RESERVED			TDM_CH2_SLOT_SEL		
0x42	66	TDM CH3 CONFIG	RESERVED	TDM_CH3_LINE_SEL		RESERVED			TDM_CH3_SLOT_SEL		
0x43	67	TDM CH4 CONFIG	RESERVED	TDM_CH4_LINE_SEL		RESERVED			TDM_CH4_SLOT_SEL		
0x44	68	TDM CH5 CONFIG	RESERVED	TDM_CH5_LINE_SEL		RESERVED			TDM_CH5_SLOT_SEL		
0x45	69	TDM CH6 CONFIG	RESERVED	TDM_CH6_LINE_SEL		RESERVED			TDM_CH6_SLOT_SEL		
0x46	70	TDM CH7 CONFIG	RESERVED	TDM_CH7_LINE_SEL		RESERVED			TDM_CH7_SLOT_SEL		
0x47	71	TDM CH8 CONFIG	RESERVED	TDM_CH8_LINE_SEL		RESERVED			TDM_CH8_SLOT_SEL		
0x48-0x49	72-73	RESERVED	RESERVED								
0x4A	74	VOLUME1	VOLUME1								
0x4B	75	VOLUME2	VOLUME2								
0x4C	76	VOLUME3	VOLUME3								
0x4D	77	VOLUME4	VOLUME4								
0x4E	78	VOLUME5	VOLUME5								
0x4F	79	VOLUME6	VOLUME6								
0x50	80	VOLUME7	VOLUME7								
0x51	81	VOLUME8	VOLUME8								
0x52	82	DAC VOL UP RATE	DAC_VOL_RATE_UP								
0x53	83	DAC VOL DOWN RATE	DAC_VOL_RATE_DOWN								
0x54	84	DAC VOL DOWN RATE FAST	DAC_VOL_RATE_FAST								
0x55	85	RESERVED	RESERVED								
0x56	86	DAC MUTE	DAC_MUTE_CH8	DAC_MUTE_CH7	DAC_MUTE_CH6	DAC_MUTE_CH5	DAC_MUTE_CH4	DAC_MUTE_CH3	DAC_MUTE_CH2	DAC_MUTE_CH1	
0x57	87	DAC INVERT	DAC_INVERT_CH8	DAC_INVERT_CH7	DAC_INVERT_CH6	DAC_INVERT_CH5	DAC_INVERT_CH4	DAC_INVERT_CH3	DAC_INVERT_CH2	DAC_INVERT_CH1	
0x58	88	FILTER SHAPE	RESERVED						FILTER_SHAPE		
0x59	89	IIR BANDWIDTH & S/PDIF SELECT	SPDIF_SEL				VOLUME_HOLD	IIR_BW			
0x5A	90	DAC PATH CONFIG	RESERVED						BYPASS_FIR4X	BYPASS_FIR2X	
0x5B-0x7A	91-122	RESERVED	RESERVED								
0x7B	123	AUTOMUTE ENABLE	AUTOMUTE_EN_CH8	AUTOMUTE_EN_CH7	AUTOMUTE_EN_CH6	AUTOMUTE_EN_CH5	AUTOMUTE_EN_CH4	AUTOMUTE_EN_CH3	AUTOMUTE_EN_CH2	AUTOMUTE_EN_CH1	
0x7C	124	AUTOMUTE TIME	AUTOMUTE_TIME						AUTOMUTE_RAMP_TO_GROUND	AUTOMUTE_TIME	
0x7D	125		RESERVED				AUTOMUTE_RAMP_TO_GROUND		AUTOMUTE_TIME		
0x7E	126	AUTOMUTE LEVEL	AUTOMUTE_LEVEL								
0x7F	127		AUTOMUTE_LEVEL								
0x80	128	AUTOMUTE OFF LEVEL	AUTOMUTE_OFF_LEVEL								
0x81	129		AUTOMUTE_OFF_LEVEL								
0x82	130	SOFT RAMP CONFIG	RESERVED				SOFT_RAMP_TIME				
0x83-0x91	131-145	RESERVED	RESERVED								
0xE0	224	SYS READ	RESERVED				MODES	ADDR1	ADDR0		
0xE1	225	CHIP ID READ	CHIP_ID								
0xE2-0xE4	226-228	RESERVED	RESERVED								
0xE5	229	INTERRUPT STATE	VOL_MIN_STATE								
0xE6	230		AUTOMUTE_STATE								
0xE7	231		SS_FULL_RAMP_STATE								
0xE8	232		INPUT_SELECT_OVERRIDE_STATE	TDM_DATA_VALID_STATE	RESERVED				BCK_WS_FAIL_STATE	DOP_VALID_STATE	
0xE9	233	INTERRUPT SOURCE	RESERVED								
0xEA	234		VOL_MIN_SOURCE								
0xEB	235		AUTOMUTE_SOURCE								
0xEC	236		SS_FULL_RAMP_SOURCE								
0xED	237		INPUT_SELECT_OVERRIDE_SOURCE	TDM_DATA_VALID_SOURCE	RESERVED				BCK_WS_FAIL_SOURCE	DOP_VALID_SOURCE	
0xEE	238	RESERVED	RESERVED								
0xEF	239	RATIO VALID READ	RATIO_VALID	RESERVED							
0xF0	240	GPIO READ	GPIO8_I_READ	GPIO7_I_READ	GPIO6_I_READ	GPIO5_I_READ	GPIO4_I_READ	GPIO3_I_READ	GPIO2_I_READ	GPIO1_I_READ	
0xF1	241	VOL MIN READ	VOL_MIN_CH8	VOL_MIN_CH7	VOL_MIN_CH6	VOL_MIN_CH5	VOL_MIN_CH4	VOL_MIN_CH3	VOL_MIN_CH2	VOL_MIN_CH1	
0xF2	242	AUTOMUTE READ	AUTOMUTE_CH8	AUTOMUTE_CH7	AUTOMUTE_CH6	AUTOMUTE_CH5	AUTOMUTE_CH4	AUTOMUTE_CH3	AUTOMUTE_CH2	AUTOMUTE_CH1	
0xF3	243	SOFT RAMP UP READ	SS_RAMP_UP_CH8	SS_RAMP_UP_CH7	SS_RAMP_UP_CH6	SS_RAMP_UP_CH5	SS_RAMP_UP_CH4	SS_RAMP_UP_CH3	SS_RAMP_UP_CH2	SS_RAMP_UP_CH1	
0xF4	244	SOFT RAMP DOWN READ	SS_RAMP_DOWN_CH8	SS_RAMP_DOWN_CH7	SS_RAMP_DOWN_CH6	SS_RAMP_DOWN_CH5	SS_RAMP_DOWN_CH4	SS_RAMP_DOWN_CH3	SS_RAMP_DOWN_CH2	SS_RAMP_DOWN_CH1	
0xF5	245	S/PDIF, TDM, DOP, AND INPUT READBACK	SPDIF_VALID	TDM_DATA_VALID	DOP_VALID				INPUT_SELECT_OVERRIDE		
0xF6-0xFB	246-251	RESERVED	RESERVED								

Table 30 - Register Map



Register Listing

System Registers

Register 0: SYSTEM CONFIG

Bits	[7]	[6]	[5:4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	2'b00	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	SOFT_RESET	Performs soft reset to digital core
[6]	ENABLE_64FS_MODE	Enables 64FS mode for 768kHz sample rate. <ul style="list-style-type: none"> 1'b0: 64FS mode disabled (default) 1'b1: 64FS mode enabled
[5:4]	CH78_SEL	Selects ch7/8 nsmode input. <ul style="list-style-type: none"> 2'b00: Input from ch7/8 interpolation path (default) 2'b01: Input from ch5/6 interpolation path 2'b10: Input from ch1/2 interpolation path 2'b11: Reserved
[3]	CH56_SEL	Selects ch5/6 nsmode input. <ul style="list-style-type: none"> 1'b0: Input from ch5/6 interpolation path (default) 1'b1: Input from ch1/2 interpolation path
[2]	CH34_SEL	Selects ch3/4 nsmode input. <ul style="list-style-type: none"> 1'b0: Input from ch3/4 interpolation path (default) 1'b1: Input from ch1/2 interpolation path
[1]	DAC_MODE_REG	Enables DAC data path <ul style="list-style-type: none"> 1'b0: DAC disabled 1'b1: DAC enabled
[0]	RESERVED	NA



Register 1: SYS MODE CONFIG

Bits	[7]	[6]	[5:4]	[3]	[2]	[1]	[0]
Default	1'b1	1'b0	2'b01	1'b0	1'b0	1'b0	1'b1

Bits	Mnemonic	Description
[7]	ENABLE_DAC	Enables DAC interpolation path clock. <ul style="list-style-type: none"> 1'b0: Clock disabled 1'b1: Clock enabled (default)
[6]	SYNC_MODE	Enables SYNC mode <ul style="list-style-type: none"> 1'b0: ASYNC mode enabled (default) 1'b1: SYNC mode enabled
[5:4]	RESERVED	NA
[3]	ENABLE_SPDIF_DECODE	Enables S/PDIF decoding. <ul style="list-style-type: none"> 1'b0: Disabled (default) 1'b1: Enabled
[2]	ENABLE_DOP_DECODE	Enables DoP decoding. <ul style="list-style-type: none"> 1'b0: Disabled (default) 1'b1: Enabled
[1]	ENABLE_DSD_DECODE	Enables DSD decoding. <ul style="list-style-type: none"> 1'b0: Disabled (default) 1'b1: Enabled
[0]	ENABLE_TDM_DECODE	Enables TDM decoding. <ul style="list-style-type: none"> 1'b0: Disabled (default) 1'b1: Enabled

Register 2: RESERVED

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Register 3: DAC CLOCK CONFIG

Bits	[7]	[6]	[5:0]
Default	1'b1	1'b0	6'd0

Bits	Mnemonic	Description
[7]	AUTO_FS_DETECT	<ul style="list-style-type: none"> 1'b0: Disabled 1'b1: Auto tune CLK_DAC/CLK_IDAC ratio according to detected FS (default) Note: Cannot be used in ASYNC mode
[6]	SELECT_IDAC_HALF	<ul style="list-style-type: none"> 1'b0: Divide by SELECT_IDAC_NUM + 1 (default) 1'b1: Divide by half of SELECT_IDAC_NUM + 1 Note: Can only produce half of an odd number divide
[5:0]	SELECT_IDAC_NUM	CLK_IDAC divider. Whole number divide value + 1 for CLK_IDAC (SYS_CLK/divide_value). <ul style="list-style-type: none"> 6'd0: Whole number divide value + 1 = 1 6'd1: Whole number divide value + 1 = 2 6'd63: Whole number divide value + 1 = 64

Register 4: CLOCK CONFIG

Bits	[7:0]
Default	8'd7

Bits	Mnemonic	Description
[7:0]	MASTER_BCK_DIV	Master mode clock divider. Whole number divide value + 1 for CLK_Master (SYS_CLK/divide_value).



Register 5: CLK GEAR SELECT

Bits	[7:6]	[5:4]	[3]	[2]	[1:0]
Default	2'b00	2'd0	1'b0	1'b0	2'b00

Bits	Mnemonic	Description
[7:6]	RESERVED	NA
[5:4]	SEL_CLK_GEAR	Clock Gearing <ul style="list-style-type: none"> • 2'd0: SYS_CLK/1 • 2'd1: SYS_CLK/2 • 2'd2: SYS_CLK/4 • 2'd3: SYS_CLK/8
[3]	RESERVED	NA
[2]	AUTO_CLK_GEAR	<ul style="list-style-type: none"> • 1'b0: Disable automatic clock gearing. SYS_CLK = SEL_CLK_GEAR • 1'b1: Enable automatic clock gearing. SYS_CLK will increase up to SEL_CLK_GEAR
[1:0]	RESERVED	NA

Register 9-6: RESERVED

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Register 10: INTERRUPT VOL MIN MASK P

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	VOL_MIN_CH8_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[6]	VOL_MIN_CH7_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[5]	VOL_MIN_CH6_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[4]	VOL_MIN_CH5_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[3]	VOL_MIN_CH4_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[2]	VOL_MIN_CH3_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[1]	VOL_MIN_CH2_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[0]	VOL_MIN_CH1_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive



Register 11: INTERRUPT AUTOMUTE MASKP

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	AUTOMUTE_FLAG_CH8_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[6]	AUTOMUTE_FLAG_CH7_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[5]	AUTOMUTE_FLAG_CH6_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[4]	AUTOMUTE_FLAG_CH5_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[3]	AUTOMUTE_FLAG_CH4_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[2]	AUTOMUTE_FLAG_CH3_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[1]	AUTOMUTE_FLAG_CH2_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[0]	AUTOMUTE_FLAG_CH1_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive

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Register 12: SS FULL RAMP MASKP

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	SS_FULL_RAMP_CH8_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[6]	SS_FULL_RAMP_CH7_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[5]	SS_FULL_RAMP_CH6_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[4]	SS_FULL_RAMP_CH5_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[3]	SS_FULL_RAMP_CH4_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[2]	SS_FULL_RAMP_CH3_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[1]	SS_FULL_RAMP_CH2_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[0]	SS_FULL_RAMP_CH1_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive



Register 14-13: INTERRUPT MASKP

Bits	[15:8]	[7:6]	[5]	[4:2]	[1]	[0]
Default	8'd0	2'b00	1'b0	3'b000	1'b0	1'b0

Bits	Mnemonic	Description
[15:8]	RESERVED	NA
[7:6]	INPUT_SELECT_OVERRIDE_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[5]	TDM_VALID_EDGE_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[4:2]	RESERVED	NA
[1]	BCK_WS_FAIL_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive
[0]	DOP_VALID_MASKP	Masks negative to positive interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from negative to positive 1'b1: Service interrupt if toggled from negative to positive

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Register 15: INTERRUPT VOL MIN MASKN

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	VOL_MIN_CH8_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[6]	VOL_MIN_CH7_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[5]	VOL_MIN_CH6_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[4]	VOL_MIN_CH5_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[3]	VOL_MIN_CH4_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[2]	VOL_MIN_CH3_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[1]	VOL_MIN_CH2_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[0]	VOL_MIN_CH1_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative



Register 16: INTERRUPT AUTOMUTE MASKN

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	AUTOMUTE_FLAG_CH8_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[6]	AUTOMUTE_FLAG_CH7_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[5]	AUTOMUTE_FLAG_CH6_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[4]	AUTOMUTE_FLAG_CH5_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[3]	AUTOMUTE_FLAG_CH4_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[2]	AUTOMUTE_FLAG_CH3_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[1]	AUTOMUTE_FLAG_CH2_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[0]	AUTOMUTE_FLAG_CH1_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative

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Register 17: INTERRUPT SS FULL RAMP MASKN

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	SS_FULL_RAMP_CH8_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[6]	SS_FULL_RAMP_CH7_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[5]	SS_FULL_RAMP_CH6_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[4]	SS_FULL_RAMP_CH5_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[3]	SS_FULL_RAMP_CH4_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[2]	SS_FULL_RAMP_CH3_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[1]	SS_FULL_RAMP_CH2_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[0]	SS_FULL_RAMP_CH1_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative



Register 19-18: INTERRUPT MASKN

Bits	[15:8]	[7:6]	[5]	[4:2]	[1]	[0]
Default	8'd0	2'b00	1'b0	3'b000	1'b0	1'b0

Bits	Mnemonic	Description
[15:8]	RESERVED	NA
[7:6]	INPUT_SELECT_OVERRIDE_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[5]	TDM_VALID_EDGE_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[4:2]	RESERVED	NA
[1]	BCK_WS_FAIL_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative
[0]	DOP_VALID_MASKN	Masks positive to negative interrupt toggling. <ul style="list-style-type: none"> 1'b0: Ignore interrupt if toggled from positive to negative 1'b1: Service interrupt if toggled from positive to negative

Register 20: INTERRUPT VOL MIN CLEAR

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	VOL_MIN_CH8_CLEAR	Write a 1'b1 to clear the interrupt
[6]	VOL_MIN_CH7_CLEAR	Write a 1'b1 to clear the interrupt
[5]	VOL_MIN_CH6_CLEAR	Write a 1'b1 to clear the interrupt
[4]	VOL_MIN_CH5_CLEAR	Write a 1'b1 to clear the interrupt
[3]	VOL_MIN_CH4_CLEAR	Write a 1'b1 to clear the interrupt
[2]	VOL_MIN_CH3_CLEAR	Write a 1'b1 to clear the interrupt
[1]	VOL_MIN_CH2_CLEAR	Write a 1'b1 to clear the interrupt
[0]	VOL_MIN_CH1_CLEAR	Write a 1'b1 to clear the interrupt


Register 21: INTERRUPT AUTOMUTE CLEAR

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	AUTOMUTE_FLAG_CH8_CLEAR	Write a 1'b1 to clear the interrupt
[6]	AUTOMUTE_FLAG_CH7_CLEAR	Write a 1'b1 to clear the interrupt
[5]	AUTOMUTE_FLAG_CH6_CLEAR	Write a 1'b1 to clear the interrupt
[4]	AUTOMUTE_FLAG_CH5_CLEAR	Write a 1'b1 to clear the interrupt
[3]	AUTOMUTE_FLAG_CH4_CLEAR	Write a 1'b1 to clear the interrupt
[2]	AUTOMUTE_FLAG_CH3_CLEAR	Write a 1'b1 to clear the interrupt
[1]	AUTOMUTE_FLAG_CH2_CLEAR	Write a 1'b1 to clear the interrupt
[0]	AUTOMUTE_FLAG_CH1_CLEAR	Write a 1'b1 to clear the interrupt

Register 22: INTERRUPT SS FULL RAMP CLEAR

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	SS_FULL_RAMP_CH8_CLEAR	Write a 1'b1 to clear the interrupt
[6]	SS_FULL_RAMP_CH7_CLEAR	Write a 1'b1 to clear the interrupt
[5]	SS_FULL_RAMP_CH6_CLEAR	Write a 1'b1 to clear the interrupt
[4]	SS_FULL_RAMP_CH5_CLEAR	Write a 1'b1 to clear the interrupt
[3]	SS_FULL_RAMP_CH4_CLEAR	Write a 1'b1 to clear the interrupt
[2]	SS_FULL_RAMP_CH3_CLEAR	Write a 1'b1 to clear the interrupt
[1]	SS_FULL_RAMP_CH2_CLEAR	Write a 1'b1 to clear the interrupt
[0]	SS_FULL_RAMP_CH1_CLEAR	Write a 1'b1 to clear the interrupt

**Register 24-23: INTERRUPT CLEAR**

Bits	[15:8]	[7:6]	[5]	[4:2]	[1]	[0]
Default	8'd0	2'b00	1'b0	3'b000	1'b0	1'b0

Bits	Mnemonic	Description
[15:8]	RESERVED	NA
[7:6]	INPUT_SELECT_OVERRIDE_CLEAR	Write a 1'b1 to clear the interrupt
[5]	TDM_VALID_EDGE_CLEAR	Write a 1'b1 to clear the interrupt
[4:2]	RESERVED	NA
[1]	BCK_WS_FAIL_CLEAR	Write a 1'b1 to clear the interrupt
[0]	DOP_VALID_CLEAR	Write a 1'b1 to clear the interrupt

Register 25: RESERVED**Register 29-26: DPLL BW**

Bits	[31:28]	[27:0]
Default	4'd4	28'd0

Bits	Mnemonic	Description
[31:28]	DPLL_BW	Sets the bandwidth of the DPLL. <ul style="list-style-type: none"> 4'd0: Reserved 4'd1: Lowest Bandwidth 4'd15: Highest Bandwidth
[27:0]	RESERVED	NA

Register 30-33: RESERVED

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Register 34: DIGITAL AUTO CONTROL CONFIG

Bits	[7]	[6]	[5:0]
Default	1'b0	1'b0	6'b000000

Bits	Mnemonic	Description
[7]	RESERVED	NA
[6]	CAL_RES_ENB	Selects the calibration resistor on GPIO3 <ul style="list-style-type: none"> • 1'b0: DAC calibration resistor enabled (default) • 1'b1: DAC calibration resistor disabled
[5:0]	RESERVED	NA

Register 35-36: RESERVED



GPIO Registers

Register 37: GPIO1/2 CONFIG

Bits	[7:4]	[3:0]
Default	4'd7	4'd13

Bits	Mnemonic	Description
[7:4]	GPIO2_CFG	Configures GPIO2 <ul style="list-style-type: none"> • 4'd0: analog shutdown - shutdown • 4'd1: output 0 – output • 4'd2: output 1 – output • 4'd3: CLK_IDAC – output • 4'd4: interrupt – output • 4'd5: mute all channel - input • 4'd6: input selection - input • 4'd7: LOCK_STATUS – output (default) • 4'd8: CLKEN_1FS – output • 4'd9: output PWM1 – output • 4'd10: output PWM2 – output • 4'd11: output PWM3 – output • 4'd12: volume minimum – output • 4'd13: automute status – output • 4'd14: soft ramp done – output • 4'd15: Reserved
[3:0]	GPIO1_CFG	Configures GPIO1 <ul style="list-style-type: none"> • 4'd0: analog shutdown - shutdown • 4'd1: output 0 – output • 4'd2: output 1 – output • 4'd3: CLK_IDAC – output • 4'd4: interrupt – output • 4'd5: mute all channel - input • 4'd6: input selection - input • 4'd7: LOCK_STATUS – output • 4'd8: CLKEN_1FS – output • 4'd9: output PWM1 – output • 4'd10: output PWM2 – output • 4'd11: output PWM3 – output • 4'd12: volume minimum – output • 4'd13: automute status – output (default) • 4'd14: soft ramp done – output • 4'd15: Reserved

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Register 38: GPIO3/4 CONFIG

Bits	[7:4]	[3:0]
Default	4'd0	4'd0

Bits	Mnemonic	Description
[7:4]	GPIO4_CFG	Configures GPIO4 <ul style="list-style-type: none"> • 4'd0: analog shutdown - shutdown • 4'd1: output 0 – output • 4'd2: output 1 – output • 4'd3: CLK_IDAC – output • 4'd4: interrupt – output • 4'd5: mute all channel - input • 4'd6: input selection - input • 4'd7: LOCK_STATUS – output • 4'd8: CLKEN_1FS – output • 4'd9: output PWM1 – output • 4'd10: output PWM2 – output • 4'd11: output PWM3 – output • 4'd12: volume minimum – output • 4'd13: automute status – output • 4'd14: soft ramp done – output • 4'd15: Reserved
[3:0]	GPIO3_CFG	Configures GPIO3 <ul style="list-style-type: none"> • 4'd0: analog shutdown - shutdown • 4'd1: output 0 – output • 4'd2: output 1 – output • 4'd3: CLK_IDAC – output • 4'd4: interrupt – output • 4'd5: mute all channel - input • 4'd6: input selection - input • 4'd7: LOCK_STATUS – output • 4'd8: CLKEN_1FS – output • 4'd9: output PWM1 – output • 4'd10: output PWM2 – output • 4'd11: output PWM3 – output • 4'd12: volume minimum – output • 4'd13: automute status – output • 4'd14: soft ramp done – output • 4'd15: Reserved



Register 39: GPIO5/6 CONFIG

Bits	[7:4]	[3:0]
Default	4'd0	4'd0

Bits	Mnemonic	Description
[7:4]	GPIO6_CFG	Configures GPIO6 <ul style="list-style-type: none"> • 4'd0: analog shutdown - shutdown • 4'd1: output 0 – output • 4'd2: output 1 – output • 4'd3: CLK_IDAC – output • 4'd4: interrupt – output • 4'd5: mute all channel - input • 4'd6: input selection - input • 4'd7: LOCK_STATUS – output • 4'd8: CLKEN_1FS – output • 4'd9: output PWM1 – output • 4'd10: output PWM2 – output • 4'd11: output PWM3 – output • 4'd12: volume minimum – output • 4'd13: automute status – output • 4'd14: soft ramp done – output • 4'd15: Reserved
[3:0]	GPIO5_CFG	Configures GPIO5 <ul style="list-style-type: none"> • 4'd0: analog shutdown - shutdown • 4'd1: output 0 – output • 4'd2: output 1 – output • 4'd3: CLK_IDAC – output • 4'd4: interrupt – output • 4'd5: mute all channel - input • 4'd6: input selection - input • 4'd7: LOCK_STATUS – output • 4'd8: CLKEN_1FS – output • 4'd9: output PWM1 – output • 4'd10: output PWM2 – output • 4'd11: output PWM3 – output • 4'd12: volume minimum – output • 4'd13: automute status – output • 4'd14: soft ramp done – output • 4'd15: Reserved

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Register 40: GPIO7/8 CONFIG

Bits	[7:4]	[3:0]
Default	4'd0	4'd0

Bits	Mnemonic	Description
[7:4]	GPIO8_CFG	Configures GPIO8 <ul style="list-style-type: none"> • 4'd0: analog shutdown - shutdown • 4'd1: output 0 – output • 4'd2: output 1 – output • 4'd3: CLK_IDAC – output • 4'd4: interrupt – output • 4'd5: mute all channel - input • 4'd6: input selection - input • 4'd7: LOCK_STATUS – output • 4'd8: CLKEN_1FS – output • 4'd9: output PWM1 – output • 4'd10: output PWM2 – output • 4'd11: output PWM3 – output • 4'd12: volume minimum – output • 4'd13: automute status – output • 4'd14: soft ramp done – output • 4'd15: Reserved
[3:0]	GPIO7_CFG	Configures GPIO7 <ul style="list-style-type: none"> • 4'd0: analog shutdown - shutdown • 4'd1: output 0 – output • 4'd2: output 1 – output • 4'd3: CLK_IDAC – output • 4'd4: interrupt – output • 4'd5: mute all channel - input • 4'd6: input selection - input • 4'd7: LOCK_STATUS – output • 4'd8: CLKEN_1FS – output • 4'd9: output PWM1 – output • 4'd10: output PWM2 – output • 4'd11: output PWM3 – output • 4'd12: volume minimum – output • 4'd13: automute status – output • 4'd14: soft ramp done – output • 4'd15: Reserved



Register 41: GPIO OUTPUT ENABLE

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b1	1'b1

Bits	Mnemonic	Description
[7]	GPIO8_OE	<ul style="list-style-type: none"> 1'b0: Tristate GPIO8 (default) 1'b1: GPIO8 Output Enable
[6]	GPIO7_OE	<ul style="list-style-type: none"> 1'b0: Tristate GPIO7 (default) 1'b1: GPIO7 Output Enable
[5]	GPIO6_OE	<ul style="list-style-type: none"> 1'b0: Tristate GPIO6 (default) 1'b1: GPIO6 Output Enable
[4]	GPIO5_OE	<ul style="list-style-type: none"> 1'b0: Tristate GPIO5 (default) 1'b1: GPIO5 Output Enable
[3]	GPIO4_OE	<ul style="list-style-type: none"> 1'b0: Tristate GPIO4 (default) 1'b1: GPIO4 Output Enable
[2]	GPIO3_OE	<ul style="list-style-type: none"> 1'b0: Tristate GPIO3 (default) 1'b1: GPIO3 Output Enable
[1]	GPIO2_OE	<ul style="list-style-type: none"> 1'b0: Tristate GPIO2 1'b1: GPIO2 Output Enable (default)
[0]	GPIO1_OE	<ul style="list-style-type: none"> 1'b0: Tristate GPIO1 1'b1: GPIO1 Output Enable (default)

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Register 42: GPIO INPUT

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b1	1'b1	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	GPIO8_SDB	<ul style="list-style-type: none"> 1'b0: Disables GPIO8 input (default) 1'b1: Enables GPIO8 input
[6]	GPIO7_SDB	<ul style="list-style-type: none"> 1'b0: Disables GPIO7 input (default) 1'b1: Enables GPIO7 input
[5]	GPIO6_SDB	<ul style="list-style-type: none"> 1'b0: Disables GPIO6 input (default) 1'b1: Enables GPIO6 input
[4]	GPIO5_SDB	<ul style="list-style-type: none"> 1'b0: Disables GPIO5 input (default) 1'b1: Enables GPIO5 input
[3]	GPIO4_SDB	<ul style="list-style-type: none"> 1'b0: Disables GPIO4 input (default) 1'b1: Enables GPIO4 input
[2]	GPIO3_SDB	<ul style="list-style-type: none"> 1'b0: Disables GPIO3 input (default) 1'b1: Enables GPIO3 input
[1]	GPIO2_SDB	<ul style="list-style-type: none"> 1'b0: Disables GPIO2 input (default) 1'b1: Enables GPIO2 input
[0]	GPIO1_SDB	<ul style="list-style-type: none"> 1'b0: Disables GPIO1 input (default) 1'b1: Enables GPIO1 input



Register 43: GPIO WK EN

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	GPIO8_WK_EN	<ul style="list-style-type: none"> 1'b0: GPIO8 weak keeper disabled (default) 1'b1: GPIO8 weak keeper enabled
[6]	GPIO7_WK_EN	<ul style="list-style-type: none"> 1'b0: GPIO7 weak keeper disabled (default) 1'b1: GPIO7 weak keeper enabled
[5]	GPIO6_WK_EN	<ul style="list-style-type: none"> 1'b0: GPIO6 weak keeper disabled (default) 1'b1: GPIO6 weak keeper enabled
[4]	GPIO5_WK_EN	<ul style="list-style-type: none"> 1'b0: GPIO5 weak keeper disabled (default) 1'b1: GPIO5 weak keeper enabled
[3]	GPIO4_WK_EN	<ul style="list-style-type: none"> 1'b0: GPIO4 weak keeper disabled (default) 1'b1: GPIO4 weak keeper enabled
[2]	GPIO3_WK_EN	<ul style="list-style-type: none"> 1'b0: GPIO3 weak keeper disabled (default) 1'b1: GPIO3 weak keeper enabled
[1]	GPIO2_WK_EN	<ul style="list-style-type: none"> 1'b0: GPIO2 weak keeper disabled (default) 1'b1: GPIO2 weak keeper enabled
[0]	GPIO1_WK_EN	<ul style="list-style-type: none"> 1'b0: GPIO1 weak keeper disabled (default) 1'b1: GPIO1 weak keeper enabled

Register 44: INVERT GPIO

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	INVERT_GPIO8	<ul style="list-style-type: none"> 1'b1: Inverts GPIO8 output.
[6]	INVERT_GPIO7	<ul style="list-style-type: none"> 1'b1: Inverts GPIO7 output.
[5]	INVERT_GPIO6	<ul style="list-style-type: none"> 1'b1: Inverts GPIO6 output.
[4]	INVERT_GPIO5	<ul style="list-style-type: none"> 1'b1: Inverts GPIO5 output.
[3]	INVERT_GPIO4	<ul style="list-style-type: none"> 1'b1: Inverts GPIO4 output.
[2]	INVERT_GPIO3	<ul style="list-style-type: none"> 1'b1: Inverts GPIO3 output.
[1]	INVERT_GPIO2	<ul style="list-style-type: none"> 1'b1: Inverts GPIO2 output.
[0]	INVERT_GPIO1	<ul style="list-style-type: none"> 1'b1: Inverts GPIO1 output.

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Register 45: GPIO READ

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	GPIO8_READ	<ul style="list-style-type: none"> 1'b0: GPIO8 Readback disabled (default) 1'b1: Allow readback of GPIO8_I
[6]	GPIO7_READ	<ul style="list-style-type: none"> 1'b0: GPIO7 Readback disabled (default) 1'b1: Allow readback of GPIO7_I
[5]	GPIO6_READ	<ul style="list-style-type: none"> 1'b0: GPIO6 Readback disabled (default) 1'b1: Allow readback of GPIO6_I
[4]	GPIO5_READ	<ul style="list-style-type: none"> 1'b0: GPIO5 Readback disabled (default) 1'b1: Allow readback of GPIO5_I
[3]	GPIO4_READ	<ul style="list-style-type: none"> 1'b0: GPIO4 Readback disabled (default) 1'b1: Allow readback of GPIO4_I
[2]	GPIO3_READ	<ul style="list-style-type: none"> 1'b0: GPIO3 Readback disabled (default) 1'b1: Allow readback of GPIO3_I
[1]	GPIO2_READ	<ul style="list-style-type: none"> 1'b0: GPIO2 Readback disabled (default) 1'b1: Allow readback of GPIO2_I
[0]	GPIO1_READ	<ul style="list-style-type: none"> 1'b0: GPIO1 Readback disabled (default) 1'b1: Allow readback of GPIO1_I



Register 47-46: GPIO OUTPUT LOGIC

Bits	[15]	[14:9]	[8:6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	6'd0	3'd0	1'b0	1'b0	1'b0	1'b1	1'b1	1'b1

Bits	Mnemonic	Description
[15]	GPIO_DAC_MODE	When any GPIOx_CFG = 6 (input system mode control): <ul style="list-style-type: none"> 1'b0: Power down when GPIO input is 1 1'b1: HIFI when GPIO input is 1 (when GPIO input is 0, system mode is determined by register DAC_MODE_REG (register 0, bit[1]))
[14:9]	RESERVED	NA
[8:6]	FLAG_CH_SEL	When GPIOx_CFG = 12, 13 or 14, and the corresponding GPIO_AND and GPIO_OR are not set: <ul style="list-style-type: none"> 3'd0: Outputs status/flag from ch1 3'd1: Outputs status/flag from ch2 3'd2: Outputs status/flag from ch3 3'd3: Outputs status/flag from ch4 3'd4: Outputs status/flag from ch5 3'd5: Outputs status/flag from ch6 3'd6: Outputs status/flag from ch7 3'd7: Outputs status/flag from ch8
[5]	GPIO_OR_SS_RAMP	When GPIOx_CFG = 14 (output soft ramp done flag): <ul style="list-style-type: none"> 1'b0: The soft ramp done flag is determined by GPIO_AND_SS_RAMP and GPIO_SEL (default) 1'b1: The soft ramp done flag is the "OR" of all 8ch soft ramp done flags
[4]	GPIO_OR_VOL_MIN	When GPIOx_CFG = 12 (output vol_min flag): <ul style="list-style-type: none"> 1'b0: The vol_min flag is determined by GPIO_AND_VOL_MIN and GPIO_SEL (default) 1'b1: The vol_min flag is the "OR" of all 8ch vol_min flags
[3]	GPIO_OR_AUTOMUTE	When GPIOx_CFG = 13 (output automute status): <ul style="list-style-type: none"> 1'b0: The automute status is determined by GPIO_AND_AUTOMUTE and GPIO_SEL (default) 1'b1: The automute status is the "OR" of all 8ch automute status
[2]	GPIO_AND_SS_RAMP	When GPIOx_CFG = 14 (output soft ramp done flag) and GPIO_OR_SS_RAMP is not set: <ul style="list-style-type: none"> 1'b0: The soft ramp done flag is from a single channel selected by GPIO_SEL 1'b1: The soft ramp done flag is the "AND" of all 8ch soft ramp done flags (default)

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[1]	GPIO_AND_VOL_MIN	<p>When GPIOx_CFG = 12 (output vol_min flag) and GPIO_OR_VOL_MIN is not set:</p> <ul style="list-style-type: none"> 1'b0: The vol_min flag is from a single channel selected by GPIO_SEL 1'b1: The vol_min flag is the "AND" of all 8ch vol_min flags (default)
[0]	GPIO_AND_AUTOMUTE	<p>When GPIOx_CFG = 13 (output automute status) and GPIO_OR_AUTOMUTE is not set:</p> <ul style="list-style-type: none"> 1'b0: The automute status is from a single channel selected by GPIO_SEL 1'b1: The automute status is the "AND" of all 8ch automute status (default)

Register 48: PWM1 COUNT

Bits	[7:0]
Default	8'd0

Bits	Mnemonic	Description
[7:0]	PWM1_COUNT	<p>8-bit value to set the number of SYS_CLK periods the PWM signal is high for.</p> <p>Valid from 8'd0 to 8'd255</p>

Register 50-49: PWM1 FREQUENCY

Bits	[15:0]
Default	16'd0

Bits	Mnemonic	Description
[15:0]	PWM1_FREQ	<p>16-bit value to set the frequency of the PWM signal in terms of SYS_CLK divisions.</p> <p>Valid from 16'h0000 to 16'hFFFF</p> $frequency(Hz) = SYS_CLK / (PWM1_FREQ + 1)$ $Duty\ Cycle\ (\%) = (PWM1_COUNT) / (PWM1_FREQ + 1) \times 100$

**Register 51: PWM2 COUNT**

Bits	[7:0]
Default	8'd0

Bits	Mnemonic	Description
[7:0]	PWM2_COUNT	8-bit value to set the number of SYS_CLK periods the PWM signal is high for. Valid from 8'd0 to 8'd255

Register 53-52: PWM2 FREQUENCY

Bits	[15:0]
Default	16'd0

Bits	Mnemonic	Description
[15:0]	PWM2_FREQ	16-bit value to set the frequency of the PWM signal in terms of SYS_CLK divisions. Valid from 16'h0000 to 16'hFFFF $frequency(Hz) = SYS_CLK / (PWM2_FREQ + 1)$ $Duty\ Cycle\ (\%) = (PWM2_COUNT) / (PWM2_FREQ + 1) \times 100$

Register 54: PWM3 COUNT

Bits	[7:0]
Default	8'd0

Bits	Mnemonic	Description
[7:0]	PWM3_COUNT	8-bit value to set the number of SYS_CLK periods the PWM signal is high for. Valid from 8'd0 to 8'd255

Register 56-55: PWM3 FREQUENCY

Bits	[15:0]
Default	16'd0

Bits	Mnemonic	Description
[15:0]	PWM3_FREQ	16-bit value to set the frequency of the PWM signal in terms of SYS_CLK divisions. Valid from 16'h0000 to 16'hFFFF $frequency(Hz) = SYS_CLK / (PWM3_FREQ + 1)$ $Duty\ Cycle\ (\%) = (PWM3_COUNT) / (PWM3_FREQ + 1) \times 100$



DAC Registers

Register 57: INPUT SELECTION

Bits	[7]	[6]	[5]	[4]	[3]	[2:1]	[0]
Default	1'b0	1'b1	1'b0	1'b0	1'b0	2'd0	1'b0

Bits	Mnemonic	Description
[7]	AUTO_CH_DETECT	Auto detect BCK/FRAME ratio to determine the number of TDM channels <ul style="list-style-type: none"> 1'b0: Disabled (default) 1'b1: Enabled
[6]	ENABLE_DSD_FAULT_DETECTION	Sets a channel to a DSD mute pattern (0x96) if the DSD data has no changes in 64 DATA_CLKs. <ul style="list-style-type: none"> 1'b0: Disabled 1'b1: Enabled (default)
[5]	DSD_MASTER_MODE	DSD master mode config. <ul style="list-style-type: none"> 1'b0: DSD slave mode (default) 1'b1: DSD master mode. DSD_CLK outputs from DATA_CLK
[4]	PCM_MASTER_MODE	PCM master mode config. <ul style="list-style-type: none"> 1'b0: PCM slave mode (default) 1'b1: PCM master mode enabled. Master BCK and WS output from DATA_CLK and DATA1
[3]	RESERVED	NA
[2:1]	INPUT_SEL	Selects input data format when AUTO_INPUT_SELECT is disabled. <ul style="list-style-type: none"> 2'd0: TDM (default) 2'd1: DSD 2'd2: DoP 2'd3: S/PDIF
[0]	AUTO_INPUT_SEL	Automatic input data selection config. <ul style="list-style-type: none"> 1'b0: Disables auto input select. Input data format is set by INPUT_SEL (default) 1'b1: Automatically determine the input data format.



Register 58: SERIAL MASTER ENCODER CONFIG

Bits	[7]	[6]	[5]	[4:3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	2'd0	1'b0	1'b0	1'b1

Bits	Mnemonic	Description
[7]	TDM_RESYNC	Force TDM decoder to resync. <ul style="list-style-type: none"> 1'b0: Let decoder sync (default) 1'b1: Force decoder not sync
[6]	BCK_INV	Invert the slave BCK <ul style="list-style-type: none"> 1'b0: Normal operation 1'b1: Invert slave BCK
[5]	RESERVED	NA
[4:3]	MASTER_FRAME_LENGTH	Selects the bit length in each TDM channel in master mode. <ul style="list-style-type: none"> 2'd0: 32-bit (default) 2'd1: 24-bit 2'd2: 16-bit 2'd3: Reserved
[2]	MASTER_WS_PULSE_MODE	When enabled, master WS is a pulse signal instead of a 50% duty cycle signal. The pulse width is 1 BCK cycle. <ul style="list-style-type: none"> 1'b0: 50% duty cycle WS signal (default) 1'b1: Pulse WS signal
[1]	MASTER_WS_INVERT	Inverts master WS. <ul style="list-style-type: none"> 1'b0: Non-inverted (default) 1'b1: Inverted
[0]	MASTER_BCK_INVERT	Inverts master BCK or DSD_CLK. <ul style="list-style-type: none"> 1'b0: Non-inverted 1'b1: Inverted (default)

Register 59: TDM CONFIG

Bits	[7:5]	[4:0]
Default	3'd0	5'd1

Bits	Mnemonic	Description
[7:5]	RESERVED	NA
[4:0]	TDM_CH_NUM	Total number of TDM slots per frame = TDM_CH_NUM + 1.

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Register 60: TDM CONFIG1

Bits	[7]	[6]	[5:0]
Default	1'b0	1'b0	6'd0

Bits	Mnemonic	Description
[7]	TDM_LJ_MODE	TDM LJ mode. <ul style="list-style-type: none"> 1'b0: Standard I²S (default) 1'b1: LJ mode
[6]	TDM_VALID_EDGE	TDM WS valid edge. <ul style="list-style-type: none"> 1'b0: negative edge (default) 1'b1: positive edge
[5:0]	RESERVED	NA

Register 61: TDM CONFIG2

Bits	[7]	[6:5]	[4:0]
Default	1'b1	2'b00	5'd0

Bits	Mnemonic	Description
[7]	ENABLE_ASYNC_LOCK_MONITOR	Monitors the lock status of the SRC, when in ASYNC mode. Sets BCK_WS_FAIL on unlock. <ul style="list-style-type: none"> 1'b0: Disabled 1'b1: Enabled (default)
[6:5]	TDM_BIT_WIDTH	Bit width of each TDM slot. <ul style="list-style-type: none"> 2'b00: 32-bit (default) 2'b01: 24-bit 2'b10: 16-bit 2'b11: Reserved
[4:0]	RESERVED	NA



Register 62: BCK/WS MONITOR CONFIG

Bits	[7]	[6]	[5]	[4]	[3]	[2:0]
Default	1'b0	1'b0	1'b1	1'b1	1'b0	3'd0

Bits	Mnemonic	Description
[7]	DISABLE_DSD_DC	<ul style="list-style-type: none"> 1'b0: DSD DC can trigger an automute if automute is enabled (default) 1'b1: DSD DC is ignored.
[6]	DISABLE_DSD_MUTE	<ul style="list-style-type: none"> 1'b0: DSD mute pattern can trigger an automute is automute is enabled (default) 1'b1: DSD mute pattern is ignored.
[5]	ENABLE_WS_MONITOR	Enable WS monitor. <ul style="list-style-type: none"> 1'b0: Disable 1'b1: Enable (default)
[4]	ENABLE_BCK_MONITOR	Enable BCK monitor. <ul style="list-style-type: none"> 1'b0: Disable (default) 1'b1: Enable
[3]	DISABLE_PCM_DC	<ul style="list-style-type: none"> 1'b0: PCM DC signal can trigger an automute if automute is enabled. 1'b1: PCM DC is ignored.
[2:0]	RESERVED	NA

Register 63: RESERVED

Register 64: TDM CH1 CONFIG

Bits	[7]	[6:5]	[4:0]
Default	1'b0	2'd0	5'd0

Bits	Mnemonic	Description
[7]	RESERVED	NA
[6:5]	TDM_CH1_LINE_SEL	CH1 data line selection, only valid for TDM, PCM and DoP. CH1 receives data from: <ul style="list-style-type: none"> 2'd0: DATA2 (default) 2'd1: DATA3 2'd2: DATA4/GPIO4 2'd3: DATA5/GPIO5 Note: Must have GPIO4_SDB and GPIO5_SDB set
[4:0]	TDM_CH1_SLOT_SEL	CH1 data slot selection. CH1 receives data from the selected slot. Selected Slot = TDM_CH1_SLOT_SEL + 1. Note: Valid for TDM, PCM and DoP.

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Register 65: TDM CH2 CONFIG

Bits	[7]	[6:5]	[4:0]
Default	1'b0	2'd0	5'd1

Bits	Mnemonic	Description
[7]	RESERVED	NA
[6:5]	TDM_CH2_LINE_SEL	CH2 data line selection, only valid for TDM, PCM and DoP. CH2 receives data from: <ul style="list-style-type: none"> • 2'd0: DATA2 (default) • 2'd1: DATA3 • 2'd2: DATA4/GPIO4 • 2'd3: DATA5/GPIO5 Note: Must have GPIO4_SDB and GPIO5_SDB set
[4:0]	TDM_CH2_SLOT_SEL	CH2 data slot selection. CH2 receives data from the selected slot. Selected Slot = TDM_CH2_SLOT_SEL + 1. Note: Valid for TDM, PCM and DoP.

Register 66: TDM CH3 CONFIG

Bits	[7]	[6:5]	[4:0]
Default	1'b0	2'd1	5'd0

Bits	Mnemonic	Description
[7]	RESERVED	NA
[6:5]	TDM_CH3_LINE_SEL	CH3 data line selection, only valid for TDM, PCM and DoP. CH3 receives data from: <ul style="list-style-type: none"> • 2'd0: DATA2 • 2'd1: DATA3 (default) • 2'd2: DATA4/GPIO4 • 2'd3: DATA5/GPIO5 Note: Must have GPIO4_SDB and GPIO5_SDB set
[4:0]	TDM_CH3_SLOT_SEL	CH3 data slot selection. CH3 receives data from the selected slot. Selected Slot = TDM_CH3_SLOT_SEL + 1. Note: Valid for TDM, PCM and DoP.



Register 67: TDM CH4 CONFIG

Bits	[7]	[6:5]	[4:0]
Default	1'b0	2'd1	5'd1

Bits	Mnemonic	Description
[7]	RESERVED	NA
[6:5]	TDM_CH4_LINE_SEL	CH4 data line selection, only valid for TDM, PCM and DoP. CH4 receives data from: <ul style="list-style-type: none"> • 2'd0: DATA2 • 2'd1: DATA3 (default) • 2'd2: DATA4/GPIO4 • 2'd3: DATA5/GPIO5 Note: Must have GPIO4_SDB and GPIO5_SDB set
[4:0]	TDM_CH4_SLOT_SEL	CH4 data slot selection. CH4 receives data from the selected slot. Selected Slot = TDM_CH4_SLOT_SEL + 1. Note: Valid for TDM, PCM and DoP.

Register 68: TDM CH5 CONFIG

Bits	[7]	[6:5]	[4:0]
Default	1'b0	2'd2	5'd0

Bits	Mnemonic	Description
[7]	RESERVED	NA
[6:5]	TDM_CH5_LINE_SEL	CH5 data line selection, only valid for TDM, PCM and DoP. CH5 receives data from: <ul style="list-style-type: none"> • 2'd0: DATA2 • 2'd1: DATA3 • 2'd2: DATA4/GPIO4 (default) • 2'd3: DATA5/GPIO5 Note: Must have GPIO4_SDB and GPIO5_SDB set
[4:0]	TDM_CH5_SLOT_SEL	CH5 data slot selection. CH5 receives data from the selected slot. Selected Slot = TDM_CH5_SLOT_SEL + 1. Note: Valid for TDM, PCM and DoP.

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Register 69: TDM CH6 CONFIG

Bits	[7]	[6:5]	[4:0]
Default	1'b0	2'd2	5'd1

Bits	Mnemonic	Description
[7]	RESERVED	NA
[6:5]	TDM_CH6_LINE_SEL	CH6 data line selection, only valid for TDM, PCM and DoP. CH6 receives data from: <ul style="list-style-type: none"> • 2'd0: DATA2 • 2'd1: DATA3 • 2'd2: DATA4/GPIO4 (default) • 2'd3: DATA5/GPIO5 Note: Must have GPIO4_SDB and GPIO5_SDB set
[4:0]	TDM_CH6_SLOT_SEL	CH6 data slot selection. CH6 receives data from the selected slot. Selected Slot = TDM_CH6_SLOT_SEL + 1. Note: Valid for TDM, PCM and DoP.

Register 70: TDM CH7 CONFIG

Bits	[7]	[6:5]	[4:0]
Default	1'b0	2'd3	5'd0

Bits	Mnemonic	Description
[7]	RESERVED	NA
[6:5]	TDM_CH7_LINE_SEL	CH7 data line selection, only valid for TDM, PCM and DoP. CH7 receives data from: <ul style="list-style-type: none"> • 2'd0: DATA2 • 2'd1: DATA3 • 2'd2: DATA4/GPIO4 • 2'd3: DATA5/GPIO5 (default) Note: Must have GPIO4_SDB and GPIO5_SDB set
[4:0]	TDM_CH7_SLOT_SEL	CH7 data slot selection. CH7 receives data from the selected slot. Selected Slot = TDM_CH7_SLOT_SEL + 1. Note: Valid for TDM, PCM and DoP.



Register 71: TDM CH8 CONFIG

Bits	[7]	[6:5]	[4:0]
Default	1'b0	2'd3	5'd1

Bits	Mnemonic	Description
[7]	RESERVED	NA
[6:5]	TDM_CH8_LINE_SEL	CH8 data line selection, only valid for TDM, PCM and DoP. CH8 receives data from: <ul style="list-style-type: none"> • 2'd0: DATA2 • 2'd1: DATA3 • 2'd2: DATA4/GPIO4 • 2'd3: DATA5/GPIO5 (default) Note: Must have GPIO4_SDB and GPIO5_SDB set
[4:0]	TDM_CH8_SLOT_SEL	CH8 data slot selection. CH8 receives data from the selected slot. Selected Slot = TDM_CH8_SLOT_SEL + 1. Note: Valid for TDM, PCM and DoP.

Register 73-72: RESERVED

Register 78: VOLUME5

Bits	[7:0]
Default	8'd0

Bits	Mnemonic	Description
[7:0]	VOLUME5	DAC ch5 volume. -0dB to -127.5dB, 0.5dB steps. <ul style="list-style-type: none"> • 8'd0: 0dB • 8'd255: -127.5dB

Register 79: VOLUME6

Bits	[7:0]
Default	8'd0

Bits	Mnemonic	Description
[7:0]	VOLUME6	DAC ch6 volume. -0dB to -127.5dB, 0.5dB steps. <ul style="list-style-type: none"> • 8'd0: 0dB • 8'd255: -127.5dB

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Register 80: VOLUME7

Bits	[7:0]
Default	8'd0

Bits	Mnemonic	Description
[7:0]	VOLUME7	DAC ch7 volume. -0dB to -127.5dB, 0.5dB steps. <ul style="list-style-type: none"> 8'd0: 0dB 8'd255: -127.5dB

Register 81: VOLUME8

Bits	[7:0]
Default	8'd0

Bits	Mnemonic	Description
[7:0]	VOLUME8	DAC ch8 volume. -0dB to -127.5dB, 0.5dB steps. <ul style="list-style-type: none"> 8'd0: 0dB 8'd255: -127.5dB

Register 82: DAC VOL UP RATE

Bits	[7:0]
Default	8'd4

Bits	Mnemonic	Description
[7:0]	DAC_VOL_RATE_UP	Value by which the old VOLUME value is incremented to reach the new VOLUME value <ul style="list-style-type: none"> 8'd0: Instant change 8'd1: Slowest change 8'd4: Default value 8'd255: Fastest change $\text{ramp_rate}[s] = 2^{15} / (\text{DAC_VOL_RATE_UP} * FS)$

**Register 83: DAC VOL DOWN RATE**

Bits	[7:0]
Default	8'd4

Bits	Mnemonic	Description
[7:0]	DAC_VOL_RATE_DOWN	Value by which the old VOLUME value is incremented to reach the new VOLUME value <ul style="list-style-type: none"> 8'd0: Instant change 8'd1: Slowest change 8'd4: Default value 8'd255: Fastest change $ramp_rate[s] = 2^{15} / (DAC_VOL_RATE_DOWN * FS)$

Register 84: DAC VOL DOWN RATE FAST

Bits	[7:0]
Default	8'd255

Bits	Mnemonic	Description
[7:0]	DAC_VOL_RATE_FAST	Value by which the old VOLUME value is incremented to reach the new VOLUME value Only used during abnormal mute (PLL unlock or BCK_WS ratio failed) <ul style="list-style-type: none"> 8'd0: Instant change 8'd1: Slowest change 8'd255: Fastest change (default) $ramp_rate[s] = 2^{15} / (DAC_VOL_RATE_FAST * FS)$

Register 85: RESERVED

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Register 86: DAC MUTE

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	DAC_MUTE_CH8	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Mute ch8
[6]	DAC_MUTE_CH7	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Mute ch7
[5]	DAC_MUTE_CH6	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Mute ch6
[4]	DAC_MUTE_CH5	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Mute ch5
[3]	DAC_MUTE_CH4	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Mute ch4
[2]	DAC_MUTE_CH3	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Mute ch3
[1]	DAC_MUTE_CH2	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Mute ch2
[0]	DAC_MUTE_CH1	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Mute ch1



Register 87: DAC INVERT

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0	1'b0

Bits	Mnemonic	Description
[7]	DAC_INVERT_CH8	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Invert the output on Ch8, OUT/OUTB are phase inverted
[6]	DAC_INVERT_CH7	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Invert the output on Ch7, OUT/OUTB are phase inverted
[5]	DAC_INVERT_CH6	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Invert the output on Ch6, OUT/OUTB are phase inverted
[4]	DAC_INVERT_CH5	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Invert the output on Ch5, OUT/OUTB are phase inverted
[3]	DAC_INVERT_CH4	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Invert the output on Ch4, OUT/OUTB are phase inverted
[2]	DAC_INVERT_CH3	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Invert the output on Ch3, OUT/OUTB are phase inverted
[1]	DAC_INVERT_CH2	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Invert the output on Ch2, OUT/OUTB are phase inverted
[0]	DAC_INVERT_CH1	<ul style="list-style-type: none"> 1'b0: Normal operation (default) 1'b1: Invert the output on Ch1, OUT/OUTB are phase inverted

Register 88: FILTER SHAPE

Bits	[7:3]	[2:0]
Default	5'd23	3'd0

Bits	Mnemonic	Description
[7:3]	RESERVED	NA
[2:0]	FILTER_SHAPE	Selects the 8x interpolation FIR filter shape. <ul style="list-style-type: none"> 3'd0: Minimum phase (default) 3'd1: Linear phase apodizing 3'd2: Linear phase fast roll-off 3'd4: Linear phase slow roll-off 3'd5: Minimum phase fast roll-off 3'd6: Minimum phase slow roll-off 3'd7: Minimum phase slow roll-off low dispersion

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Register 89: IIR BANDWIDTH & S/PDIF SELECT

Bits	[7:4]	[3]	[2:0]
Default	4'd0	1'b0	3'd4

Bits	Mnemonic	Description
[7:4]	SPDIF_SEL	<p>Selects the S/PDIF data input pin</p> <ul style="list-style-type: none"> • 4'd0: Disconnected (default) • 4'd1: GPIO1 • 4'd2: GPIO2 • 4'd3: GPIO3 • 4'd4: DATA1 • 4'd5: DATA2 • 4'd6: DATA3 • 4'd7: DATA4/GPIO4 • 4'd8: DATA5/GPIO5 • 4'd9: DATA6/GPIO6 • 4'd10: DATA7/GPIO7 • 4'd11: DATA8/GPIO8 • Others: Reserved <p>Note: GPIO pins also require the GPIO input to be enabled</p>
[3]	VOLUME_HOLD	Hold volume coefficients to allow for all channels to update at same time.
[2:0]	IIR_BW	<p>Controls the IIR bandwidth in the digital datapath.</p> <ul style="list-style-type: none"> • 3'd0: Invalid • 3'd1: BW * 8 • 3'd2: BW * 4 • 3'd3: BW * 2 • 3'd4: Default BW • 3'd5: BW / 2 • 3'd6: BW / 4 • 3'd7: BW / 8

Register 90: DAC PATH CONFIG

Bits	[7:2]	[1]	[0]
Default	6'b000000	1'b0	1'b0



Bits	Mnemonic	Description
[7:2]	RESERVED	NA
[1]	BYPASS_FIR4X	<ul style="list-style-type: none"> 1'b0: Non-bypass IFir_4x (default) 1'b1: Bypass IFir_4x
[0]	BYPASS_FIR2X	<ul style="list-style-type: none"> 1'b0: Non-bypass IFir_2x (default) 1'b1: Bypass IFir_2x

Register 122-91: RESERVED

Register 123: AUTOMUTE ENABLE

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	1'b1	1'b1	1'b1	1'b1	1'b1	1'b1	1'b1	1'b1

Bits	Mnemonic	Description
[7]	AUTOMUTE_EN_CH8	<ul style="list-style-type: none"> 1'b0: Disables ch8 automute 1'b1: Enables ch8 automute (default) Note: Automute is available for PCM only
[6]	AUTOMUTE_EN_CH7	<ul style="list-style-type: none"> 1'b0: Disables ch7 automute 1'b1: Enables ch7 automute (default) Note: Automute is available for PCM only
[5]	AUTOMUTE_EN_CH6	<ul style="list-style-type: none"> 1'b0: Disables ch6 automute 1'b1: Enables ch6 automute (default) Note: Automute is available for PCM only
[4]	AUTOMUTE_EN_CH5	<ul style="list-style-type: none"> 1'b0: Disables ch5 automute 1'b1: Enables ch5 automute (default) Note: Automute is available for PCM only
[3]	AUTOMUTE_EN_CH4	<ul style="list-style-type: none"> 1'b0: Disables ch4 automute 1'b1: Enables ch4 automute (default) Note: Automute is available for PCM only
[2]	AUTOMUTE_EN_CH3	<ul style="list-style-type: none"> 1'b0: Disables ch3 automute 1'b1: Enables ch3 automute (default) Note: Automute is available for PCM only
[1]	AUTOMUTE_EN_CH2	<ul style="list-style-type: none"> 1'b0: Disables ch2 automute 1'b1: Enables ch2 automute (default) Note: Automute is available for PCM only
[0]	AUTOMUTE_EN_CH1	<ul style="list-style-type: none"> 1'b0: Disables ch1 automute 1'b1: Enables ch1 automute (default) Note: Automute is available for PCM only

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Register 125-124: AUTOMUTE TIME

Bits	[15:12]	[11]	[10:0]
Default	4'd0	1'b1	11'd15

Bits	Mnemonic	Description
[15:12]	RESERVED	NA
[11]	AUTOMUTE_RAMP_TO_GROUND	<ul style="list-style-type: none"> 1'b0: When ramped to min volume during normal mute, do not soft ramp to ground 1'b1: When ramped to min volume during normal mute, soft ramp to ground for power saving (default) normal mute includes: automute, mute by register, mute by GPIO
[10:0]	AUTOMUTE_TIME	Configures the amount of time in seconds the audio must remain below AUTOMUTE_LEVEL before an automute condition is flagged. Valid from 0 (disabled) to 11'h7FF (fastest), where 11'h001 is the slowest $Time[s] = 2^8 / (AUTOMUTE_TIME * FS)$

Register 127-126: AUTOMUTE LEVEL

Bits	[15:0]
Default	16'0008

Bits	Mnemonic	Description
[15:0]	AUTOMUTE_LEVEL	Configures the threshold which the audio must be below before an automute condition is flagged. Valid from: 16'hFFFF (-42dB) to 16'h0001 (-132dB) Shift right 1 bit corresponds to -6dB Note: this register works in tandem with AUTOMUTE_TIME to create the automute condition

Register 129-128: AUTOMUTE OFF LEVEL

Bits	[15:0]
Default	16'000A

Bits	Mnemonic	Description
[15:0]	AUTOMUTE_OFF_LEVEL	Configures the threshold which the audio must be above before the automute condition is cleared (cleared immediately). Valid from: 16'hFFFF (-42dB) to 16'h0001 (-132dB) Shift right 1 bit corresponds to -6dB



Register 130: SOFT RAMP CONFIG

Bits	[7:5]	[4:0]
Default	3'd0	5'd3

Bits	Mnemonic	Description
[7:5]	RESERVED	NA
[4:0]	SOFT_RAMP_TIME	<p>Sets the amount of time that it takes to perform a soft start ramp. This time affects both ramp to ground and ramp to AVCC/2. Valid from 0 to 20 (inclusive).</p> $Time[s] = 4096 * (2^{(SOFT_RAMP_TIME+1)}) / CLK_{DAC}[Hz]$

Register 145-131: RESERVED



Readback Registers

Register 224: SYS READ

Bits	[7:4]	[3:2]	[1]	[0]
Default	-	-	-	-

Bits	Mnemonic	Description
[7:4]	RESERVED	NA
[3:2]	MODES	Chip mode readback. Based off MODE Pin (Pin 3) <ul style="list-style-type: none"> 2'b00: I²C 2'b11: SPI Note: All other values are invalid.
[1]	ADDR1	I ² C address select bit1.
[0]	ADDR0	I ² C address select bit0.

Register 225: CHIP ID READ

Bits	[7:0]
Default	8'h58

Bits	Mnemonic	Description
[7:0]	CHIP_ID	Chip ID. <ul style="list-style-type: none"> ES9027PRO: 0x58

Register 228-226: RESERVED



Register 233-229: INTERRUPT STATE

Bits	[39:32]	[31:30]	[29]	[28:26]	[25]	[24]	[23:16]	[15:8]	[7:0]
Default	-	-	-	-	-	-	-	-	-

Bits	Mnemonic	Description
[39:32]	RESERVED	NA
[31:30]	INPUT_SELECT_OVERRIDE_STATE	State of the INPUT_SELECT_OVERRIDE interrupt. Note: Interrupt clear bits are required to reset value.
[29]	TDM_DATA_VALID_STATE	State of the TDM_DATA_VALID interrupt. Note: Interrupt clear bit is required to reset value.
[28:26]	RESERVED	NA
[25]	BCK_WS_FAIL_STATE	State of the BCK_WS_FAIL interrupt. Note: Interrupt clear bit is required to reset value.
[24]	DOP_VALID_STATE	State of the DOP_VALID interrupt. Note: Interrupt clear bit is required to reset value.
[23:16]	SS_FULL_RAMP_STATE	State of each channel's SS_FULL_RAMP interrupt. Note: Interrupt clear bit is required to reset value.
[15:8]	AUTOMUTE_STATE	State of each channel's AUTOMUTE_STATE interrupt. Note: Interrupt clear bit is required to reset value.
[7:0]	VOL_MIN_STATE	State of each channel's VOL_MIN_STATE interrupt. Note: Interrupt clear bit is required to reset value.

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Register 238-234: INTERRUPT SOURCE

Bits	[39:32]	[31:30]	[29]	[28:26]	[25]	[24]	[23:16]	[15:8]	[7:0]
Default	-	-	-	-	-	-	-	-	-

Bits	Mnemonic	Description
[39:32]	RESERVED	NA
[31:30]	INPUT_SELECT_OVERRIDE_SOURCE	Output of the AUTO_INPUT_SELECT logic.
[29]	TDM_DATA_VALID_SOURCE	TDM data valid flag.
[28:26]	RESERVED	NA
[25]	BCK_WS_FAIL_SOURCE	Validity of BCK, WS, and ASYNC_LOCK flag. Requires respective monitor bits to be set.
[24]	DOP_VALID_SOURCE	Valid DoP flag for Channels 1 and 2.
[23:16]	SS_FULL_RAMP_SOURCE	Channel flag for whether it is fully ramped up or down.
[15:8]	AUTOMUTE_SOURCE	Channel flag for whether it is automute is active.
[7:0]	VOL_MIN_SOURCE	Channel flag for whether the corresponding volume register = 0x00

Register 239: RATIO VALID READ

Bits	[7]	[6:0]
Default	-	-

Bits	Mnemonic	Description
[7]	RATIO_VALID	Indicates validity of the CLK_DAC/CLK_IDAC ratio <ul style="list-style-type: none"> • 1'b0: Invalid • 1'b1: Valid
[6:0]	RESERVED	NA



Register 240: GPIO READ

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	-	-	-	-	-	-	-	-

Bits	Mnemonic	Description
[7]	GPIO8_I_READ	GPIO8 Readback
[6]	GPIO7_I_READ	GPIO7 Readback
[5]	GPIO6_I_READ	GPIO6 Readback
[4]	GPIO5_I_READ	GPIO5 Readback
[3]	GPIO4_I_READ	GPIO4 Readback
[2]	GPIO3_I_READ	GPIO3 Readback
[1]	GPIO2_I_READ	GPIO2 Readback
[0]	GPIO1_I_READ	GPIO1 Readback

Register 241: VOL MIN READ

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	-	-	-	-	-	-	-	-

Bits	Mnemonic	Description
[7]	VOL_MIN_CH8	Volume min flag ch8
[6]	VOL_MIN_CH7	Volume min flag ch7
[5]	VOL_MIN_CH6	Volume min flag ch6
[4]	VOL_MIN_CH5	Volume min flag ch5
[3]	VOL_MIN_CH4	Volume min flag ch4
[2]	VOL_MIN_CH3	Volume min flag ch3
[1]	VOL_MIN_CH2	Volume min flag ch2
[0]	VOL_MIN_CH1	Volume min flag ch1



Register 242: AUTOMUTE READ

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	-	-	-	-	-	-	-	-

Bits	Mnemonic	Description
[7]	AUTOMUTE_CH8	Automute status ch8
[6]	AUTOMUTE_CH7	Automute status ch7
[5]	AUTOMUTE_CH6	Automute status ch6
[4]	AUTOMUTE_CH5	Automute status ch5
[3]	AUTOMUTE_CH4	Automute status ch4
[2]	AUTOMUTE_CH3	Automute status ch3
[1]	AUTOMUTE_CH2	Automute status ch2
[0]	AUTOMUTE_CH1	Automute status ch1

Register 243: SOFT RAMP UP READ

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	-	-	-	-	-	-	-	-

Bits	Mnemonic	Description
[7]	SS_RAMP_UP_CH8	Soft ramped up flag ch8
[6]	SS_RAMP_UP_CH7	Soft ramped up flag ch7
[5]	SS_RAMP_UP_CH6	Soft ramped up flag ch6
[4]	SS_RAMP_UP_CH5	Soft ramped up flag ch5
[3]	SS_RAMP_UP_CH4	Soft ramped up flag ch4
[2]	SS_RAMP_UP_CH3	Soft ramped up flag ch3
[1]	SS_RAMP_UP_CH2	Soft ramped up flag ch2
[0]	SS_RAMP_UP_CH1	Soft ramped up flag ch1

**Register 244: SOFT RAMP DOWN READ**

Bits	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Default	-	-	-	-	-	-	-	-

Bits	Mnemonic	Description
[7]	SS_RAMP_DOWN_CH8	Soft ramped down flag ch8
[6]	SS_RAMP_DOWN_CH7	Soft ramped down flag ch7
[5]	SS_RAMP_DOWN_CH6	Soft ramped down flag ch6
[4]	SS_RAMP_DOWN_CH5	Soft ramped down flag ch5
[3]	SS_RAMP_DOWN_CH4	Soft ramped down flag ch4
[2]	SS_RAMP_DOWN_CH3	Soft ramped down flag ch3
[1]	SS_RAMP_DOWN_CH2	Soft ramped down flag ch2
[0]	SS_RAMP_DOWN_CH1	Soft ramped down flag ch1

Register 245: S/PDIF, TDM, DOP, AND INPUT READBACK

Bits	[7]	[6]	[5:2]	[1:0]
Default	-	-	-	-

Bits	Mnemonic	Description
[7]	SPDIF_VALID	S/PDIF valid flag
[6]	TDM_DATA_VALID	TDM valid data flag
[5:2]	DOP_VALID	DoP valid flag
[1:0]	INPUT_SELECT_OVERRIDE	AUTO_INPUT_SEL value

Register 251-246: RESERVED



ES9027PRO Reference Schematic

Hardware Mode

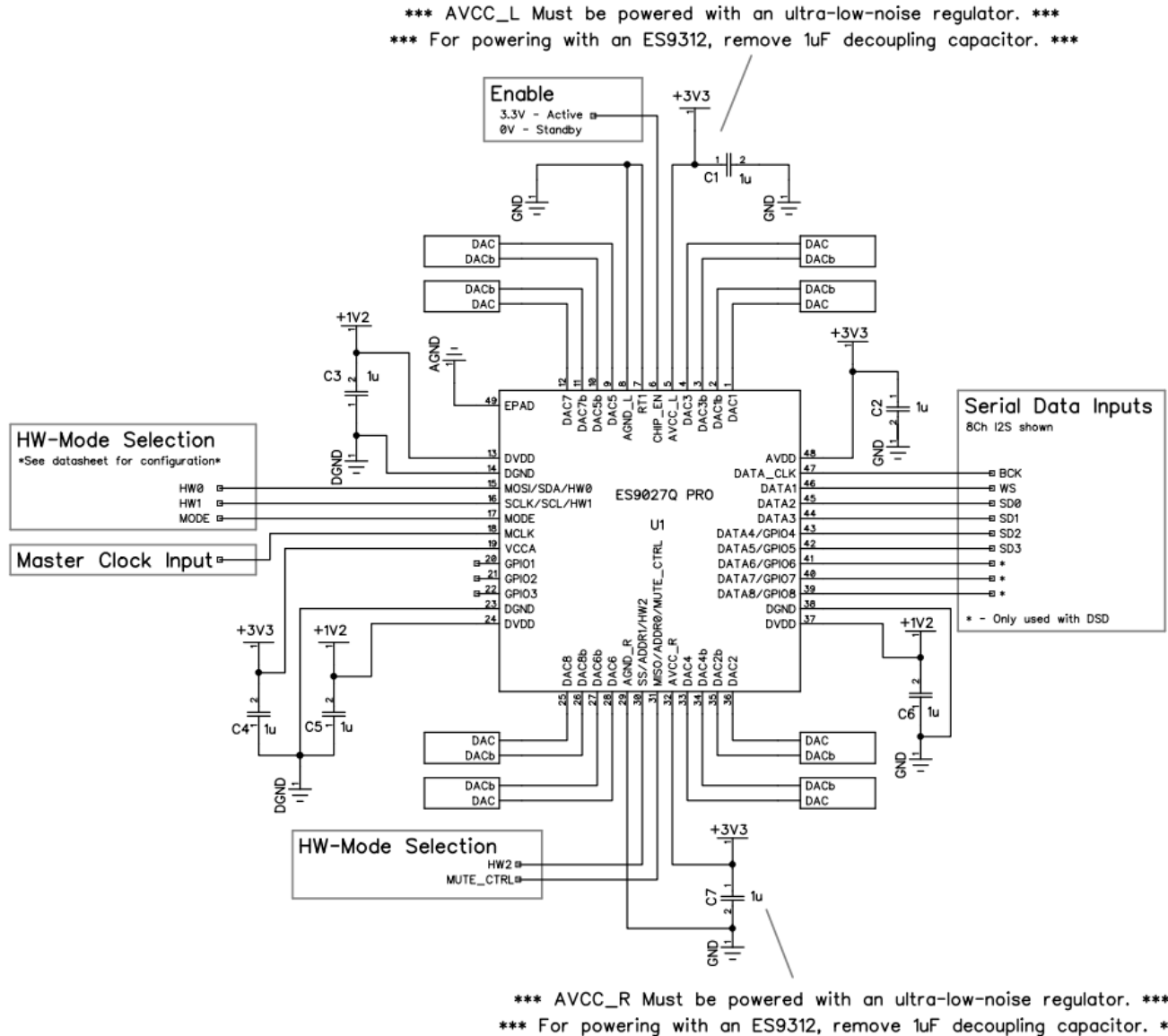


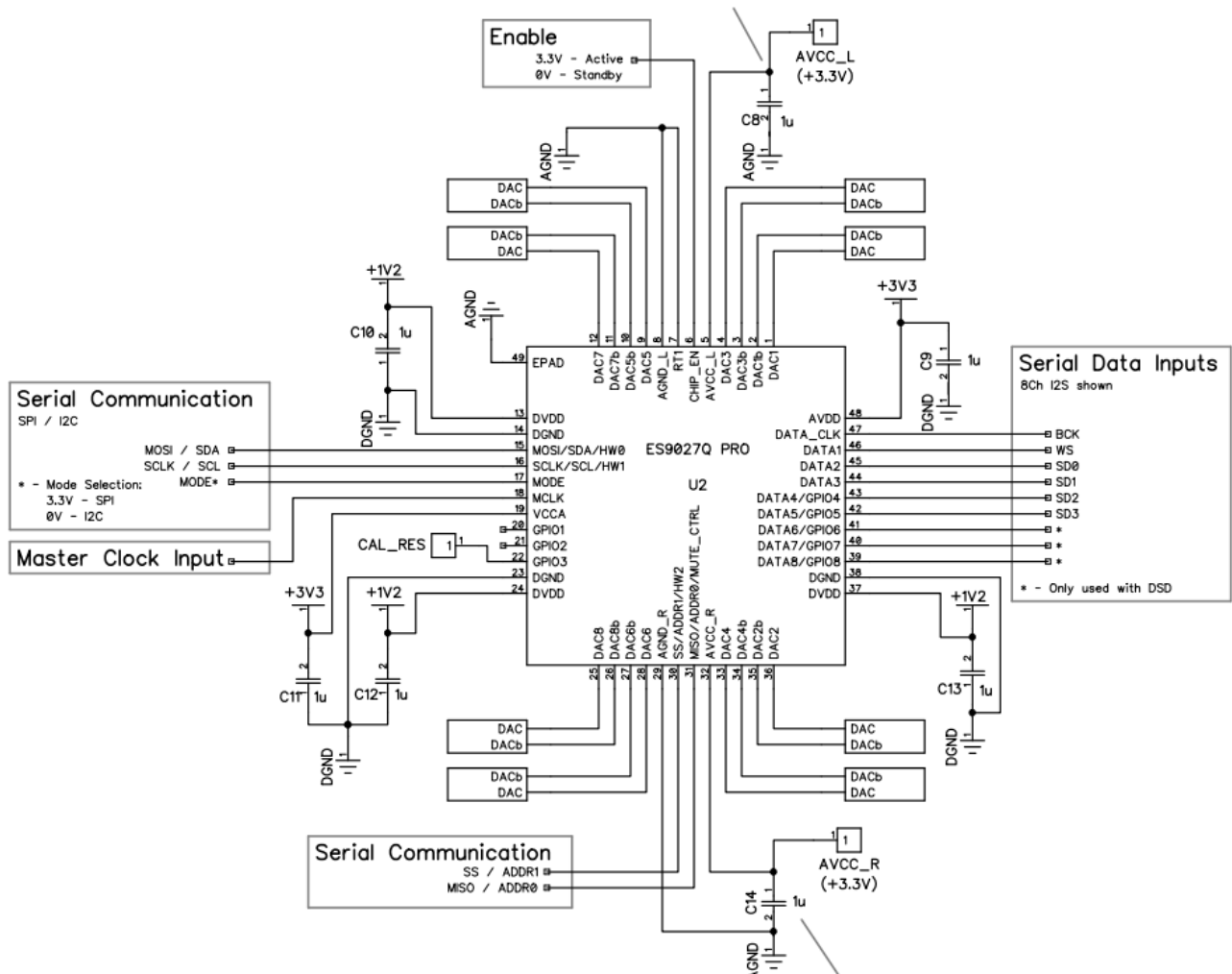
Figure 20 - ES9027QPRO & ES9027SPRO Hardware Mode Reference Schematic

Note: The ES9027QPRO QFN package has an exposed pad (Pin 49) that should be connected to ground.



Software Mode

*** AVCC_L Must be powered with an ultra-low-noise regulator. ***
 *** For powering with an ES9312, remove 1uF decoupling capacitor. ***



*** AVCC_R Must be powered with an ultra-low-noise regulator. ***
 *** For powering with an ES9312, remove 1uF decoupling capacitor. ***

Figure 21 - ES9027QPRO & ES9027SPRO Software Mode Reference Schematic

Note: The ES9027QPRO QFN package has an exposed pad (Pin 49) that should be connected to ground.

Reference Output Stage

This output stage is used on the ES9027PRO 1v2 evaluation boards.

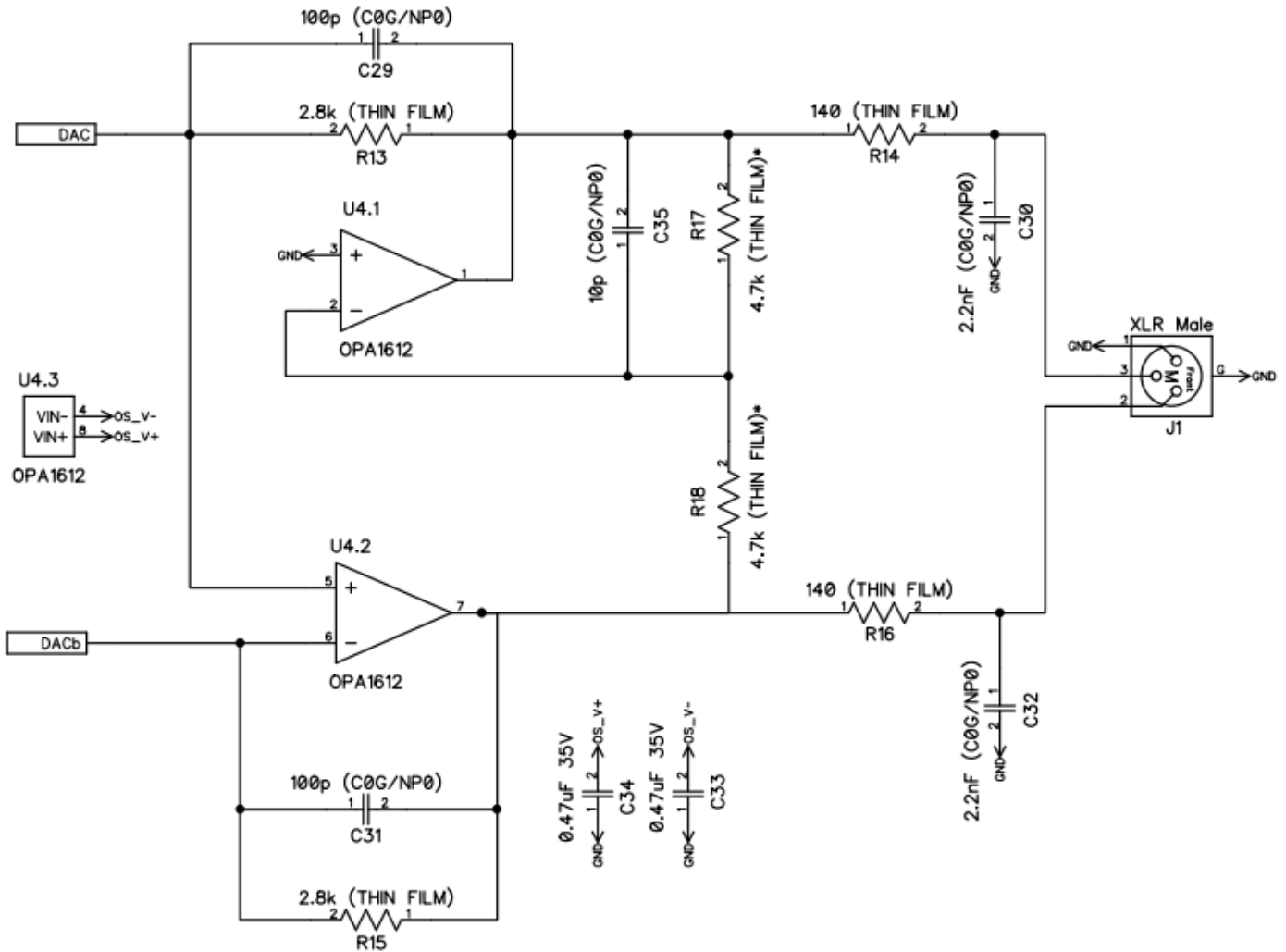


Figure 22 - ES9027PRO Output Stage Reference Schematic



Recommended Power Supply

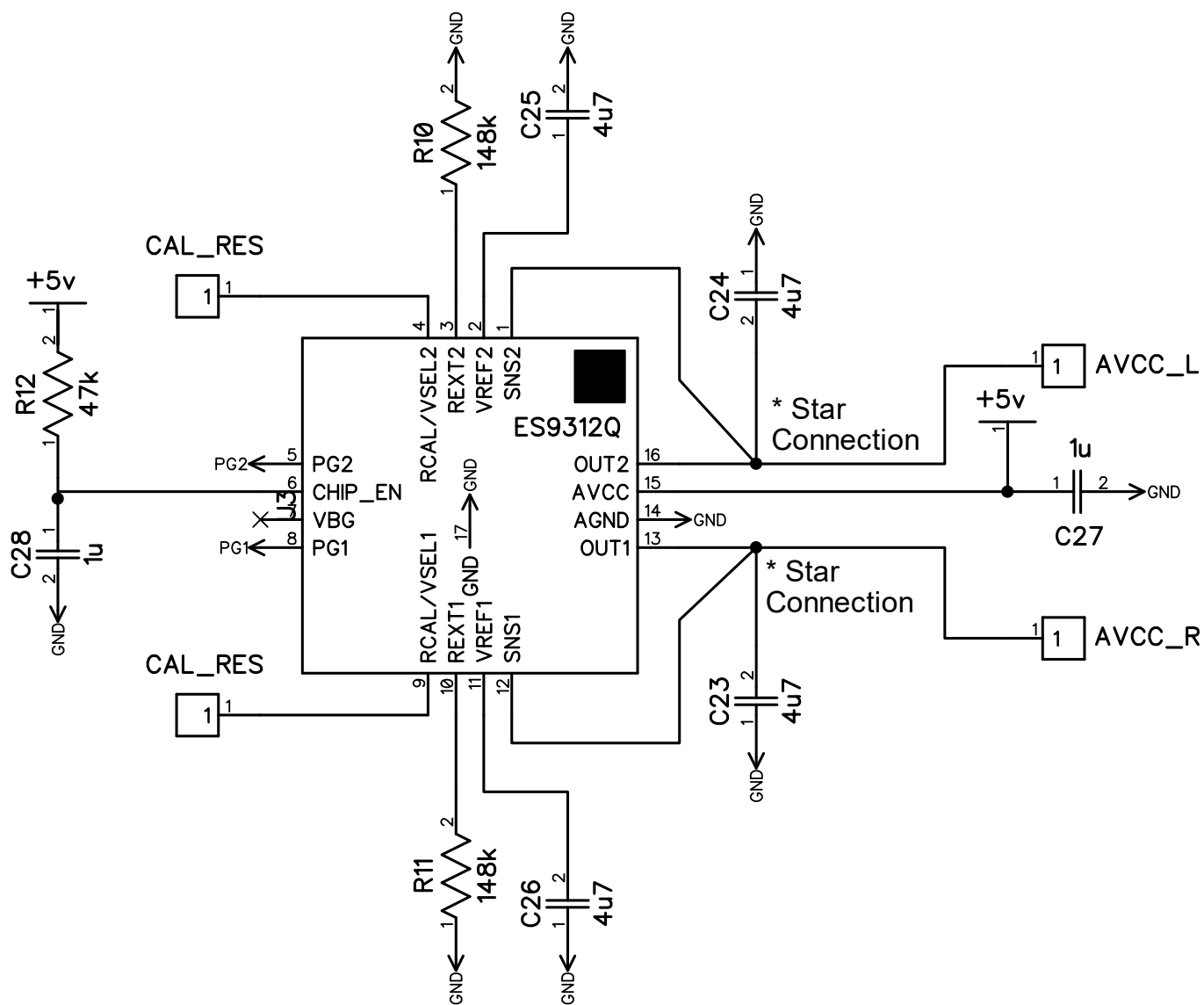


Figure 23 - ES9027PRO Power Supply Schematic

Note: In all configurations V_{BG} must remain floating. SNS_x and OUT_x pins need to be start connected to 4.7µF capacitors which are located close to ES9312.



Internal Pad Circuitry

Pin Name	Pin	Type	Equivalent Circuit
AVCC_L VCAA AVCC_R AVDD	5 19 32 48	Power	
GND GND GND GND GND	8 14 23 29 38	Ground	
CHIP_EN	6	Digital I	



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RT1	7		
MOSI/SDA/HW0	15		
SCLK/SCL/HW1	16		
GPIO1	20		
GPIO2	21		
SS/ADDR1/HW1	30		
MISO/ADDR0/MUTE_CTRL	31		
DATA8/GPIO8	39	Digital I/O	<p>The diagram shows a digital I/O pin connected to a square symbol labeled 'Digital I/O'. The pin is pulled up to VDD by a resistor labeled 'PU/PD'. The pin is also connected to an output driver consisting of a PMOS transistor (gate to VDD, source to VDD, drain to pin) and an NMOS transistor (gate to GND, source to GND, drain to pin). The gates of both transistors are driven by an input signal 'O' through an inverter. An enable signal 'OE' is connected to the gates of both transistors through an inverter. ESD protection diodes are shown between the pin and both VDD and GND.</p>
DATA7/GPIO7	40		
DATA6/GPIO6	41		
DATA5/GPIO5	42		
DATA4/GPIO4	43		
DATA3	44		
DATA2	45		
DATA1	46		
DATA_CLK	47		
MODE	17		

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<p>GPIO 3</p>	<p>22</p>	<p>Digital I/O</p>	<p>The diagram shows a digital I/O pin configuration. On the left, there are four input pins: OE, O, I, and PU/PD. OE and O are connected to inverters. I is connected to an inverter with a resistor symbol. PU/PD is connected to a resistor. The outputs of these inverters and the PU/PD resistor are connected to a central node. This node is also connected to VDD through an ESD protection diode (pointing towards VDD) and to GND through another ESD protection diode (pointing towards GND). The central node is connected to the GPIO3 pin. The GPIO3 pin is connected to a Calibration Resistor, which is in series with a Normally Closed Switch connected to GND.</p>
<p>DVDD DVDD DVDD</p>	<p>13 24 37</p>	<p>IO Power</p>	<p>The diagram shows an IO Power pin configuration. On the left, there are three DVDD pins. The top DVDD pin is connected to a node. This node is connected to VCC through an ESD protection diode (pointing towards VCC) and to GND through another ESD protection diode (pointing towards GND). The node is also connected to a Power Pad.</p>

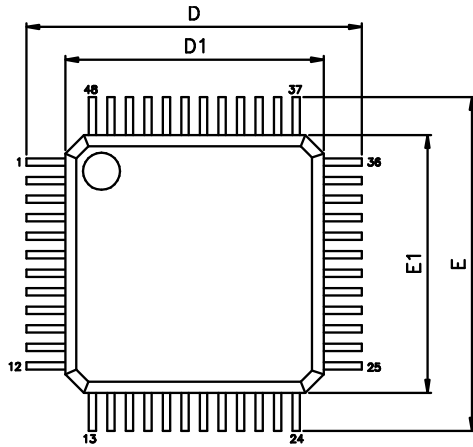


DAC1	1	Analog I/O	
DAC1B	2		
DAC3B	3		
DAC3	4		
DAC5	9		
DAC5B	10		
DAC7B	11		
DAC7	12		
DAC8	25		
DAC8B	26		
DAC6B	27		
DAC6	28		
DAC4	33		
DAC4B	34		
DAC2B	35		
DAC2	36		
MCLK	18	Analog I	

Table 31 - Internal Pad Circuitry

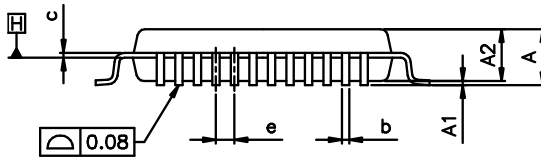


48 QFP Package Dimensions



VARIATIONS (ALL DIMENSIONS SHOWN IN MM)

SYMBOLS	MIN.	NOM.	MAX.
A	--	--	1.60
A1	0.05	--	0.15
A2	1.35	1.40	1.45
b	0.17	0.22	0.27
c	0.09	--	0.20
D	9.00 BSC		
D1	7.00 BSC		
E	9.00 BSC		
E1	7.00 BSC		
e	0.50 BSC		
L	0.45	0.60	0.75
L1	1.00 REF		
θ	0°	3.5°	7°



- NOTES:
1. JEDEC OUTLINE : MS-026 BBC
 2. DATUM PLANE [H] IS LOCATED AT THE BOTTOM OF THE MOLD PARTING LINE COINCIDENT WITH WHERE THE LEAD EXITS THE BODY.
 3. DIMENSIONS D1 AND E1 DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25 mm PER SIDE. DIMENSIONS D1 AND E1 DO INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE [H].
 4. DIMENSION b DOES NOT INCLUDE DAMBAR PROTRUSION.

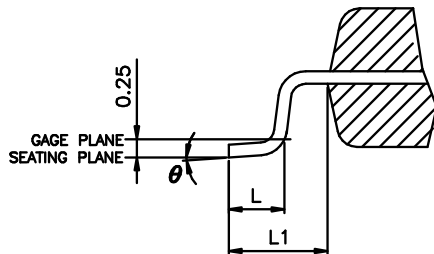
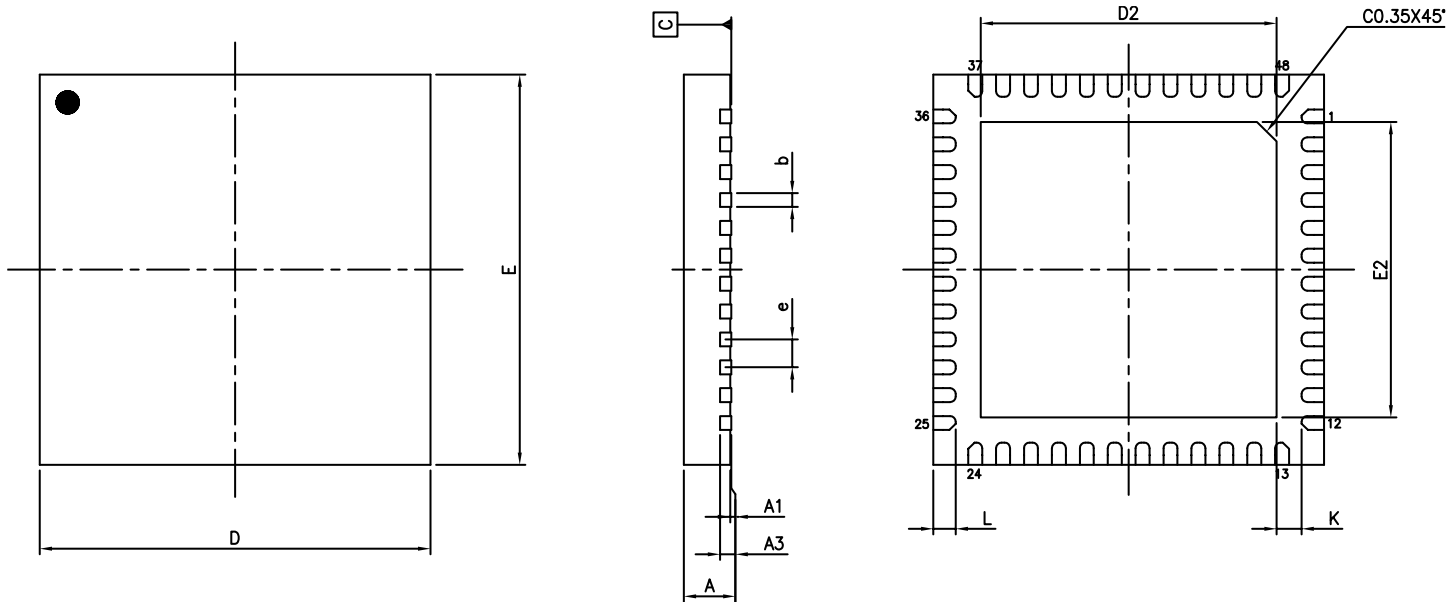


Figure 24 - ES9027SPRO 48 QFP Package Dimensions



48 QFN Package Dimensions



PACKAGE TYPE				
JEDEC OUTLINE	MO-220			
PKG CODE	VQFN(Y74B)			
SYMBOLS	MIN.	NOM.	MAX.	
A	0.80	0.85	0.90	
A1	0.00	0.02	0.05	
A3	0.203 REF.			
b	0.20	0.25	0.30	
D	7.00 BSC			
E	7.00 BSC			
e	0.50 BSC			
L	0.35	0.40	0.45	
K	0.20	-	-	

PAD SIZE	D2			E2			LEAD FINISH		JEDEC CODE
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	Pure Tin	PPF	
224X224 MIL	5.25	5.30	5.35	5.25	5.30	5.35	V	X	N/A

NOTES :

1. ALL DIMENSIONS ARE IN MILLIMETERS.
2. DIMENSION b APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.15mm AND 0.30mm FROM THE TERMINAL TIP. IF THE TERMINAL HAS THE OPTIONAL RADIUS ON THE OTHER END OF THE TERMINAL, THE DIMENSION b SHOULD NOT BE MEASURED IN THAT RADIUS AREA.
3. BILATERAL COPLANARITY ZONE APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.

Figure 25 - ES9027SPRO 48 QFN Package Dimensions



48 QFP/QFN Top View Marking

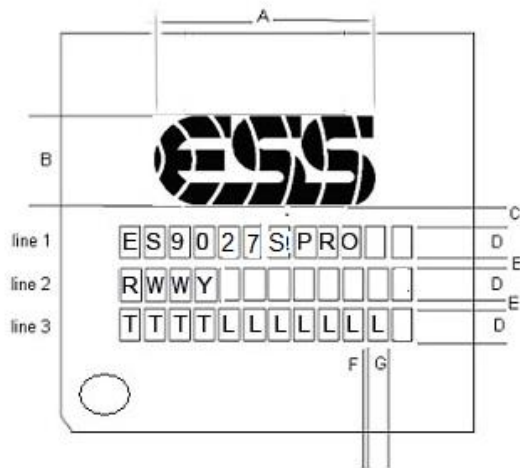


Figure 26 - ES9027SPRO Marking

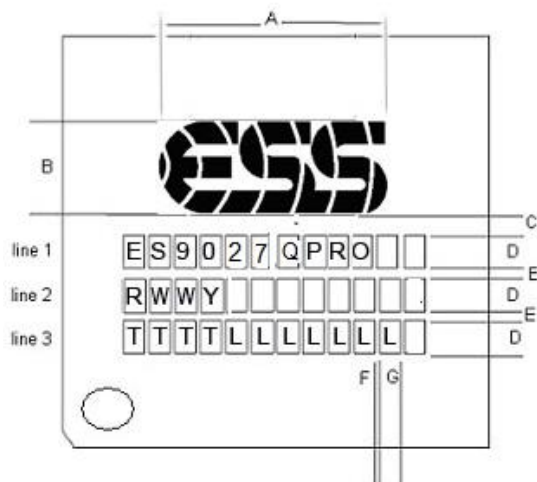


Figure 27 - ES9027QPRO Marking

Package Type	Dimension in mm						
	A	B	C	D	E	F	G
48 LQFP 7mm x 7mm	5.0	2.0	0.3	0.56	0.2	0.08	0.33

T	Tracking Number
W	Work Week
Y	Last Digital of Year
L	Low Number
R	Silicon Revision



Reflow Process Considerations

Temperature Controlled

For lead-free soldering, the characterization and optimization of the reflow process is the most important factor to consider.

The lead-free alloy solder has a melting point of 217°C. This alloy requires a minimum reflow temperature of 235°C to ensure good wetting. The maximum reflow temperature is in the 245°C to 260°C range, depending on the package size (**Error! Reference source not found.**). This narrows the process window for lead-free soldering to 10°C to 20°C.

The increase in peak reflow temperature in combination with the narrow process window makes the development of an optimal reflow profile a critical factor for ensuring a successful lead-free assembly process. The major factors contributing to the development of an optimal thermal profile are the size and weight of the assembly, the density of the components, the mix of large and small components, and the paste chemistry being used.

Reflow profiling needs to be performed by attaching calibrated thermocouples well adhered to the device as well as other critical locations on the board to ensure that all components are heated to temperatures above the minimum reflow temperatures and that smaller components do not exceed the maximum temperature limits (Table RPC-2).

To ensure that all packages can be successfully and reliably assembled, the reflow profiles studied and recommended by ESS are based on the JEDEC/IPC standard J-STD-020 revision D.1.

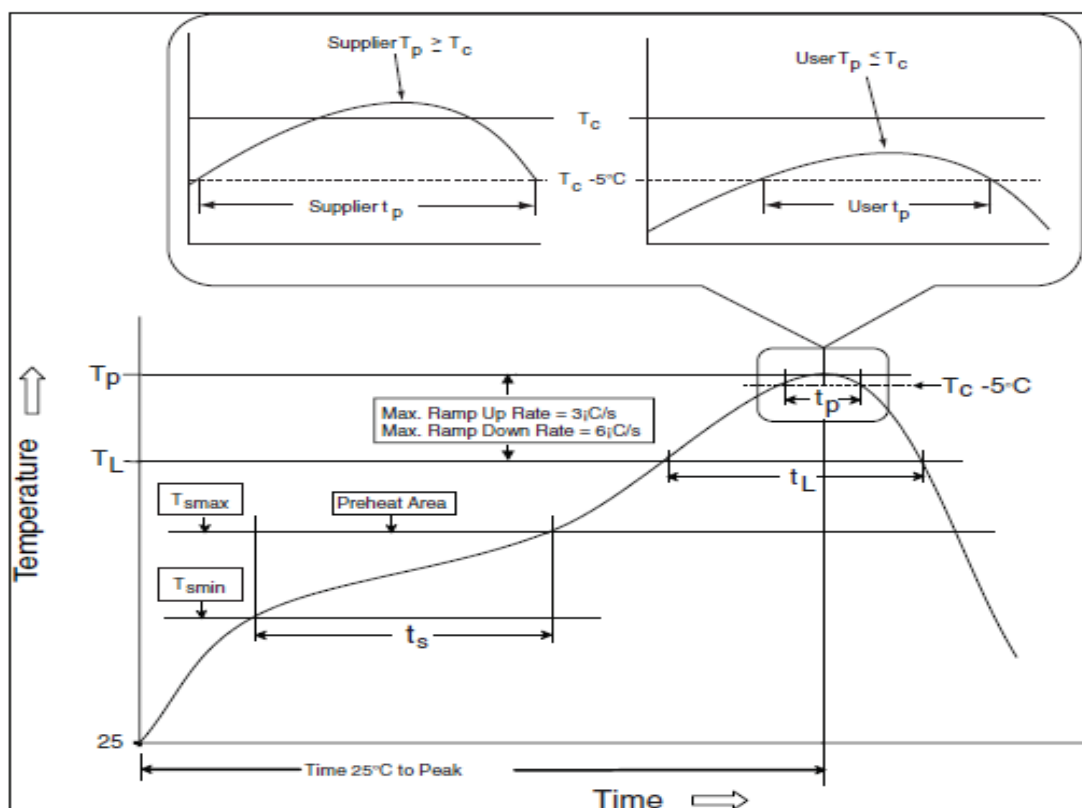


Figure 28 - IR/Convection Reflow Profile (IPC/JEDEC J-STD-020D.1)

Reflow is allowed 3 times. Caution must be taken to ensure time between re-flow runs does not exceed the allowed time by the moisture sensitivity label. If the time elapsed between the re-flows exceeds the moisture sensitivity time bake the board according to the moisture sensitivity label instructions.



Manual

Allowed up to 2 times with maximum temperature of 350°C no longer than 3 seconds.

RPC-1 Classification Reflow Profile

Profile Feature	Pb-Free Assembly
Preheat/Soak Temperature Min (T_{SMIN}) Temperature Max (T_{SMAX}) Time (t_s) from (T_{SMIN} to T_{SMAX})	150°C 200°C 60-120 seconds
Ramp-up rate (T_L to T_P)	3°C / second maximum
Liquidous Temperature (T_L) Time (t_L) maintained above T_L	217°C 60-150 seconds
Peak package body temperature (T_P)	For users T_P must not exceed the classification temp in Table RPC-2 For suppliers T_P must equal or exceed the classification temp in Table RPC-2
Time (t_P)* within 5°C of the specified classification temperature (T_C)	30* seconds
Ramp-down rate (T_P to T_L)	6°C / second maximum
Time 25°C to peak temperature	8 minutes maximum
* Tolerance for peak profile temperature (T_P) is defined as a supplier minimum and a user maximum	

Table 32 - RPC-1 Classification Reflow Profile

All temperatures refer to the center of the package, measured on the package body surface that is facing up during assembly reflow (e.g., live-bug). If parts are reflowed in other than the normal live-bug assembly reflow orientation (i.e., dead-bug), T_P shall be within $\pm 2^\circ\text{C}$ of the live-bug T_P and still meet the T_C requirements, otherwise, the profile shall be adjusted to achieve the latter. To accurately measure actual peak package body temperatures, refer to JEP140 for recommended thermocouple use.

Reflow profiles in this document are for classification/preconditioning and are not meant to specify board assembly profiles. Actual board assembly profiles should be developed based on specific process needs and board designs and should not exceed the parameters in Table RPC-1.

For example, if T_C is 260°C and time t_P is 30 seconds, this means the following for the supplier and the user. For a supplier, the peak temperature must be at least 260°C. The time above 255°C must be at least 30 seconds. For a user, the peak temperature must not exceed 260 °C. The time above 255 °C must not exceed 30 seconds.

All components in the test load shall meet the classification profile requirements.



RPC-2 Pb-Free Process - Classification Temperatures (T_c)

Package Thickness	Volume mm ³ , <350	Volume mm ³ , 350 to 2000	Volume mm ³ , >2000
<1.6 mm	260°C	260°C	260°C
1.6 mm – 2.5 mm	260°C	250°C	245°C
>2.5 mm	250°C	245°C	245°C

Table 33 - RPC-2 Pb Free Classification Temperature

At the discretion of the device manufacturer, but not the board assembler/user, the maximum peak package body temperature (T_p) can exceed the values specified in Table RPC-2. The use of a higher T_p does not change the classification temperature (T_c).

Package volume excludes external terminals (e.g., balls, bumps, lands, leads) and/or nonintegral heat sinks.

The maximum component temperature reached during reflow depends on package thickness and volume. The use of convection reflow processes reduces the thermal gradients between packages. However, thermal gradients due to differences in thermal mass of SMD packages may still exist.



Ordering Information

Part Number	Description	Package
ES9027SPRO	SABRE PRO 32-bit 8 Channel DAC	7mm x 7mm 48 QFP
ES9027QPRO		7mm x 7mm 48 QFN

Table 34 - Ordering Information

Revision History

Current Version 0.5

Rev.	Date	Notes
0.1	March 25 th , 2022	Initial release
0.5	July, 2024	<ul style="list-style-type: none"> • Updated Formatting • Updated Reg 47-46[8:6] mnemonic for clarity • Updated Registers 57[6], 64-71[6:5], 82-84, 87 descriptions • Updated Registers 64-71 defaults • Unreserved 34[6], 61[7] • Reserved 61[4:0], not required for operational use • Updated audio input format & pre-programmed digital filters section • Updated software mode & hardware mode pin configurations section • Added GPIO Functions in Hardware Mode section • Added GPIO Configuration descriptions • Added Calibration Resistor section • Added 64FS Mode info and filters • Added Internal Pad Circuitry & switching characteristics • Updated ESD rating information • Added SPI Slave Interface & Bit-Clock (BCLK) and Word-Select (WS) Timing • Updated Reference Output stage

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